



GE Digital Energy  
Multilin

# 350

## Feeder Protection System

Feeder protection and control



## Instruction manual

350 revision: 1.2

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Part number: 1601-9091-A6 (August 2009)

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# 350 Feeder Protection System

## Chapter 1: Introduction

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### 1.1 Overview

The 350 is a microprocessor-based relay for primary and backup over-current protection of medium and low voltage distribution feeders. The relay is also suitable for providing over-current protection for small and medium size motors, transformers, generators, and distribution bus-bars. The small footprint and the withdrawable option make the 350 relay ideal for panel mounting on either new or retrofit installations. The combination of proven hardware, a variety of protection and control features, and communications, makes the relay ideal for total feeder protection and control. Equipped with serial (RS485), USB, and Ethernet ports, and a wide selection of protocols such as Modbus, DNP3.0, IEC 60870-5-103, 60870-5-104, GOOSE, the 350 relay is the best-in-class for MCCs, SCADA and inter-relay communications. The 350 relay provides excellent transparency with respect to power system conditions and events, through its four-line 20-character display, as well as the EnerVista SR3 Setup program. Conveniently located LEDs provide indication of relay operation, alarm, and pickup, as well as breaker, and relay status.

The 350 relay provides the following key benefits:

- Withdrawable small footprint – saves on rewiring and space.
- Multiple protection groups with the added flexibility of switching through a wide selection of overcurrent protection and control features.
- Fast setup (Quick Setup) menu for power-system setup and a simple overcurrent protection configuration.
- Large four-line LCD display, LEDs, and an easy-to-navigate keypad.
- Multiple communication protocols for simultaneous access when integrated into monitoring and control systems.

---

## 1.2 Cautions and warnings

Before attempting to install or use this device, it is imperative that all caution and danger indicators in this manual are reviewed to help prevent personal injury, equipment damage, or downtime. The following icons are used to indicate notes, cautions, and dangers.

Figure 1-1: Note icons used in the documentation



The standard **note** icon emphasizes a specific point or indicates minor problems that may occur if instructions are not properly followed.

The **caution** icon indicates that possible damage to equipment or data may occur if instructions are not properly followed.

The **danger** icon provides users with a warning about the possibility of serious or fatal injury to themselves or others.

---

## 1.3 Description of the 350 Feeder Protection System

### CPU

Relay functions are controlled by two processors: a Freescale MPC5554 32-bit microprocessor measures all analog signals and digital inputs and controls all output relays; a Freescale MPC5202B 32-bit microprocessor controls all the Ethernet communication protocols.

### Analog Input Waveform Capture

Magnetic transformers are used to scale-down the incoming analog signals from the source instrument transformers. The analog signals are then passed through a 960 Hz low pass anti-aliasing filter. All signals are then simultaneously captured by sample and hold buffers to ensure there are no phase shifts. The signals are converted to digital values by a 12-bit A/D converter before finally being passed on to the CPU for analysis.

Current is sampled thirty-two times per power frequency cycle. These 'raw' samples are calibrated in software, then placed into the waveform capture buffer, thus emulating a fault recorder. The waveforms can be retrieved from the relay via the EnerVista SR3 Setup software for display and diagnostics.

### Phasors, Transients, and Harmonics

Current waveforms are processed twice every cycle with a DC Offset Filter and a Discrete Fourier Transform (DFT). The resulting phasors have fault current transients and all harmonics removed. This results in an overcurrent relay that is extremely secure and reliable; one that will not overreach.

### Processing of AC Current Inputs

The DC Offset Filter is an infinite impulse response (IIR) digital filter, which removes the DC component from the asymmetrical current present at the moment a fault occurs. This is done for all current signals used for overcurrent protection. This filter ensures no overreach of the overcurrent protection; unfortunately, the filter also causes slower overcurrent response times (0 to 50 ms) for faults marginally over the pickup level.

The Discrete Fourier Transform (DFT) uses exactly one sample cycle to calculate a phasor quantity which represents the signal at the fundamental frequency; all harmonic components are removed. All subsequent calculations (e.g. RMS, power, etc.) are based upon the current phasors, such that the resulting values have no harmonic components.

### Protection Elements

All protection elements are processed twice every cycle to determine if a pickup has occurred or a timer has expired. The protection elements use RMS current, based on the magnitude of the phasor. Hence, protection is impervious to both harmonics and DC transients.

Figure 1-2: Single line diagram

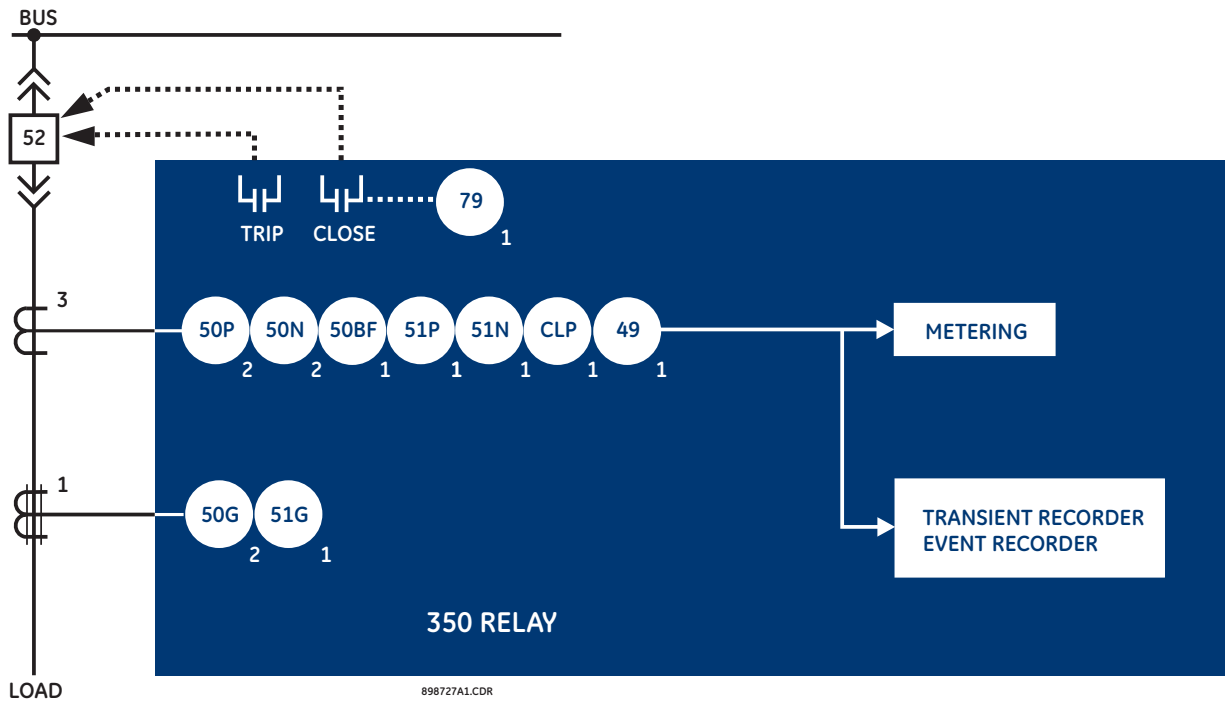
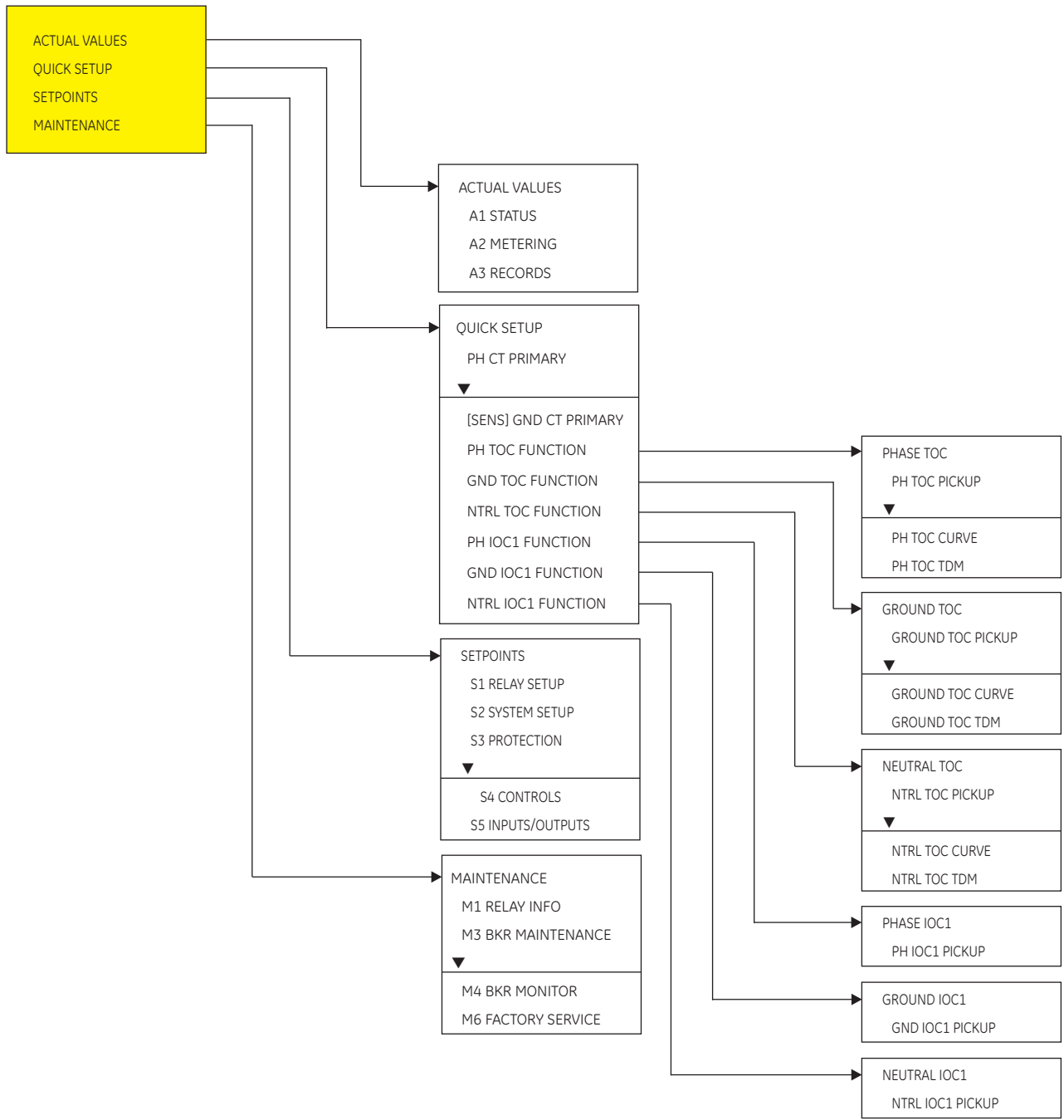


Table 1: 350 protection functions

ANSI device	Description
49	Thermal Model
50P	Phase Instantaneous Overcurrent
50N	Neutral Instantaneous Overcurrent
50G	Ground/Sensitive Ground Instantaneous Overcurrent
50BF	Breaker Failure
51P	Phase Timed Overcurrent
51G	Ground Timed Overcurrent
51N	Neutral Timed Overcurrent
79	Autoreclose
CLP	Cold Load Pickup

Figure 1-3: 350 Main Menu structure



898790.cdr

## 1.4 350 order codes

The information to specify an 350 relay is provided in the following order code figure.

Figure 1-4: 350 order codes

	350	-	E	*	*	*	S	*	*	N	*	*	D	*	
Interface	350														350 Feeder Protection System
Phase Currents	P1														1 A 3-phase current inputs
	P5														5 A 3-phase current inputs
Ground Currents <sup>a</sup>	G1														1 A ground current input
	G5														5 A ground current input
	S1														1 A sensitive ground current input
	S5														5 A sensitive ground current input
Power Supply	L														24 to 48 V DC
	H														110 to 250 V DC/110 to 230 V AC
Current Protection	S														Standard overcurrent protection - 50P(1), 50G(1), 50N(1), 51P(1), 51G(1), 51N(1)
	E														Extended overcurrent protection - 49, 50P(2), 50G(2), 50N(2), 51P(1), 51G(1), 51N(1)
Control	N														No selection
	C														CLP, 50BF, Autoreclose (79)
Communications	S N														Standard: Front USB, Rear RS485: Modbus RTU, DNP3.0, IEC60870-5-103
	1 E														Standard + Ethernet (Copper & Fiber - MTRJ), Modbus TCP/IP, DNP3.0, IEC 60870-5-104
	2 E														Standard + Ethernet (Copper & Fiber - MTRJ), Modbus TCP/IP, DNP3.0, IEC 60870-5-104, IEC 61850 GOOSE
Harsh Environment	N														None
	H														Harsh Environment Conformal Coating

a. The ground input CT rating must match the phase input CTs

## 1.5 Specifications



NOTE

Specifications are subject to change without notice.

### 1.5.1 Password security

#### PASSWORD SECURITY

Master Reset Password: .....	8 to 10 alpha-numeric characters
Settings Password:.....	3 to 10 alpha-numeric characters for local and remote access
Control Password:.....	3 to 10 alpha-numeric characters for local and remote access

### 1.5.2 Protection specifications

#### PHASE/NEUTRAL/GROUND TIME OVERCURRENT (51P/51N/51G)

Pickup Level:.....	0.04 to 20 x CT in steps of 0.01 x CT
Dropout Level: .....	97 to 99% of Pickup @ $I > 1 \times CT$ Pickup - $0.02 \times CT @ I < 1 \times CT$
Curve Shape:.....	ANSI Extremely/Very/Moderately/Normally Inverse Definite Time (0.05 s base curve) IEC Curve A/B/C/Short IAC Extreme/Very/Inverse/Short User Curve, FlexCurve™ A/B (programmable curves)
Curve Multiplier:.....	0.5 to 20.0 in steps of 0.1
Reset Time: .....	Instantaneous, Linear
Time Delay Accuracy:.....	$\pm 3\%$ of expected inverse time or 1 cycle, whichever is greater
Level Accuracy:.....	per CT input

#### SENSITIVE GROUND TIME OVERCURRENT (51SG)

Pickup Level:.....	0.005 to 3 x CT in steps of 0.001 x CT
Dropout Level: .....	97 to 99% of Pickup @ $I > 0.1 \times CT$ Pickup - $0.02 \times CT @ I < 0.1 \times CT$
Curve Shape:.....	ANSI Extremely/Very/Moderately/Normally Inverse Definite Time IEC Curve A/B/C/Short Inverse IAC Extreme/Very/Inverse/Short Inverse User Curve, FlexCurve™ A/B
Curve Multiplier:.....	0.5 to 20.0 in steps of 0.1
Reset Time: .....	Instantaneous, Linear
Time Delay Accuracy:.....	$\pm 3\%$ of expected inverse time or 1 cycle, whichever is greater
Level Accuracy:.....	per CT input

#### PHASE/NEUTRAL/GROUND INSTANTANEOUS OVERCURRENT (50P/50N/50G)

Pickup Level:.....	0.05 to 20 x CT in steps of 0.01 x CT
Dropout Level: .....	97 to 99% of Pickup @ $I > 1 \times CT$ Pickup - $0.02 \times CT @ I < 1 \times CT$
Time Delay:.....	0.00 to 300.00 sec in steps of 0.01
Operate Time:.....	<30 ms @ 60Hz ( $I > 2.0 \times PKP$ , No time delay) <35 ms @ 50Hz ( $I > 2.0 \times PKP$ , No time delay)
Time Delay Accuracy:.....	0 to 1 cycle (Time Delay selected)
Level Accuracy:.....	per CT input



**EVENT RECORDER**

Number of events:.....	256
Header:.....	relay name, order code, firmware revision
Content:.....	event number, date of event, cause of event, per-phase current, ground current, sensitive ground current, neutral current, system frequency, thermal capacity
Data Storage:.....	RAM - Battery backed-up

**CLOCK**

Setup:.....	Date and time Daylight Saving Time
IRIG-B:.....	Auto-detect (DC shift or Amplitude Modulated) Amplitude modulated: 1 to 10 V pk-pk DC shift: 1 to 10 V DC Input impedance: 40kOhm $\pm$ 10% RTC Accuracy: $\pm$ 1 min / month

**1.5.4 Control specifications****LOGIC ELEMENTS**

Number of logic elements:.....	8
Trigger source inputs per element:.....	3
Block inputs per element:.....	3
Supported operations:.....	AND, OR, NOT, Pickup / Dropout timers
Pickup timer:.....	0 to 6000 ms in steps of 1 ms
Dropout timer:.....	0 to 6000 ms in steps of 1 ms

**BREAKER CONTROL**

Operation:.....	Asserted Contact Input, Logic Element, Virtual Input, Manual Command
Function:.....	Opens / closes the feeder breaker

**AUTORECLOSE**

Reclose attempts:.....	Up to 4 shots
Time Delay Accuracy:.....	0 to 3 cycles (AR Dead Time selected)
Elements:.....	Inputs, Outputs, Breaker Status (52 status)

**BREAKER FAILURE**

Pickup Level:.....	0.05 to 20.00 $\times$ CT in steps of 0.01
Dropout Level:.....	97 to 98% of pickup
Time Delay Accuracy:.....	0 to 1 cycle (Timer 1, Timer 2)
Level Accuracy:.....	per CT input

**BREAKER TRIP COUNTER**

Trip Counter Limit (Pickup):.....	1 to 10000 in steps of 1
-----------------------------------	--------------------------

**COLD LOAD PICKUP BLOCKING**

Operation:.....	Automatically, or by command (asserted Contact Input, Logic Element, Virtual Input)
Function:.....	Block IOC for selected period of time, raise TOC pickup for selected period of time
Time Delay Accuracy:.....	0 to 1 cycle (Block Time) <200 ms (Outage Time)



## 1.5.6 Outputs specifications

### FORM-A RELAYS

Configuration:	2 (two) electromechanical
Contact material:	silver-alloy
Operate time:	<8 ms
Continuous current:	10 A
Make and carry for 0.2s:	30 A per ANSI C37.90
Break (DC inductive, L/R=40 ms):	24 V / 1 A 48 V / 0.5 A 125 V / 0.3 A 250 V / 0.2 A
Break (DC resistive):	24 V / 10 A 48 V / 6 A 125 V / 0.5 A 250 V / 0.3 A
Break (AC inductive):	720 VA @ 250 VAC Pilot duty A300
Break (AC resistive):	277 VAC / 10 A

### FORM-A VOLTAGE MONITOR

Applicable voltage:	20 to 250 VDC
Trickle current:	1 to 2.5 mA

### FORM-C RELAYS

Configuration:	5 (five) electromechanical
Contact material:	silver-alloy
Operate time:	<8 ms
Continuous current:	10 A
Make and carry for 0.2s:	30 A per ANSI C37.90
Break (DC inductive, L/R=40 ms):	24 V / 1 A 48 V / 0.5 A 125 V / 0.3 A 250 V / 0.2 A
Break (DC resistive):	24 V / 10 A 48 V / 6 A 125 V / 0.5 A 250 V / 0.3 A
Break (AC inductive):	720 VA @ 250 VAC Pilot duty A300
Break (AC resistive):	277 VAC / 10 A

### TRIP / CLOSE SEAL-IN

Relay 1 trip seal-in:	0.00 to 9.99 s in steps of 0.01
Relay 2 close seal-in:	0.00 to 9.99 s in steps of 0.01

## 1.5.7 Power supply specifications

### HIGH RANGE POWER SUPPLY

Nominal:	120 to 240 VAC 125 to 250 VDC
Range:	60 to 300 VAC (50 and 60 Hz) 84 to 250 VDC
Ride-through time:	35 ms

### LOW RANGE POWER SUPPLY

Nominal:	24 to 48 VDC
Range:	20 to 60 VDC

### ALL RANGES

Voltage withstand:	2 × highest nominal voltage for 10 ms
Power consumption:	15 W nominal, 20 W maximum 20 VA nominal, 28 VA maximum

## 1.5.8 Communications specifications

### SERIAL

RS485 port: ..... Opto-coupled  
 Baud rates: ..... up to 115 kbps  
 Response time: ..... 1 ms typical  
 Parity: ..... None, Odd, Even  
 Protocol: ..... Modbus RTU, DNP 3.0, IEC 60870-5-103  
 Maximum distance: ..... 1200 m (4000 feet)  
 Isolation: ..... 2 kV

### ETHERNET (COPPER)

Modes: ..... 10/100 MB (auto-detect)  
 Connector: ..... RJ-45  
 Protocol: ..... Modbus TCP, DNP3.0, iec 60870-5-104, IEC 61850 GOOSE

### ETHERNET (FIBER)

Fiber type: ..... 100 MB Multi-mode  
 Wavelength: ..... 1300 nm  
 Connector: ..... MTRJ  
 Protocol: ..... Modbus TCP, DNP3.0, iec 60870-5-104, IEC 61850 GOOSE  
 Transmit power: ..... -20 dBm  
 Receiver sensitivity: ..... -31 dBm  
 Power budget: ..... 9 dB  
 Maximum input power: ..... -11.8 dBm  
 Typical distance: ..... 2 km (1.25 miles)  
 Duplex: ..... half/full

### USB

Standard specification: ..... Compliant with USB 2.0  
 Data transfer rate: ..... 115 kbps

## 1.5.9 Testing and certification

### CERTIFICATION

ISO: ..... Manufactured under an ISO9001 registered program  
 CE: ..... Conforms to EN61000-6-2 / EN60255-26 / EN60255-27 / EN61010-1 / EN60255-5  
 cULus: ..... Conforms to UL 508 / UL 1053 and C22.2.14-05 (CSA)  
 UL: ..... UL listed for USA and Canada, E83849

**TYPE TESTS**

Relative Humidity Cyclic: .....	IEC 60068-2-30: 55°C at 95% RH
Hot: .....	IEC 60068-2-2 (Hot Start) 16 hours / +85°C
Cold: .....	IEC 60068-2-1 (Cold Start) 16 hours / -40°C
Dielectric Strength:.....	IEC 60255-5: 2300 VAC
Insulation Resistance:.....	IEC 60255-5: >100 MΩ / 500 VDC / 10 s
Impulse Voltage:.....	IEC 60255-5: 5 kV / 0.5 J
Sinusoidal Vibration:.....	IEC 60255-21-1: 2 g, Class 2
Shock and Bump:.....	IEC 60255-21-2: 10 g / 20 g / 30 g, Class 2
Seismic:.....	IEC 60255-21-3: 2 g
Damped Oscillatory Burst:.....	IEC 60255-22-1: 1 MHz 2.5 kV / 1 kV
Electrostatic Discharge Immunity - Air and Direct:.....	IEC 60255-22-2: 8 kV / 6 kV
Radiated RF Immunity:.....	IEC 60255-22-3: 10 V/m (80 MHz to 1 GHz / 1.4 to 2.7 GHz)
Electrical Fast Transient / Burst Immunity: .....	IEC 60255-22-4: ±4 kV
Surge Immunity:.....	IEC 60255-22-5: ±2 kV / 1 kV
Conducted RF Immunity:.....	IEC 60255-22-6: 150 kHz to 80 MHz 10 V/m
Radiated RF Emission: .....	IEC 60255-25: EN55022, Class A
Conducted RF Emission: .....	IEC 60255-25: EN55022, Class A
Ingress of Solid Objects and Water:.....	IEC 60529: IP40 (front), IP10 (back)
Power Frequency Magnetic Field Immunity: .....	IEC 61000-4-8: 30 A/m, 1000 A/m, Class 5
Pulse Magnetic Field Immunity: .....	IEC 61000-4-9: 1000 A/m
Voltage Dip; Voltage Interruption:.....	IEC 61000-4-11: 0%, 40%, 100%
Fast Transient SWC:.....	IEEE C37.90.1: ±4 kV
Oscillatory Transient SWC: .....	IEEE C37.90.1: ±2.5 kV
Electrostatic Discharge - Air and Direct: ..	IEEE C37.90.3: ±8 kV / ±6 kV

**1.5.10 Physical specifications****DIMENSIONS**

Size: .....	Refer to section 2.1.1
Weight:.....	4.1 kg [9.0 lb]

**1.5.11 Environmental specifications****OPERATING ENVIRONMENT**

Ambient operating temperature: .....	-40°C to +60°C [-40°F to +140°F]
Ambient storage / shipping temperature:.....	-40°C to +85°C [-40°F to +185°F]
Humidity:.....	up to 90% non-condensing
Pollution degree: .....	2
Installation category:.....	I
Overvoltage category:.....	III





# 350 Feeder Protection System

## Chapter 2: Installation

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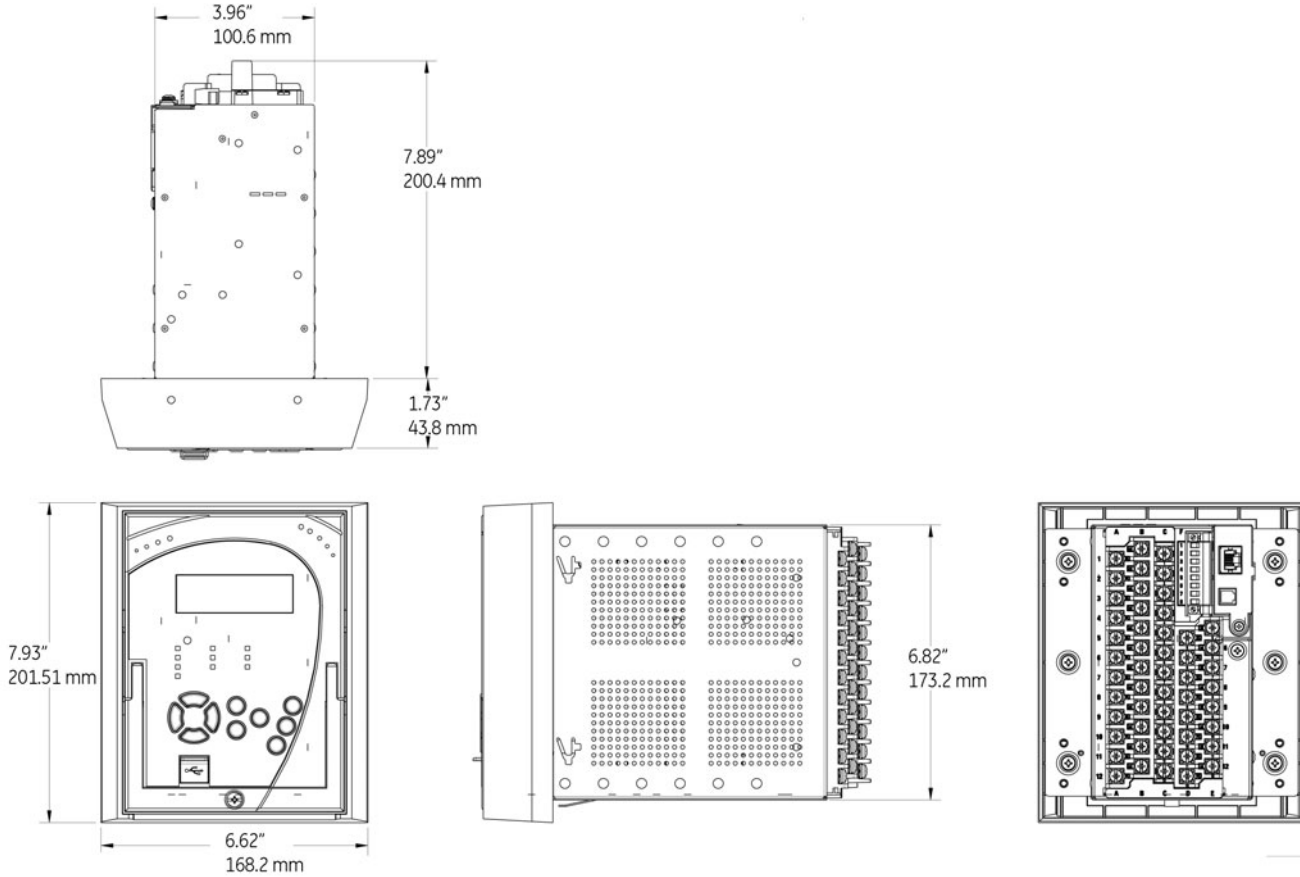
### 2.1 Mechanical installation

This section describes the mechanical installation of the 350 system, including dimensions for mounting and information on module withdrawal and insertion.

### 2.1.1 Dimensions

The dimensions of the 350 are shown below. Additional dimensions for mounting and panel cutouts are shown in the following sections.

Figure 2-1: 350 dimensions



### 2.1.2 Product identification

The product identification label is located on the side panel of the 350. This label indicates the product model, serial number, firmware revision, and date of manufacture.

Figure 2-2: 350 label



## 2.1.3 Mounting

### STANDARD PANEL MOUNT

The standard panel mount and cutout dimensions are illustrated below.



To avoid the potential for personal injury due to fire hazards, ensure the unit is mounted in a safe location and/or within an appropriate enclosure.

Figure 2-3: Panel mounting

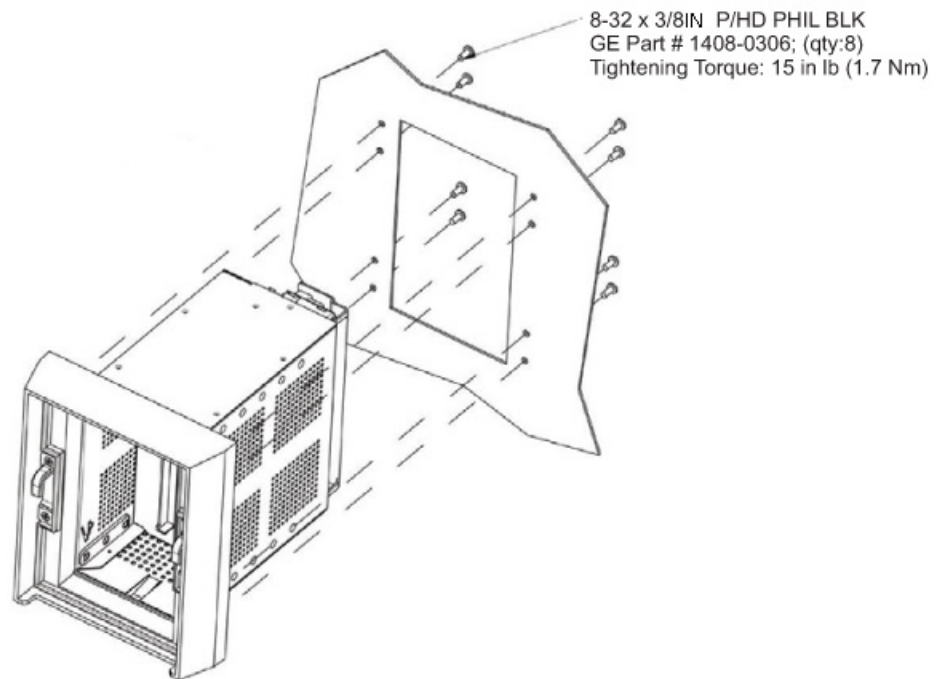
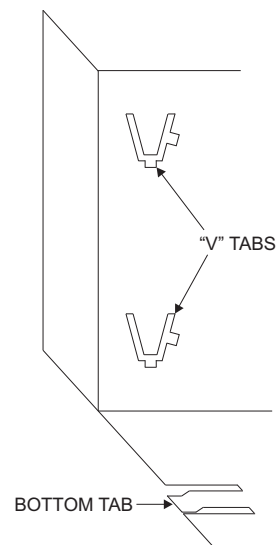


Figure 2-4: Mounting tabs (optional)

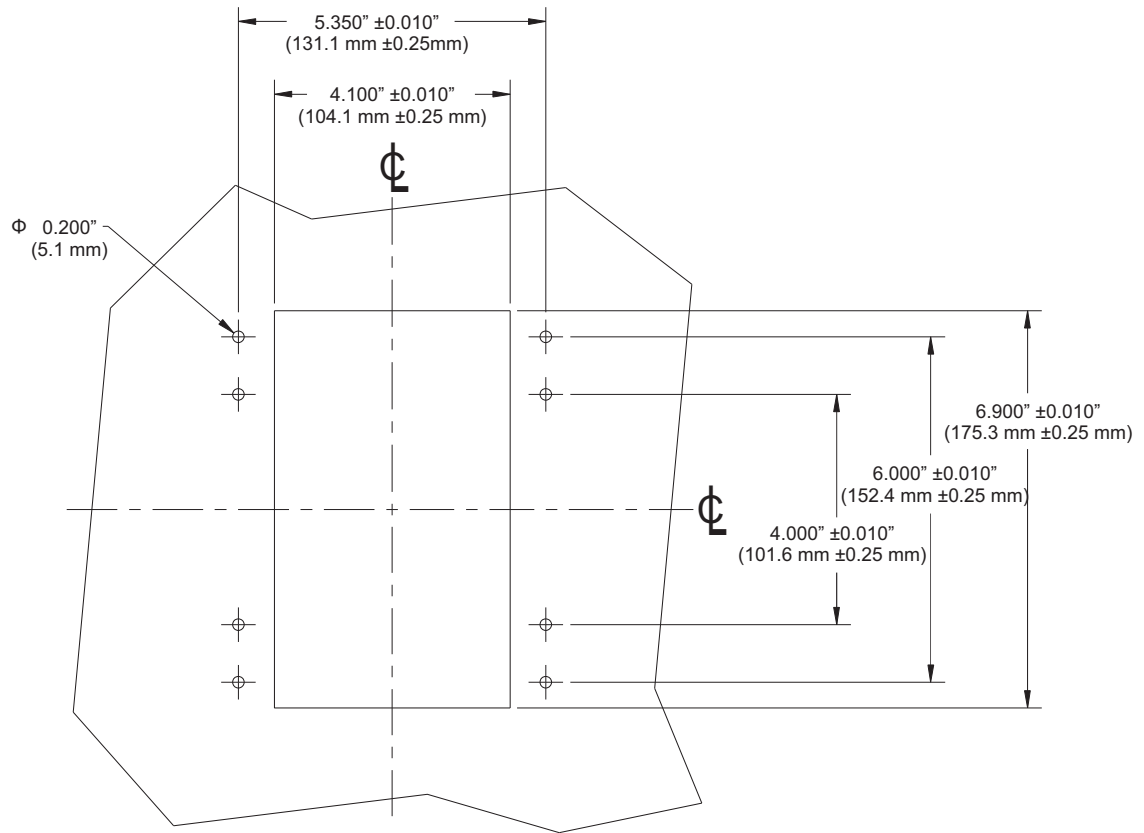


1. From the front of the panel, slide the empty case into the cutout until the bottom tab clicks into place (see above).

2. From the rear of the panel screw the case into the panel at the 8 screw positions shown above.
3. If added security is required, bend the retaining "V" tabs outward, to about 90°. These tabs are located on the sides of the case and appear as shown above.

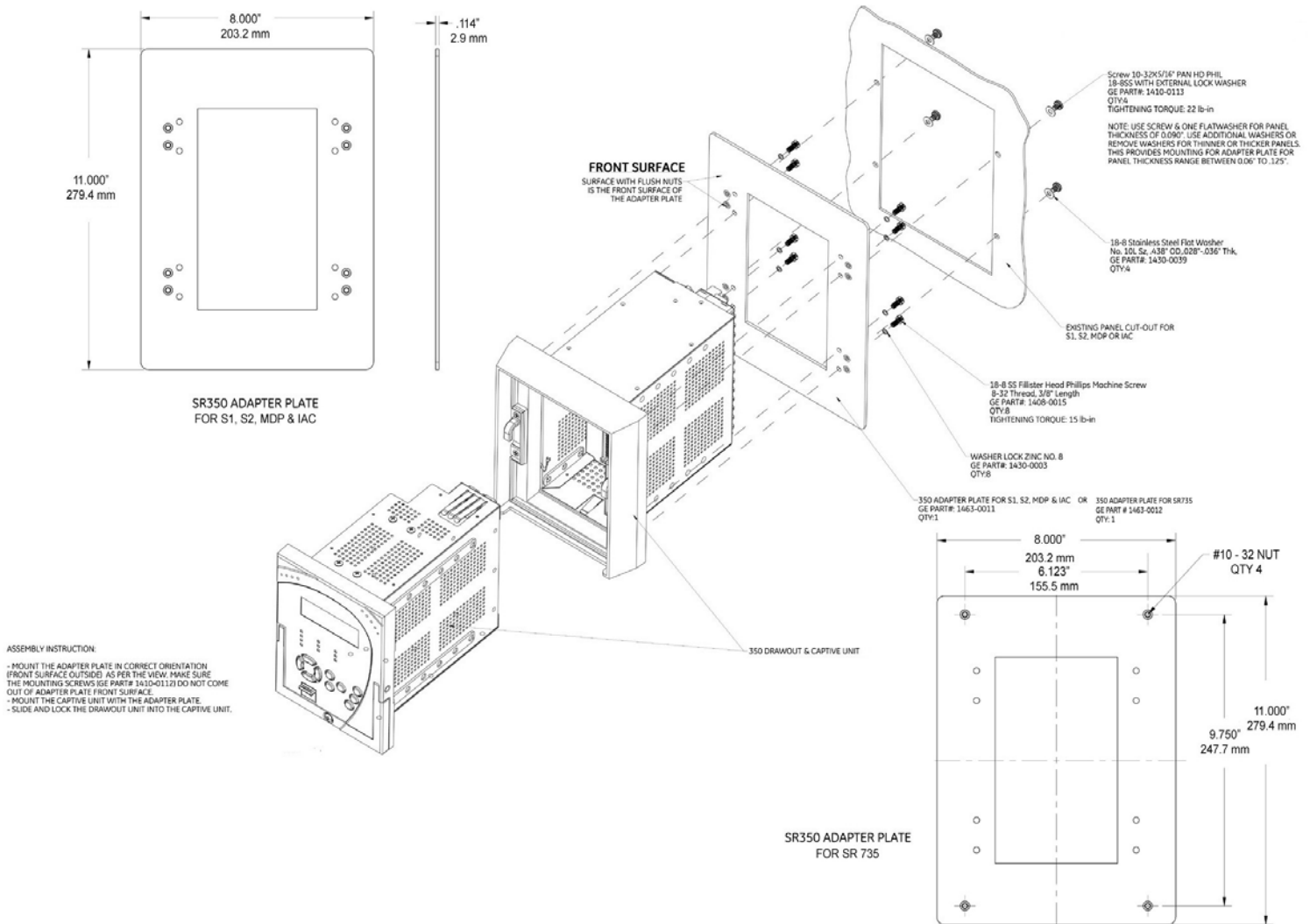
The relay can now be inserted and can be panel wired.

**Figure 2-5: Panel cutout dimensions**

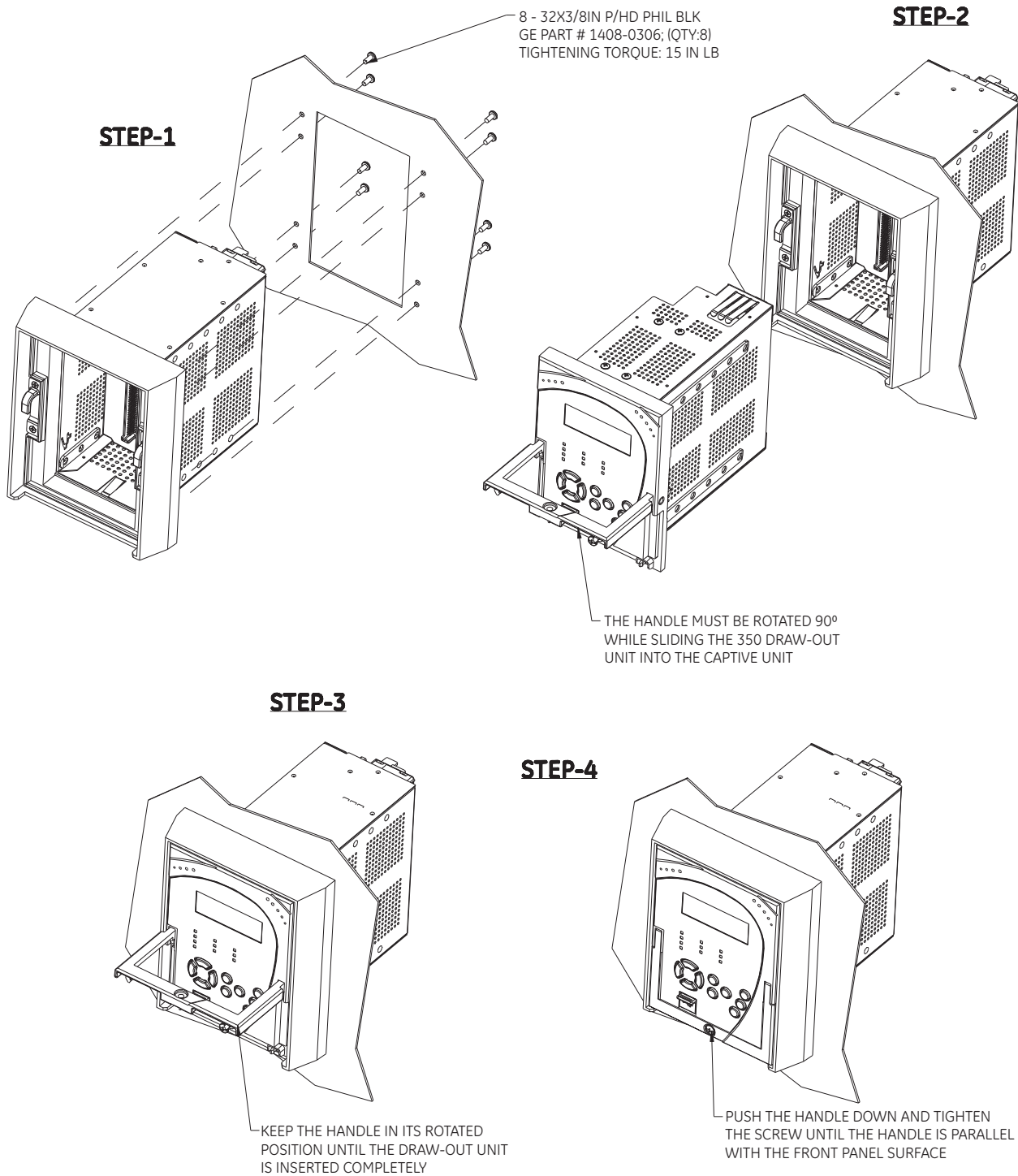


**MOUNTING USING THE S1/S2/MDP/IAC OR SR735 ADAPTER PLATE**

The adaptor plate for mounting the 350 directly over the existing S1/S2/MDP/IAC or SR735 mounting plate, is shown below:



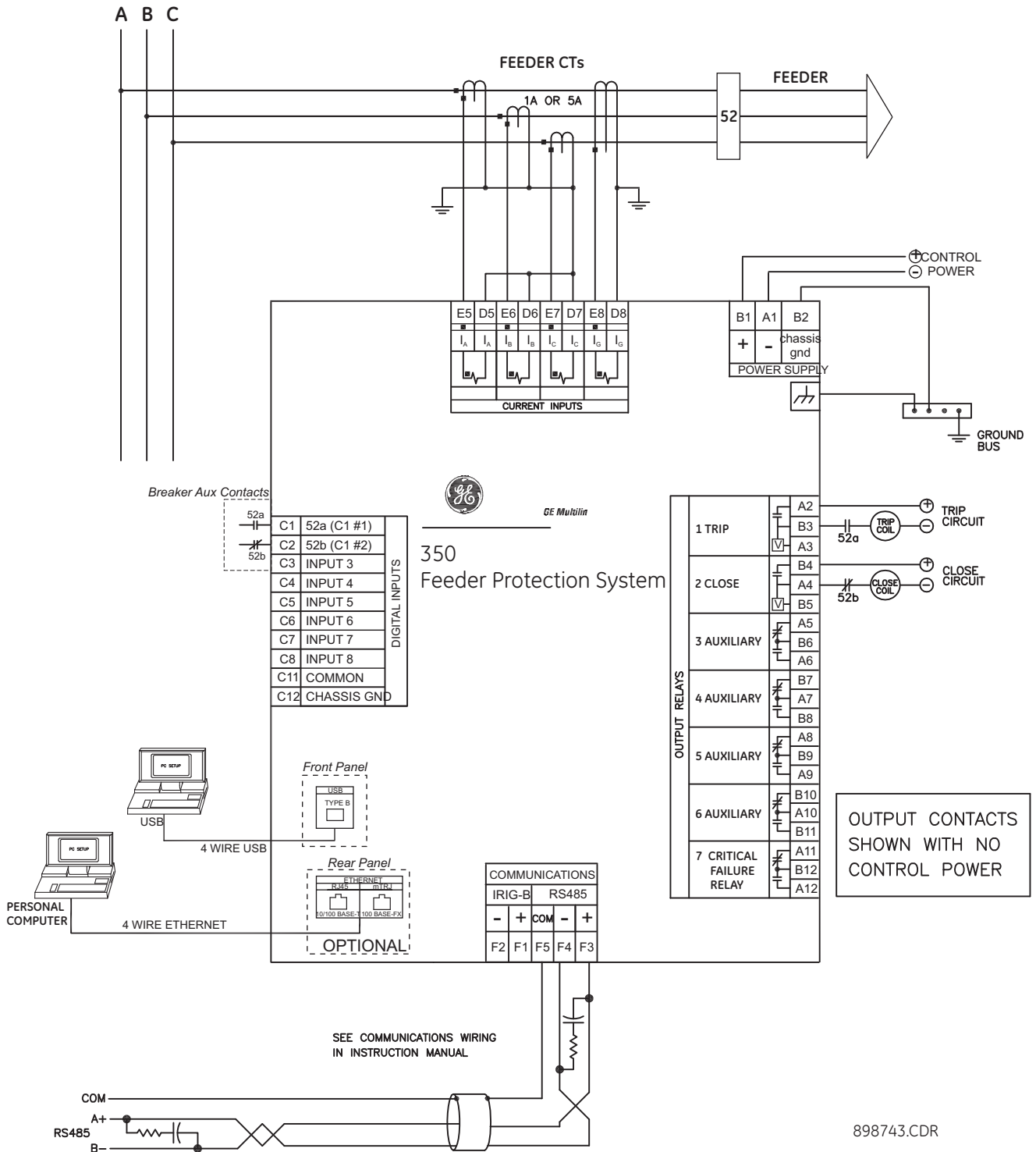
### 2.1.4 Unit withdrawal and insertion



**NOTE:** IT IS THE RESPONSIBILITY OF THE USER TO ENSURE THAT THE EQUIPMENT IS INSTALLED, OPERATED, AND USED FOR ITS INTENDED FUNCTION, IN THE MANNER SPECIFIED BY THE MANUFACTURER. IF THIS IS NOT THE CASE, THEN THE SAFETY PROTECTION PROVIDED BY THE EQUIPMENT MAY BE IMPAIRED.

## 2.2 Electrical installation

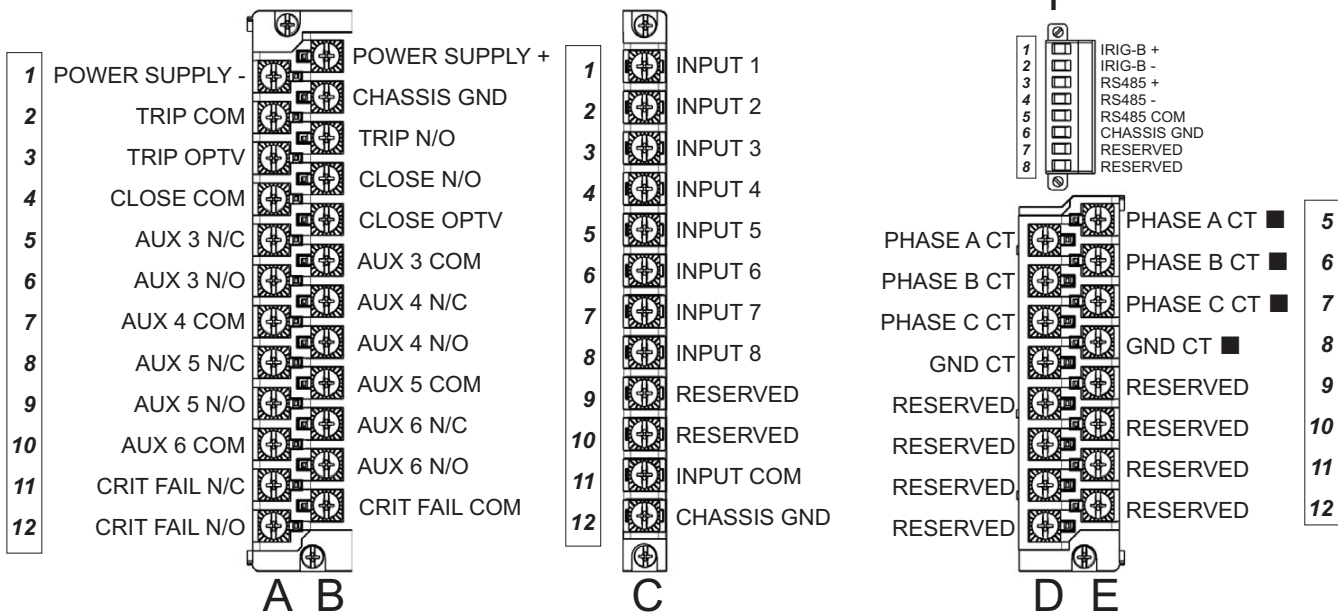
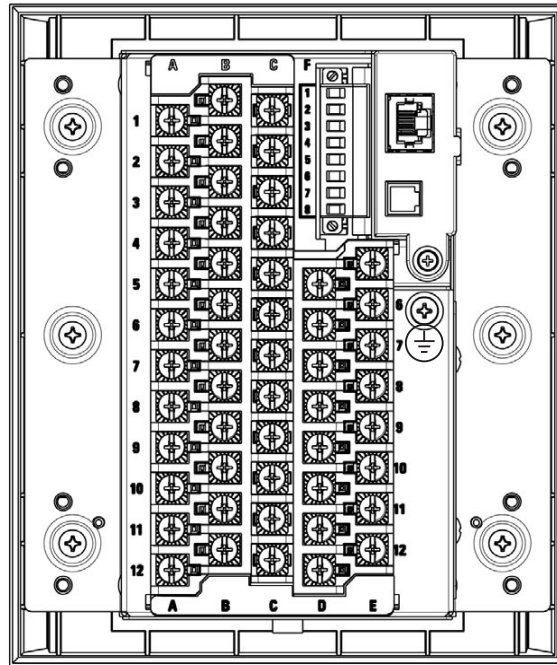
Figure 2-6: Typical wiring diagram



898743.CDR

## 2.2.1 Terminal identification

Figure 2-7: 350 Terminal Identification



## 2.2.2 Phase sequence and transformer polarity

For correct operation of the relay features, the user must follow the instrument transformer polarities, shown in the Typical Wiring Diagram. Note the solid square markings shown with all instrument transformer connections. When the connections adhere to this drawing, the arrow shows the direction of power flow for positive watts and the positive direction of lagging vars. The phase sequence is user programmable for either ABC or ACB rotation.

## 2.2.3 Current inputs

The 350 relay has four (4) channels for AC current inputs, each with an isolating transformer. There are no internal ground connections on the current inputs. Current transformers with 1 to 6000 A primaries may be used.



**Verify that the relay's nominal input current of 1 A or 5 A matches the secondary rating of the connected CTs. Unmatched CTs may result in equipment damage or inadequate protection.**



**IMPORTANT: The phase and ground current inputs will correctly measure up to 20 times the current input's nominal rating. Time overcurrent curves become horizontal lines for currents above the  $20 \times$  CT rating. This becomes apparent if the pickup level is set above the nominal CT rating.**



**Before working on CTs, they MUST be short circuited.**

## 2.2.4 Ground and sensitive ground CT inputs

One dedicated ground input is referred to throughout this manual as the **Ground Current** or **Sensitive Ground Current** input. Before making ground connections, consider that the relay automatically calculates the neutral (residual) current from the sum of the three phase current phasors. The following figures show three possible ground connections (or three possible sensitive ground connections).

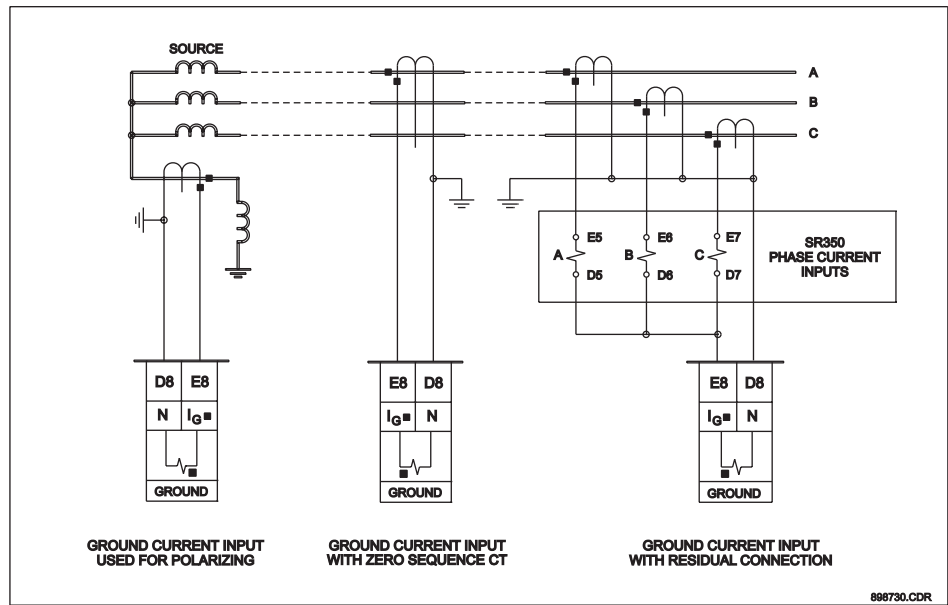
The ground input (Terminals D8 and E8) is used in conjunction with a Zero Sequence CT as source, or in the neutral of wye-connected source CTs. When using the residual connection set the GROUND CT PRIMARY setpoint to a value equal to the PHASE CT PRIMARY setpoint.

In cases where the relay is equipped with sensitive ground CT (terminals D8 and E8) the sensitive ground current input is intended for use either with a CT in a source neutral of a high-impedance grounded system, or on ungrounded systems. On ungrounded systems it is connected residually with the phase current inputs. In this case, the SENSTV GND CT PRIMARY setpoint should be programmed to a value equal to the PHASE CT PRIMARY setpoint. The sensitive ground current input can be connected to a Zero Sequence CT for increased sensitivity and accuracy when physically possible in the system.



The Sensitive Ground input must only be used on systems where the maximum ground current does not exceed 100 times the rated current for 1 second.

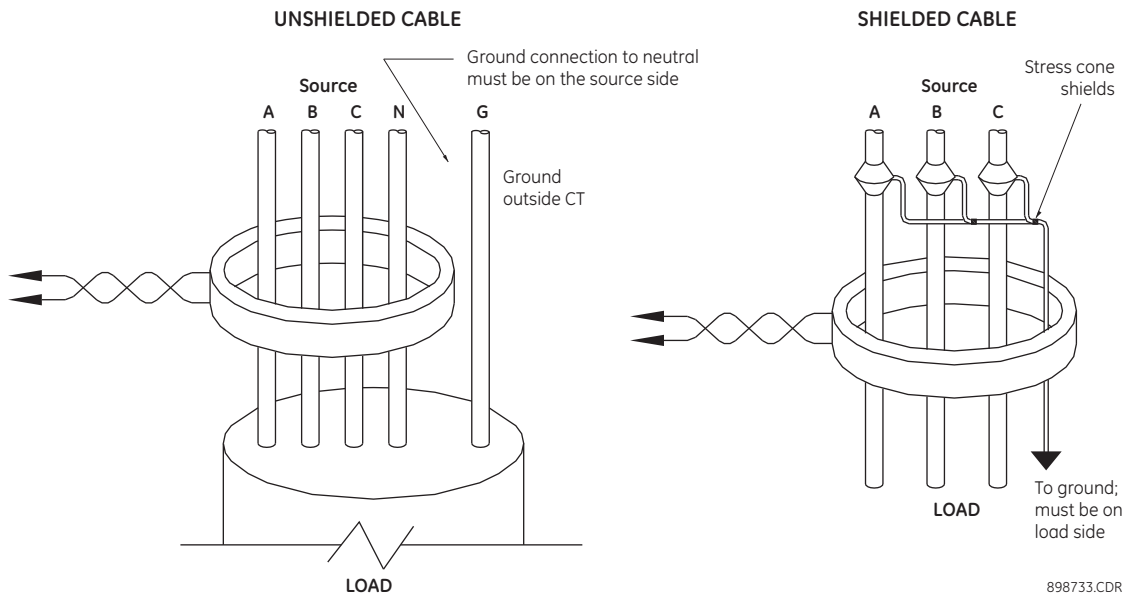
Figure 2-8: Ground/Sensitive Ground wiring



### 2.2.5 Zero sequence CT installation

The various CT connections and the exact placement of a Zero Sequence CT, for ground fault current detection, are shown in the figure below. Twisted pair cabling on the Zero Sequence CT is recommended.

Figure 2-9: Zero sequence core balance (CT) installation



## 2.2.6 Control power



Control power supplied to the relay must match the installed power supply range. If the applied voltage does not match, damage to the unit may occur. All grounds **MUST** be connected for safe, normal operation regardless of control power supply type.

The label found on the relay specifies its order code or model number. The installed power supply's operating range will be one of the following:

LO: 24 to 48 V DC (Range: 20 to 60 V DC)

HI: 125 to 250 V DC/120 to 240 V AC (Range: 84 to 250 V DC/66 to 265 V AC)



The relay should be connected directly to the ground bus, using the shortest practical path. A tinned copper, braided, shielding and bonding cable should be used. As a minimum, 96 strands of number 34 AWG should be used. Belden catalog number 8660 is suitable.

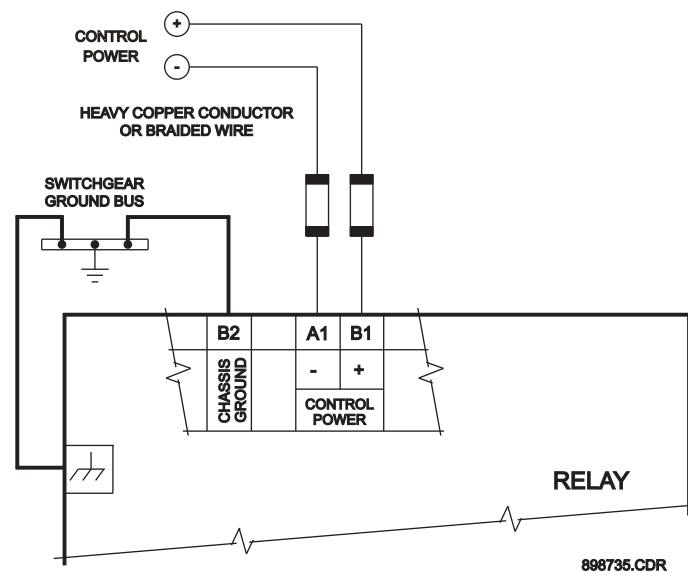


Isolate power prior to servicing.



An external switch, circuit breaker, or other protective device **must** be connected near to the equipment.

Figure 2-10: Control power connection



## 2.2.7 Trip and Close output relays

The 350 relay is equipped with seven electromechanical output relays: two special relays designed for Breaker trip and close (Relay 1 "Trip", Relay 2 "Close"), four general purpose relays (Auxiliary Relays 3 to 6), and a Critical Failure relay. The special purpose relays have fixed operating characteristics and the general purpose relays can be configured by the user.

Operation of the Trip and Close output relays is designed to be controlled by the state of the circuit breaker as monitored by a 52a or 52b contact.

- The Trip and Close relays reset after the breaker is detected in a state corresponding to the command. When a relay feature sends a command to one of these special relays, it will remain operational until the requested change of breaker state is confirmed by a breaker auxiliary contact and the initiating condition has reset.

- If the initiating feature resets, but the breaker does not change state, the output relay will be reset after a default interval of 2 seconds.
- If neither of the breaker auxiliary contacts, 52a nor 52b, is programmed to a contact input, the Trip Relay is de-energized after either the delay programmed in the Breaker Failure feature, or a default interval of 100 ms after the initiating input resets. The Close Relay is de-energized after 200 ms.
- If a delay is programmed for the Trip or Close contact seal-in time, then this delay is added to the reset time. Note that the default setting for the seal-in time is 40 ms.

52a Contact Configured	52b Contact Configured	Relay Operation
Yes	Yes	Trip Relay remains operational until 52b indicates an open breaker. Close Relay remains operational until 52a indicates a closed breaker.
Yes	No	Trip Relay remains operational until 52a indicates an open breaker. Close Relay remains operational until 52a indicates a closed breaker.
No	Yes	Trip Relay remains operational until 52b indicates an open breaker. Close Relay remains operational until 52b indicates a closed breaker.
No	No	Trip Relay operates until either the Breaker Failure delay expires (if the Breaker Failure element is enabled), or 100 ms after the feature causing the trip resets. Close Relay operates for 200 ms.

Breaker monitoring (Trip and Close coil monitoring) is performed by a built-in voltage monitor on Form A output relays: #1 Trip, and #2 Close. The voltage monitor is connected across each of the two Form A contacts, and the relay effectively detects healthy current through the circuit. In order to do this, an external jumper must be connected between terminals A2 and A3 for Trip coil monitoring, or/and B4, and B5 for Close coil monitoring.

As long as the current through the Voltage Monitor is above the threshold of the trickle currents (see Technical Specification for Form A output relays), the circuit integrity for the Trip (Close) coil is effectively normal. If the Trip (Close) coil circuit gets disconnected, or if in general a high resistance is detected in the circuitry, a Trip (Close) alarm will be set and the "ALARM" and "MAINTENANCE" LEDs will be on.

**Example 1:** The figures below show the two different connections of the breaker trip (close) coil to the relay's trip output #1 terminals (output #2 Close coil monitoring) for both no voltage monitoring and voltage monitoring of the trip (close) circuit integrity.



NOTE

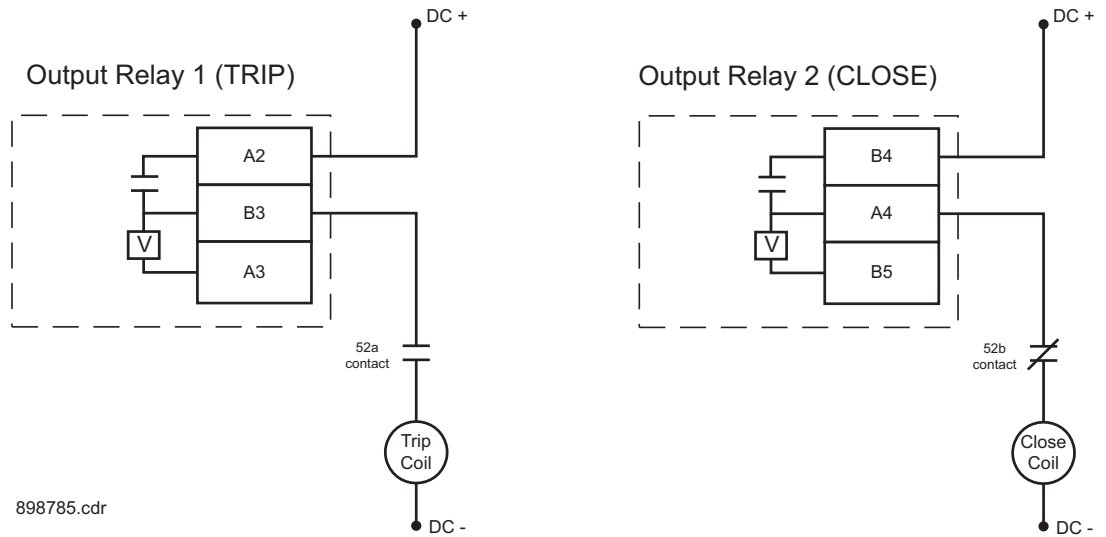
To monitor the trip coil circuit integrity, use the relay terminals A2 and B3 to connect the Trip coil, and provide a jumper between terminals A2 (optional voltage) and A3.



NOTE

To monitor the close coil circuit integrity, use the relay terminals B4 and A4 to connect the Close coil, and provide a jumper between terminals B4 (optional voltage) and B5.

Figure 2-11: Trip and Close circuits with no voltage monitoring

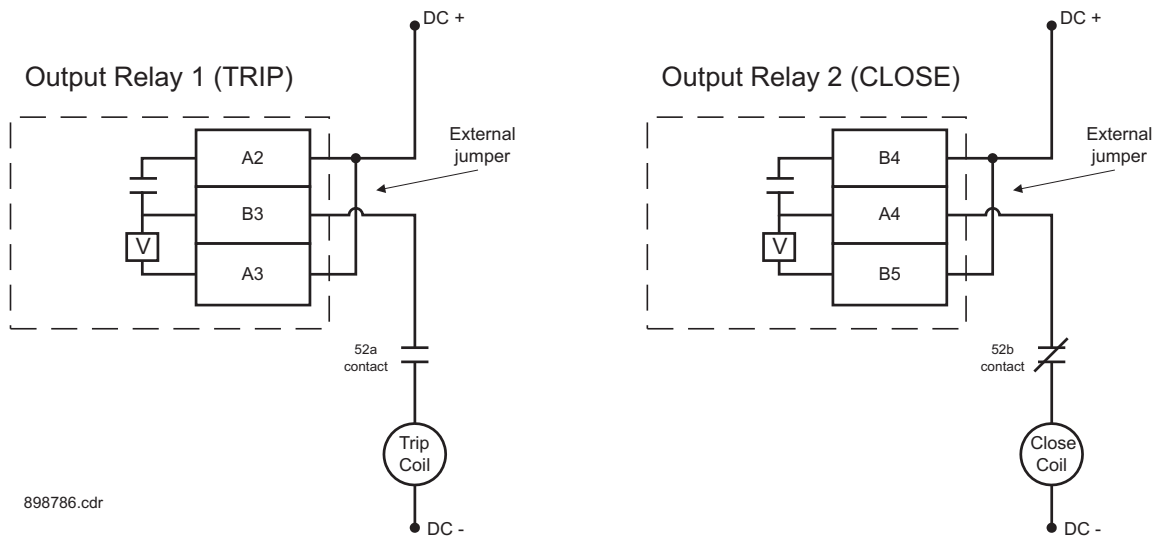


898785.cdr



All AUX contacts are shown when the breaker is open.

Figure 2-12: Trip and close circuits with voltage monitoring



898786.cdr

### 2.2.8 Contact inputs

External contacts can be connected to the relay's eight (8) digital inputs. These contacts are wet only.

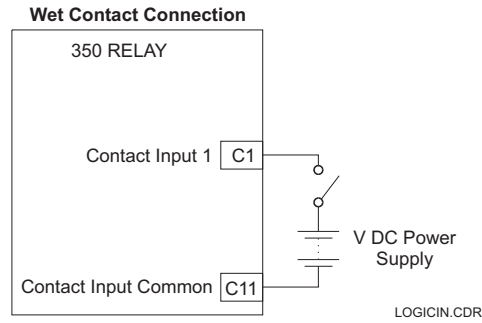
The inputs can be programmed to different thresholds depending on the DC voltage (17, 33, 84, 166).



**Ensure correct polarity on contact input connections and do not connect any contact input circuits to ground or else relay hardware may be damaged.**

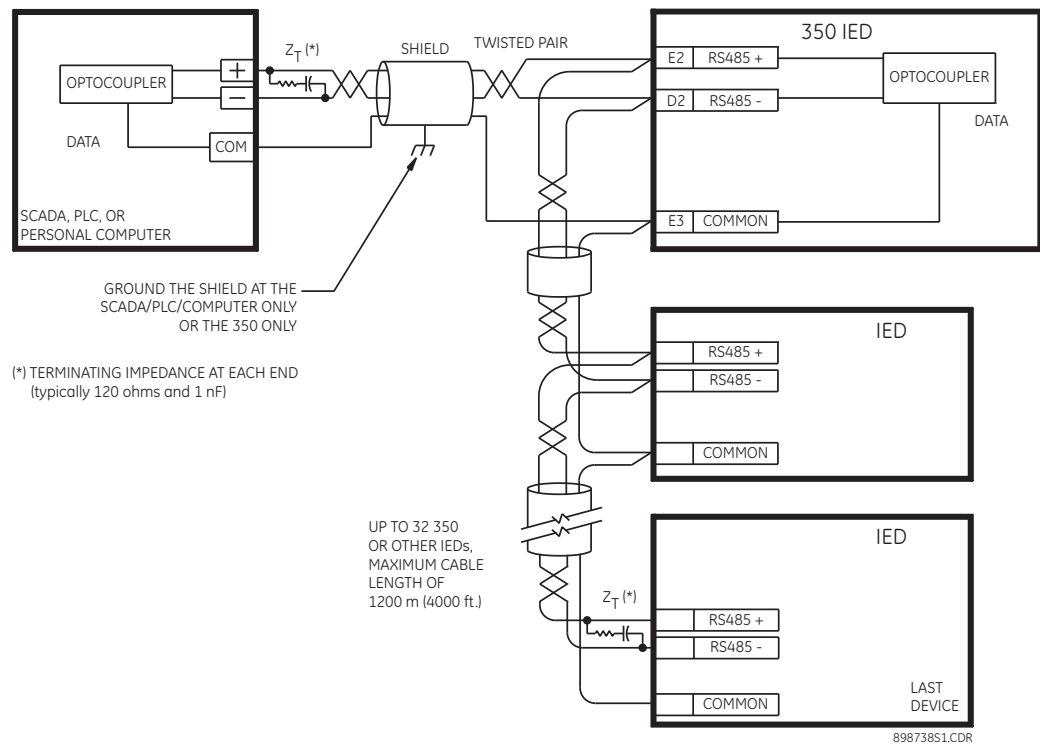
A wet contact has one side connected to the positive terminal of an external DC power supply. The other side of this contact is connected to the required contact input terminal. In addition, the negative side of the external source must be be connected to the relay's DC negative rail at Terminal C11. The maximum external source voltage for this arrangement is 300 V DC.

Figure 2-13: Wet contact connections



### 2.2.9 Serial communications

Figure 2-14: RS485 wiring diagram



One two-wire RS485 port is provided. Up to 32 350 IEDs can be daisy-chained together on a communication channel without exceeding the driver capability. For larger systems, additional serial channels must be added. Commercially available repeaters can also be used to add more than 32 relays on a single channel. Suitable cable should have a characteristic impedance of 120 ohms (for example, Belden #9841) and total wire length should not exceed 1200 meters (4000 ft.). Commercially available repeaters will allow for transmission distances greater than 1200 meters.

Voltage differences between remote ends of the communication link are not uncommon. For this reason, surge protection devices are internally installed across all RS485 terminals. Internally, an isolated power supply with an optocoupled data interface is used to prevent noise coupling.



**To ensure that all devices in a daisy-chain are at the same potential, it is imperative that the common terminals of each RS485 port are tied together and grounded only once, at the master or at the 350. Failure to do so may result in intermittent or failed communications.**

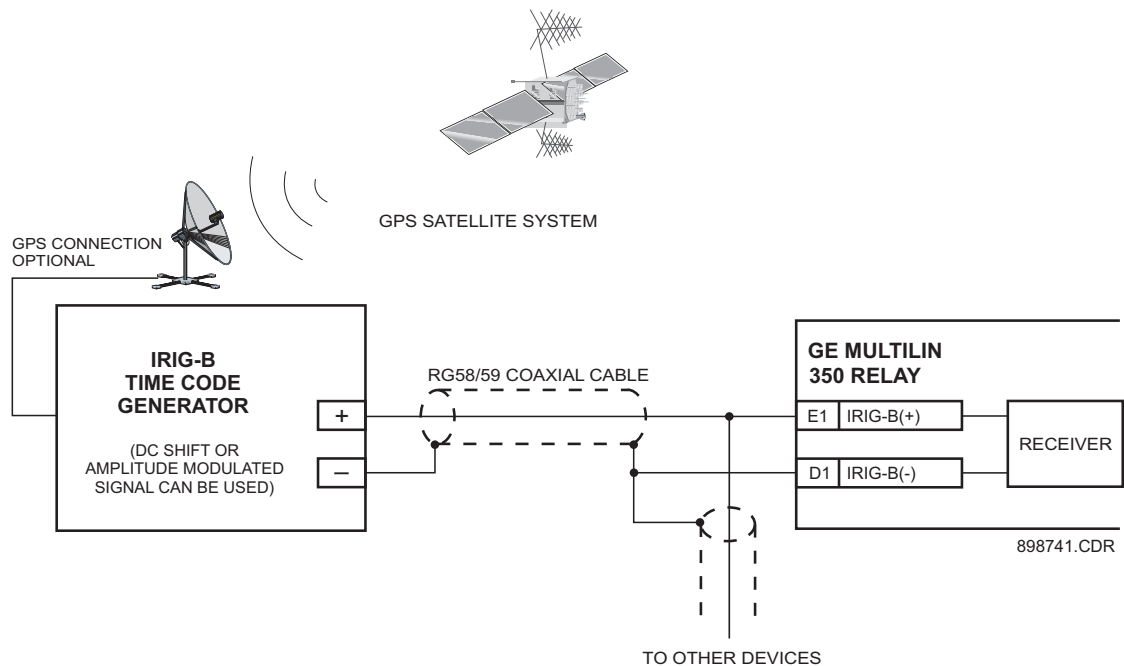
The source computer/PLC/SCADA system should have similar transient protection devices installed, either internally or externally. Ground the shield at one point only, as shown in the figure above, to avoid ground loops.

Correct polarity is also essential. The 350 IEDs must be wired with all the positive (+) terminals connected together and all the negative (-) terminals connected together. Each relay must be daisy-chained to the next one. Avoid star or stub connected configurations. The last device at each end of the daisy-chain should be terminated with a 120 ohm ¼ watt resistor in series with a 1 nF capacitor across the positive and negative terminals. Observing these guidelines will ensure a reliable communication system immune to system transients.

## 2.2.10 IRIG-B

IRIG-B is a standard time code format that allows time stamping of events to be synchronized among connected devices within 1 millisecond. The IRIG time code formats are serial, width-modulated codes which can be either DC level shift or amplitude modulated (AM) form. The type of form is auto-detected by the 350 relay. Third party equipment is available for generating the IRIG-B signal; this equipment may use a GPS satellite system to obtain the time reference so that devices at different geographic locations can also be synchronized.

**Figure 2-15: IRIG-B connection**







# 350 Feeder Protection System

## Chapter 3: Interfaces

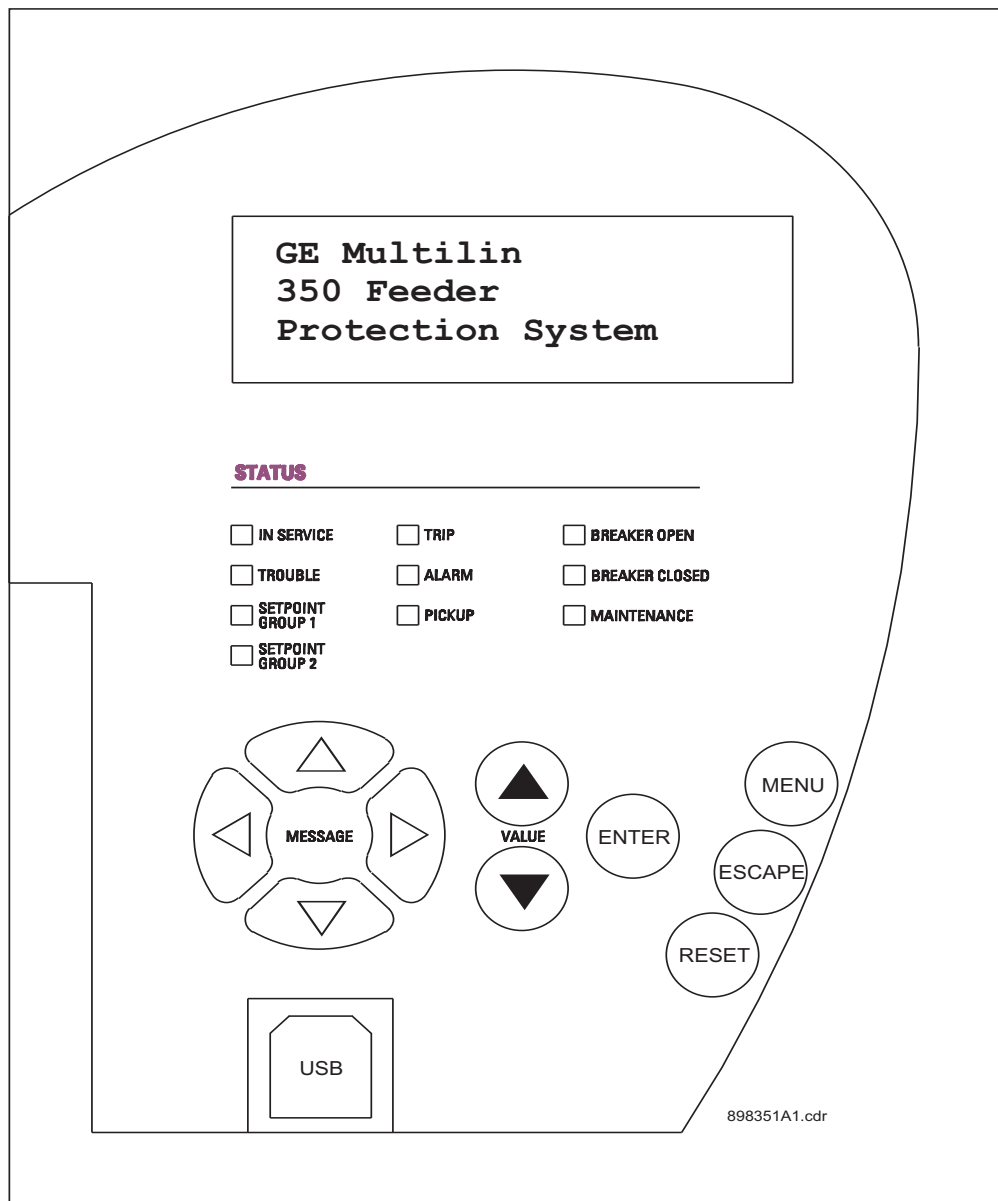
There are two methods of interfacing with the 350 Feeder Protection System.

- Interfacing via the relay keypad and display.
- Interfacing via the EnerVista SR3 Setup software.

This section provides an overview of the interfacing methods available with the 350 using the relay control panels and EnerVista SR3 Setup software. For additional details on interface parameters (for example, settings, actual values, etc.), refer to the individual chapters.

## 3.1 Front control panel interface

Figure 3-1: 350 Feeder Protection System Front Panel



### 3.1.1 Description

The relay front panel provides an interface with a liquid crystal display, LED status indicators, control keys, and a USB program port. The display and status indicators show the relay information automatically. The control keys are used to select the appropriate message for entering setpoints or displaying measured values. The USB program port is also provided for connection with a computer running the EnerVista SR3 Setup software.

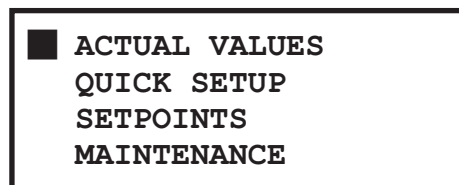
### 3.1.2 Display

The 80-character liquid crystal display (LCD) allows visibility under varied lighting conditions. When the keypad and display are not being used, system information is displayed after a user-defined period of inactivity. Pressing the Menu key during the display of default message returns the display to the last message shown before the default message appeared. Any trip, alarm, or pickup is displayed immediately, automatically overriding the default message.

### 3.1.3 Working with the Keypad

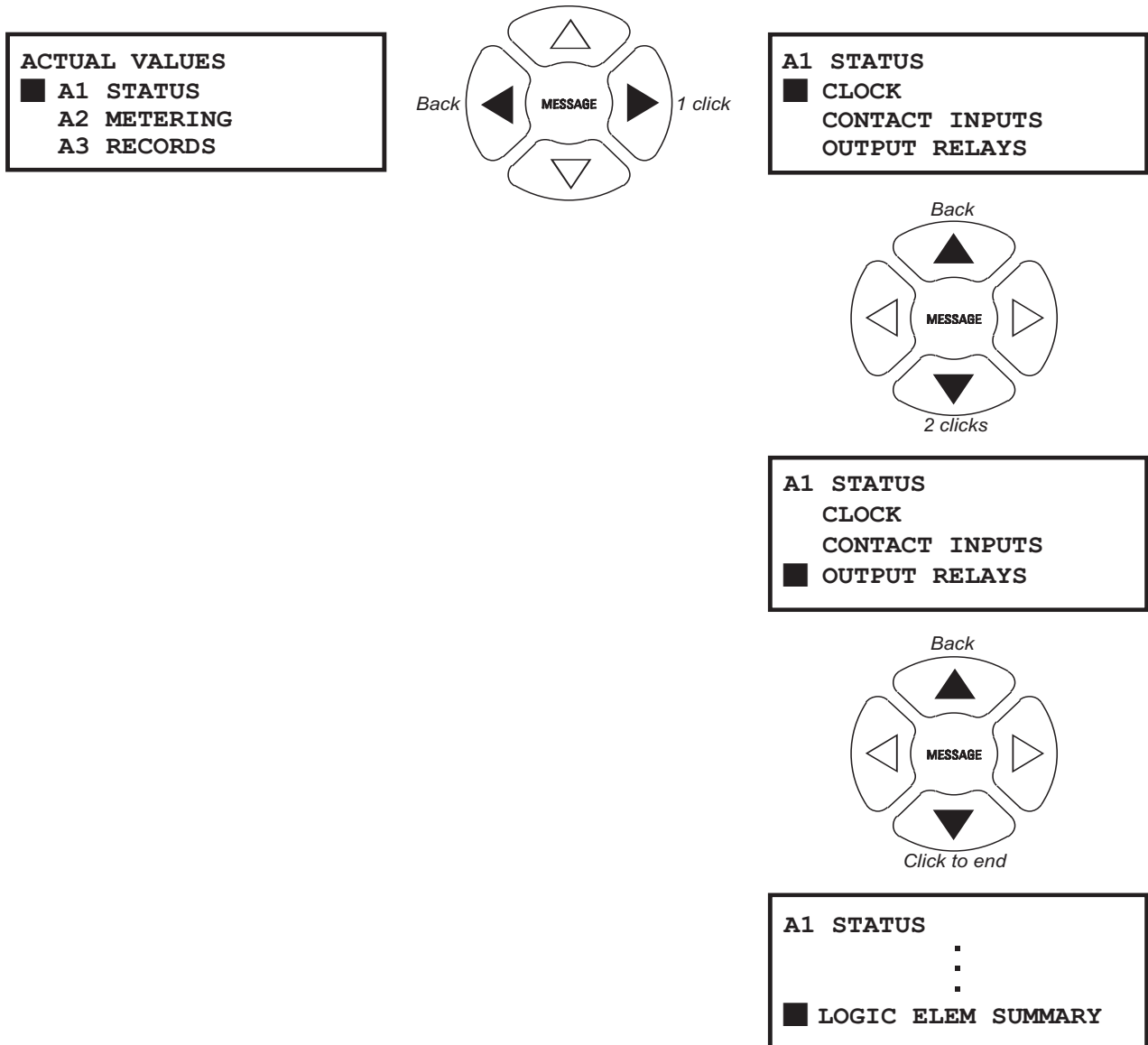
The 350 display messages are organized into a Main Menu, pages, and sub-pages. There are four main menus labeled Actual Values, Quick Setup, Setpoints, and Maintenance. Pressing the MENU key followed by the MESSAGE key scrolls through the four Main Menu headers, which appear in sequence as follows:

Figure 3-2: The four Main Menu headers



Pressing the **MESSAGE** ► key or the **ENTER** key from these Main Menu pages will display the corresponding menu Page. Use the MESSAGE ▲ and MESSAGE ▼ keys to scroll through the Page headers.

Figure 3-3: Typical paging operation from Main Menu selection



When the display shows **SETPOINTS**, pressing the **MESSAGE ►** key or the **ENTER** key will display the page headers of programmable parameters (referred to as setpoints in the manual). When the display shows **ACTUAL VALUES**, pressing the **MESSAGE ►** key or the **ENTER** key displays the page headers of measured parameters (referred to as actual values in the manual).

Each page is broken down further into logical sub-pages of messages. The **MESSAGE ▲** and **MESSAGE ▼** keys are used to navigate through the sub-pages. A summary of the setpoints and actual values pages can be found in the Chapters : Setpoints and Actual Values, respectively.

The **ENTER** key is dual purpose. It is used to enter the sub-pages and to store altered setpoint values into memory to complete the change. The **MESSAGE ►** key can also be used to enter sub-pages but not to store altered setpoints.

The **ESCAPE** key is also dual purpose. It is used to exit the sub-pages and to cancel a setpoint change. The **MESSAGE** ◀ key can also be used to exit sub-pages and to cancel setpoint changes.

The **VALUE** keys are used to scroll through the possible choices of an enumerated setpoint. They also decrement and increment numerical setpoints.

The **RESET** key resets any latched conditions that are not currently active. This includes resetting latched output relays, latched Trip LEDs, breaker operation failure, and trip / close coil failures. The Autoreclose Scheme is also reset with the shot counter being returned to zero and the lockout condition being cleared.

The **MESSAGE** ▲ and **MESSAGE** ▼ keys scroll through any active conditions in the relay. Diagnostic messages are displayed indicating the state of protection and monitoring elements that are picked up, operating, or latched.

### 3.1.4 LED status indicators

- **IN SERVICE: Green**  
This LED will be continuously “ON”, when the relay is set to “Ready” under S1 RELAY SETUP/INSTALLATION/RELAY STATUS, and no major self-test errors have been detected.
- **TROUBLE: Amber**  
This LED will turn “ON”, when the relay is not programmed (Not Ready) state under S1 RELAY SETUP/INSTALLATION/RELAY STATUS, or upon detection of a major self-test error. The relay will turn back to “IN-SERVICE” if no major self-test error is present.
- **SETPOINT GROUP 1, 2: Green**  
These LEDs indicate the group of active protection elements. If setpoint group 1 is lit green, only the protection elements under group 1 will be active. The protection elements from group 2 will be inactive. The settings for each protection element can be edited and displayed regardless of the active group.
- **TRIP: Red**  
This indicator turns on when the relay detects a fault and sends a trip command to the trip output relay. The LED will reset by initiating a reset command from either the RESET pushbutton Breaker Control, or communications; in all cases after the fault condition has cleared.
- **ALARM: Amber**  
This LED will flash upon detection of an alarm condition, with element functions selected as “alarm”. The LED will automatically turn off if the alarm condition clears. The LED will remain steady “ON”, if the function of the operated protection was selected as “latched alarm”.
- **PICKUP: Amber**  
This indicator will light ON upon pickup condition generated by any of the relay features. The indicator will turn off if no pickup condition is detected.
- **BREAKER OPEN: Red/Green – programmable**  
When the breaker is open, this indicator will be on continuously.
- **BREAKER CLOSED: Red/Green – programmable**  
When the breaker is closed, this indicator will be on continuously.  
Breaker status indication is based on the breaker’s 52a and 52b contacts. With both contacts wired to the relay, closed breaker status is determined by closed 52a contact and opened 52b contact. Visa-versa the open breaker status is determined by opened

52a contact and closed 52b contact. If both 52a and 52b contacts are open, due to a breaker being racked out from the switchgear, both the Breaker Open and Breaker Closed LED Indicators will be off.



It is strongly recommended to detect the breaker status by using both 52a and 52b contacts.

The 350 provides also detecting the breaker status by using only one contact: either 52a or 52b. However, one should be aware that in such cases, it would be impossible to distinguish between a breaker open state and breaker racked out state, unless another contact from the breaker is wired to the relay.

To clarify this ambiguity, the BKR CONNECTED function under SETPOINTS/S2 SYSTEM SETUP/S2 BREAKER should be programmed to an additional contact input. When this additional input is closed, a single 52a or 52b contact will show both breaker states. When the breaker is racked out, this additional breaker connected input should be open. In this case, both breaker status indicators will be off.

- **MAINTENANCE: Amber**

This LED may indicate both breaker or relay maintenance depending on the programmed maintenance elements. The LED will turn on upon operation of a maintenance element.

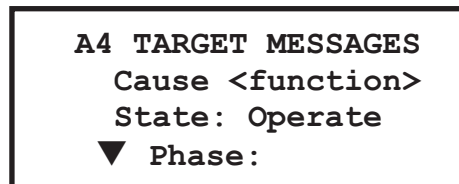
### 3.1.5 Relay messages

#### 3.1.5.1 Target messages

Target messages are automatically displayed for any active condition on the relay such as pickups, trips, or alarms.

The relay displays the most recent event first, and after 5 seconds will start rolling up the other target messages until the conditions clear and/or the RESET command is initiated. The Target Messages can be reviewed by pressing either the MESSAGE UP or MESSAGE DOWN key. If a RESET command is not performed but any of the other faceplate pushbuttons is pressed, the display will not show the target messages unless the user navigates to [ACTUAL VALUES > A4 TARGET MESSAGES](#), where they can be reviewed. If the target messages have not been cleared before the user presses a pushbutton different from "RESET", they will reappear on the screen after the time specified under the [SETPOINTS > S1 RELAY SETUP > S1 FRONT PANEL > MESSAGE TIMEOUT](#) setting, that will start timing out from the last pressed pushbutton. The following shows the format of a typical Target Message:

Figure 3-4: Typical target message



Example of a Phase IOC1 operation - phase A:

Phase IOC1 function: Trip

```

A4 TARGET MESSAGES
Ph IOC1 Trip
State: Operate
▼ Phase:A

```

**Cause <Function>**

The first line contains information of the cause of operation (the name of the operated element), and the element function.

**State: Operate**

This line from the display shows the state of the element: Pickup, Operated, Alarm.

**Phase: A**

The last line from the display shows the phase that picked up or operated.

**3.1.5.2 Self-test errors**

The relay performs self diagnostics at initialization (after power up), and continuously as a background task to ensure that the hardware and software are functioning correctly. There are two types of self-test warnings indicating either a minor or major problem. Minor problems indicate a problem with the relay that does not compromise protection of the power system. Major errors indicate a problem with the relay which takes it out of service.

**Self-Test Warnings may indicate a serious problem with the relay hardware!**

Upon detection of a **minor** problem, the relay will:

- Turn on the "TROUBLE" LED at the same time as the "IN SERVICE" LED is on.
- Display the error on the relay display.
- Record the minor self-test error in the Event Recorder.

Upon detection of a **major** problem, the relay will:

- De-energize critical failure relay (Output Relay 7).
- Inhibit operation of all other output relays (1 to 6).
- Turn off the "IN SERVICE" LED; turn on the "TROUBLE" LED.
- Flash the "ALARM" LED.
- Display the cause of major self-test failure.
- Record the major self-test failure in the Event Recorder.

**Figure 3-5: Typical Self-test warning**

```

A4 TARGET MESSAGES
UNIT FAILURE:
Contact Factory:
Error code:1

```

**Table 1: Minor Self-test Errors**

Self-test Error Message	Latched Target Message?	Description of Problem	How Often the Test is Performed	What to do
MAINTENANCE ALERT: IRIG-B Failure	No	A bad IRIG-B input signal has been detected.	Every 5 seconds	Ensure IRIG-B cable is connected, check cable functionality (i.e. physical damage or perform continuity test), ensure IRIG-B receiver is functioning, and check input signal level (it may be less than specification). If none of these apply, contact the factory.
MAINTENANCE ALERT: Clock Not Set	No	Clock time is the same as the default time.	Every 5 seconds	Set the date and time in PRODUCT SETUP.
MAINTENANCE ALERT: Comm Alert 1, 2, or 3	No	Communication error between CPU and Comms board.	Every 5 seconds	If alert doesn't self-reset, then contact factory. Otherwise monitor recurrences as errors are detected and self-reset.
MAINTENANCE ALERT: Ethernet Link Fail	No	Communication error between 350 and Network.	Detected Instantaneously	Check Ethernet cable and Ethernet connection. Check health of the network. Check status of external routers and switches.

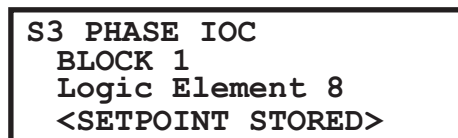
**Table 2: Major Self-test Errors**

Self-test Error Message	Latched Target Message?	Description of Problem	How Often the Test is Performed	What to do
UNIT FAILURE: Contact Factory (XXXX)	Yes	This warning is caused by a unit hardware failure. Failure code (XXXX) is shown.	Every 5 seconds	Contact the factory and provide the failure code.
RELAY NOT READY: Check Settings	No	PRODUCT SETUP INSTALLATION setting indicates that relay is not in a programmed state.	On power up and whenever the PRODUCT SETUP INSTALLATION setting is altered.	Program all required settings then set the PRODUCT SETUP INSTALLATION setting to "Programmed".

**3.1.5.3 Flash messages**

Flash messages are warning, error, or general information messages displayed in response to pressing certain keys. The factory default flash message time is 4 seconds.

**Figure 3-6: Typical Flash message**



**SETPOINT STORED**

This flash message is displayed in response to the **ENTER** key while on any setpoint message (see example above). The edited value was stored as entered.

**COMMAND EXECUTED**

This flash message is displayed in response to executing a command: ON, OFF, YES, NO, etc.

**INVALID PASSWORD**

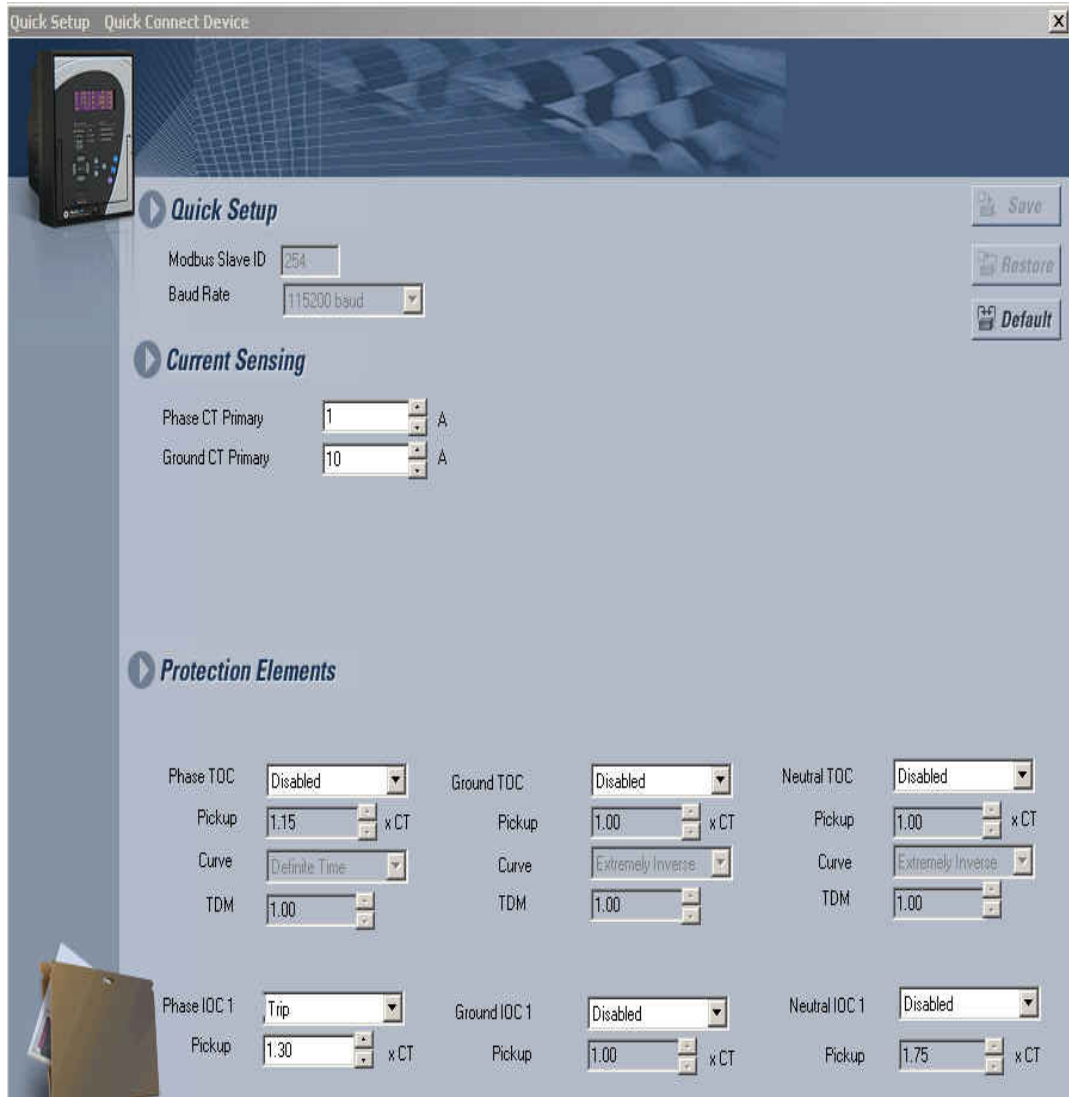
This flash message appears upon an attempt to enter an incorrect password, as part of password security.

**AR IN PROGRESS**

This flash message appears when the Autoreclosure is in progress performing the configured sequence.

## 3.2 Software setup

### 3.2.1 Quick setup - Software interface



- **The Quick Setup** window allows you to configure important settings from different screens in the relay by adding them to a common window.
- **Quick Setup** window options are available for a single device or a file.
- **The Quick Setup** Window option is accessed from the "Tree" which launches on clicking.

### 3.2.2 EnerVista SR3 Setup Software

Although settings can be entered manually using the control panel keys, a PC can be used to download setpoints through the communications port. The EnerVista SR3 Setup software is available from GE Multilin to make this as convenient as possible. With EnerVista SR3 Setup running, it is possible to:

- Program and modify settings
- Load and save setting files to and from a disk
- Read actual values
- Monitor status
- Read pre-trip data and event records
- Get help on any topic
- Upgrade the 350 firmware

The EnerVista SR3 Setup software allows immediate access to all 350 features with easy to use pull down menus in the familiar Windows environment. This section provides the necessary information to install EnerVista SR3 Setup, upgrade the relay firmware, and write and edit setting files.

The EnerVista SR3 Setup software can run without a 350 connected to the computer. In this case, settings may be saved to a file for future use. If a 350 is connected to a PC and communications are enabled, the 350 can be programmed from the setting screens. In addition, measured values, status and trip messages can be displayed with the actual value screens.

### 3.2.2.1 Hardware and software requirements

The following requirements must be met for the EnerVista SR3 Setup software.

- Microsoft Windows™ 2000 / XP / Vista is installed and running properly.
- At least 100 MB of hard disk space is available.
- At least 256 MB of RAM is installed.

The EnerVista SR3 Setup software can be installed from either the GE EnerVista CD or the GE Multilin website at <http://www.GEmultilin.com>.

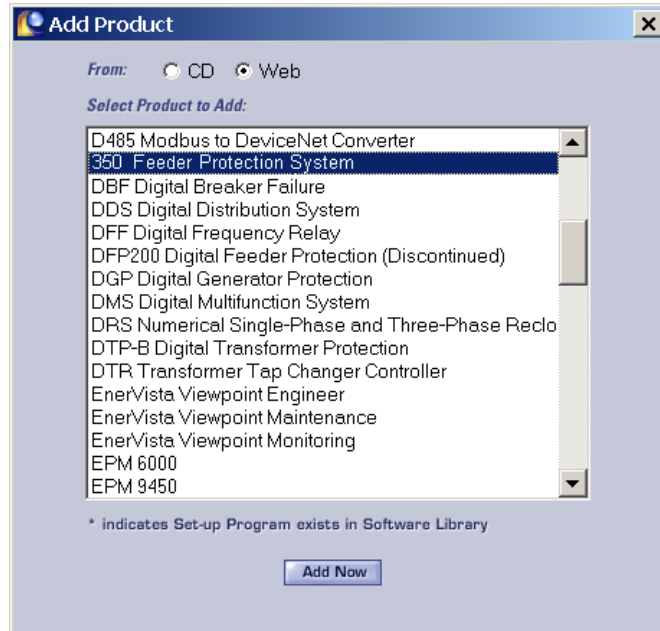
### 3.2.2.2 Installing the EnerVista SR3 Setup software

After ensuring the minimum requirements indicated earlier, use the following procedure to install the EnerVista SR3 Setup software from the enclosed GE EnerVista CD.

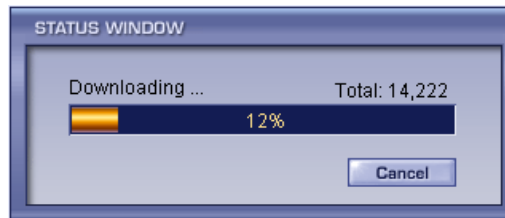
1. Insert the GE EnerVista CD into your CD-ROM drive.
2. Click the **Install Now** button and follow the installation instructions to install the no-charge EnerVista software on the local PC.
3. When installation is complete, start the EnerVista Launchpad application.
4. Click the **IED Setup** section of the LaunchPad toolbar.



5. In the EnerVista Launchpad window, click the **Add Product** button and select the 350 Feeder Protection System as shown below. Select the Web option to ensure the most recent software release, or select CD if you do not have a web connection, then click the **Add Now** button to list software items for the 350.



6. EnerVista Launchpad will obtain the latest installation software from the Web or CD and automatically start the installation process. A status window with a progress bar will be shown during the downloading process.

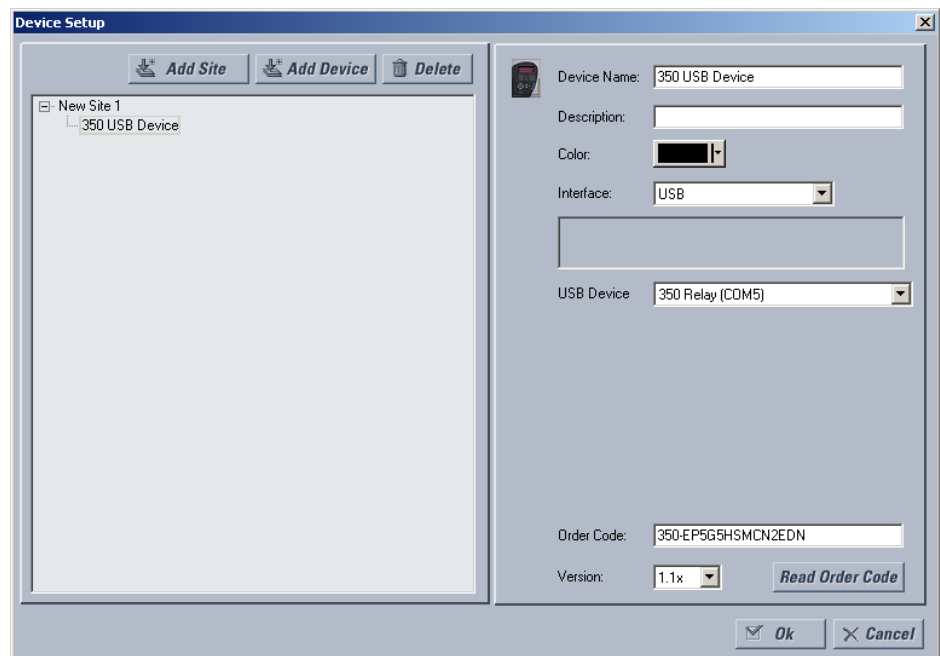


7. Select the complete path, including the new directory name, where the EnerVista SR3 Setup software will be installed.
8. Click on **Next** to begin the installation. The files will be installed in the directory indicated, the USB driver will be loaded into the computer, and the installation program will automatically create icons and add EnerVista SR3 Setup software to the Windows start menu.
9. The 350 device will be added to the list of installed IEDs in the EnerVista Launchpad window, as shown below.



If you are going to communicate from your computer to the 350 Relay using the USB port:

10. Plug the USB cable into the USB port on the 350 Relay then into the USB port on your computer.
11. Launch EnerVista SR3 Setup from LaunchPad.
12. In **EnerVista > Device Setup**:



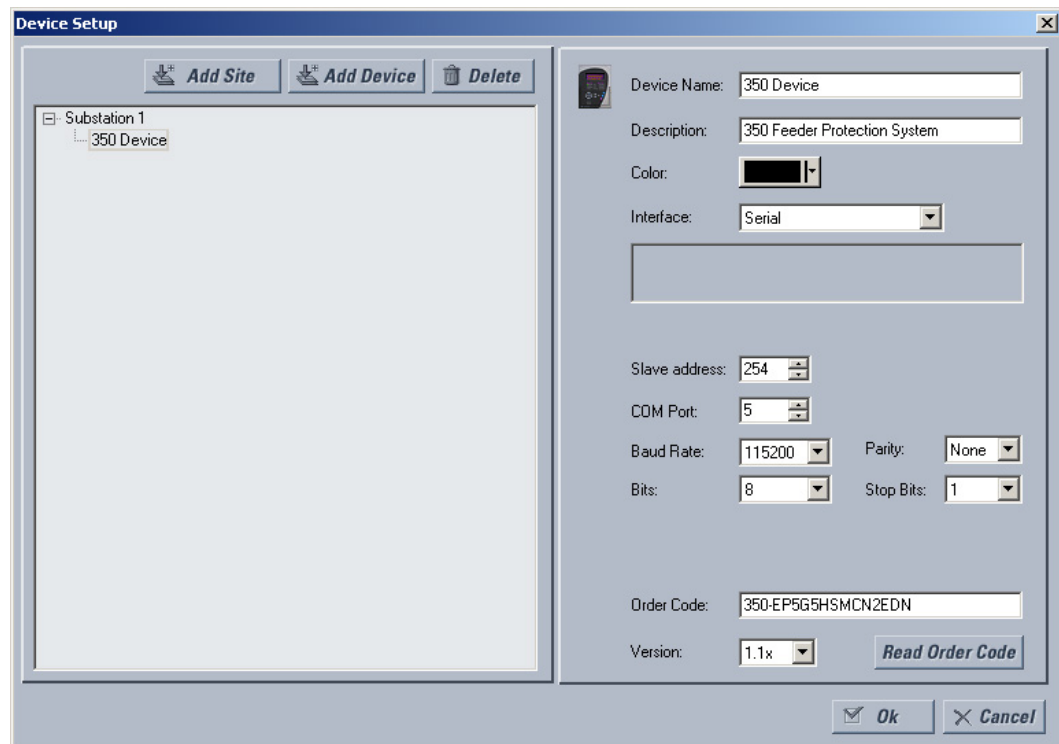
13. Select **USB** as the Interface type.
14. Select **350 Relay** as the USB device.

## 3.2.3 Connecting EnerVista SR3 Setup to the relay

### 3.2.3.1 Configuring serial communications

Before starting, verify that the cable is properly connected to either the USB port on the front panel of the device (for USB communications) or to the RS485 terminals on the back of the device (for RS485 communications). This example demonstrates an USB connection. For RS485 communications, the GE Multilin F485 converter will be required. Refer to the F485 manual for additional details. To configure the relay for Ethernet communications, see *Configuring Ethernet Communications* below.

1. Install and start the latest version of the EnerVista SR3 Setup software (available from the GE EnerVista CD). See the previous section for the installation procedure.
2. Click on the **Device Setup** button to open the Device Setup window and click the **Add Site** button to define a new site.
3. Enter the desired site name in the "Site Name" field. If desired, a short description of the site can also be entered. In this example, we will use "Substation 1" as the site name.
4. The new site will appear in the upper-left list in the EnerVista SR3 Setup window.
5. Click the **Add Device** button to define the new device.
6. Enter the desired name in the "Device Name" field and a description (optional) of the device.
7. Select "USB Device" from the Interface drop-down list.



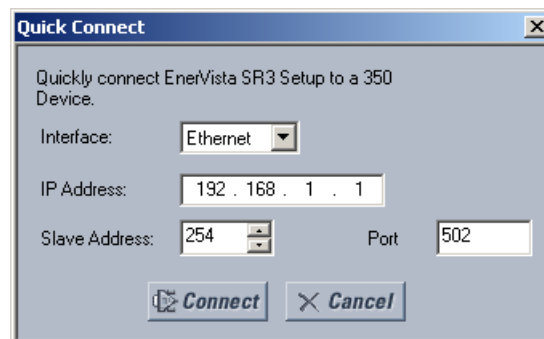
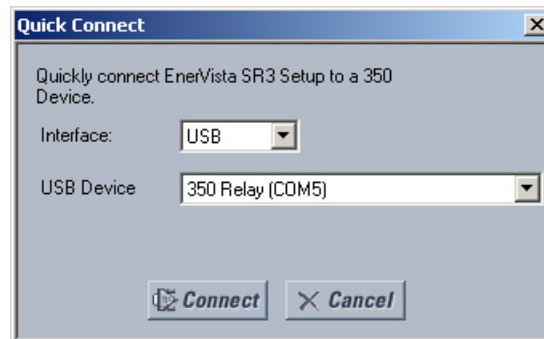
8. Select the 350 relay as the USB device.
9. Click the **Read Order Code** button to connect to the 350 device and upload the order code.

10. Click **OK** when the relay order code has been received. The new device will be added to the Site List window (or Online window) located in the top left corner of the main EnerVista SR3 Setup window.

The 350 Site Device has now been configured for USB communications. Proceed to *Connecting to the Relay* below, to begin communications.

### 3.2.3.2 Using the Quick Connect feature

The **Quick Connect** button can be used to establish a fast connection through the front panel USB port of a 350 relay, or through the Ethernet port. The following window will appear when the **QuickConnect** button is pressed:



As indicated by the window, the "Quick Connect" feature can quickly connect the EnerVista SR3 Setup software to a 350 front port if the USB is selected in the interface drop-down list. Select "350 Relay" and press the **Connect** button. Ethernet can also be used as the interface for Quick Connect as shown above.

When connected, a new Site called "Quick Connect" will appear in the Site List window.



The 350 Site Device has now been configured via the Quick Connect feature for either USB or Ethernet communications. Proceed to *Connecting to the Relay* below, to begin communications.

### 3.2.3.3 Configuring Ethernet communications

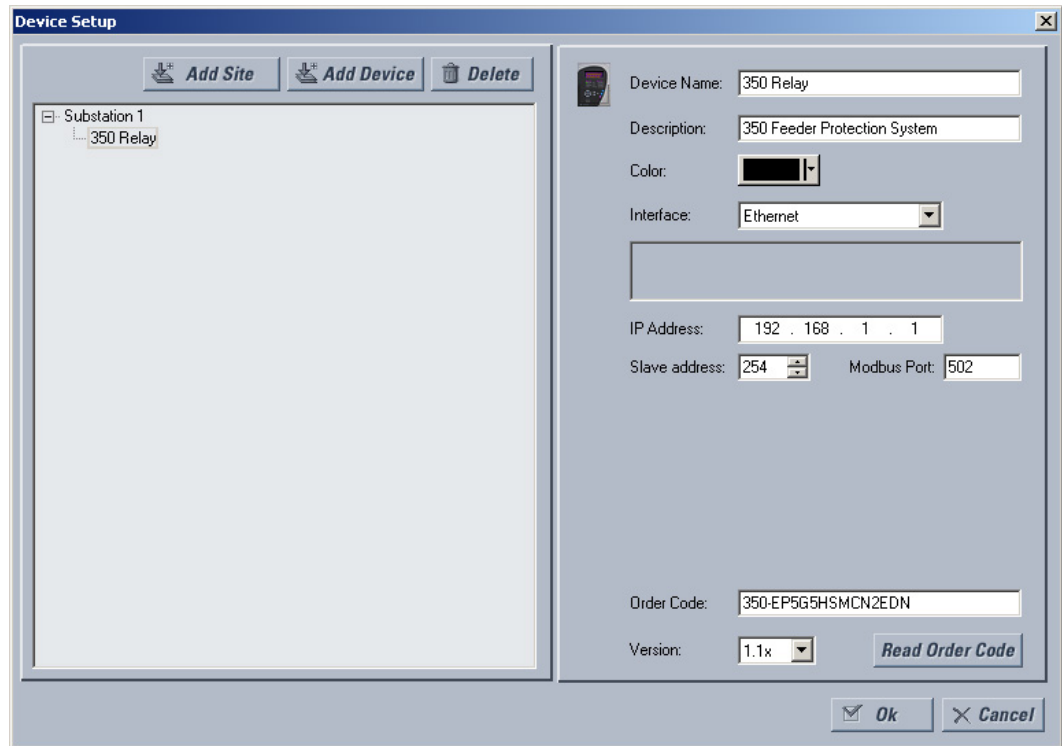
Before starting, verify that the Ethernet cable is properly connected to the RJ-45 Ethernet port.

350 supports a maximum of 3 TCP/IP sessions.



NOTE

1. Install and start the latest version of the EnerVista SR3 Setup Setup software (available from the GE EnerVista CD). See the previous section for the installation procedure.
2. Click on the **Device Setup** button to open the Device Setup window and click the **Add Site** button to define a new site.
3. Enter the desired site name in the "Site Name" field. If desired, a short description of the site can also be entered. In this example, we will use "Substation 1" as the site name.
4. The new site will appear in the upper-left list.
5. Click the **Add Device** button to define the new device.
6. Enter the desired name in the "Device Name" field, and a description (optional).
7. Select "Ethernet" from the Interface drop-down list. This will display a number of interface parameters that must be entered for proper Ethernet functionality.



8. Enter the IP address, slave address, and Modbus port values assigned to the 350 relay (from the S1 RELAY SETUP > COMMUNICATIONS > ETHERNET menu).
9. Click the **Read Order Code** button to connect to the 350 and upload the order code. If a communications error occurs, ensure that the Ethernet communication values correspond to the relay setting values.
10. Click **OK** when the relay order code has been received. The new device will be added to the Site List window (or Online window) located in the top left corner of the main EnerVista SR3 Setup window.

The 350 Site Device has now been configured for Ethernet communications. Proceed to the following section to begin communications.

### 3.2.3.4 Connecting to the relay

Now that the communications parameters have been properly configured, the user can easily communicate with the relay.

1. Expand the Site list by double clicking on the site name or clicking on the «+» box to list the available devices for the given site.
2. Desired device trees can be expanded by clicking the «+» box. The following list of headers is shown for each device:
  - Device Definition
  - Actual Values
  - Quick Setup
  - Setpoints
  - Maintenance.
3. Expand the SETTINGS > RELAY SETUP list item and double click on **Front Panel** to open the "Front Panel" settings window as shown below:



4. The "Front Panel" settings window will open with a corresponding status indicator on the lower left of the EnerVista SR3 Setup window.
5. If the status indicator is red, verify that the serial, USB, or Ethernet cable is properly connected to the relay, and that the relay has been properly configured for communications (steps described earlier).

The "Front Panel" settings can now be edited, printed, or changed. Other setpoint and command windows can be displayed and edited in a similar manner. "Actual Values" windows are also available for display. These windows can be arranged, and resized at will.

## 3.2.4 Working with setpoints and setpoint files

### 3.2.4.1 Engaging a device

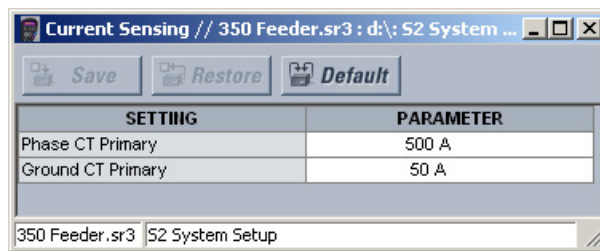
The EnerVista SR3 Setup software may be used in on-line mode (relay connected) to directly communicate with a relay. Communicating relays are organized and grouped by communication interfaces and into sites. Sites may contain any number of relays selected from the product series.

### 3.2.4.2 Entering setpoints

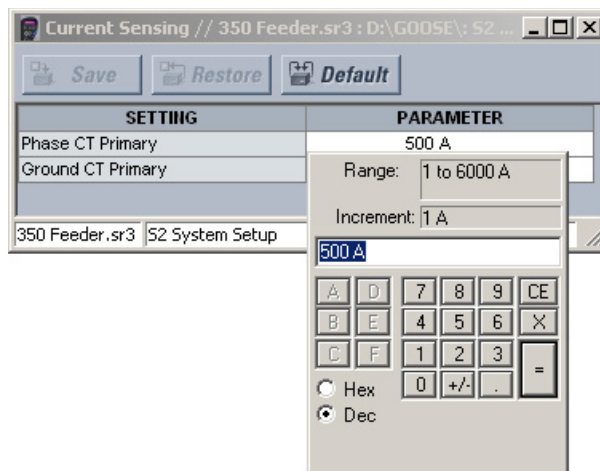
The System Setup page will be used as an example to illustrate the entering of setpoints. In this example, we will be changing the current sensing setpoints.

1. Establish communications with the relay.
2. Select the **Setpoint > System Setup > Current Sensing** menu item.

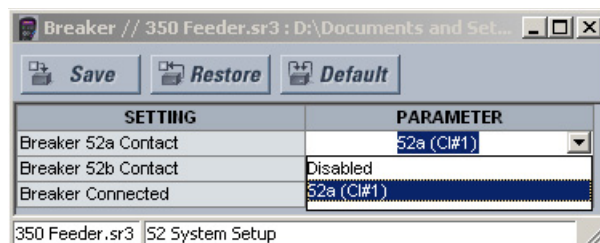
3. Select the **PHASE CT PRIMARY** setpoint by clicking anywhere in the parameter box. This will display three arrows: two to increment/decrement the value and another to launch the numerical keypad.



4. Clicking the arrow at the end of the box displays a numerical keypad interface that allows the user to enter a value within the setpoint range displayed near the top of the keypad: Click "=" to exit from the keypad and keep the new value. Click on "X" to exit from the keypad and retain the old value.



5. For setpoints requiring non-numerical pre-set values (e.g. **Breaker 52a contact** below), clicking anywhere within the setpoint value box displays a drop-down selection menu arrow. Select the desired value from this list.



6. For setpoints requiring an alphanumeric text string (e.g. "Relay Name"), the value may be entered directly within the setpoint value box.
7. In the **Setpoint > System Setup > Current Sensing** dialog box, click on **Save** to save the values into the 350. Click **Yes** to accept any changes. Click **Restore** to retain previous values. Click **Default** to restore Default values.

### 3.2.4.3 File support

Opening any EnerVista SR3 Setup file will automatically launch the application or provide focus to the already opened application. If the file is a settings file (has a 'SR3' extension) which had been removed from the Settings List tree menu, it will be added back to the Settings List tree.

New files will be automatically added to the tree.

### 3.2.4.4 Using setpoints files

The EnerVista SR3 Setup software interface supports three ways of handling changes to relay settings:

- In off-line mode (relay disconnected) to create or edit relay settings files for later download to communicating relays.
- Directly modifying relay settings while connected to a communicating relay, then saving the settings when complete.
- Creating/editing settings files while connected to a communicating relay, then saving them to the relay when complete.

Settings files are organized on the basis of file names assigned by the user. A settings file contains data pertaining to the following types of relay settings:

- Device Definition
- Relay Setup
- System Setup
- Protection
- Control
- Inputs/Outputs

Factory default values are supplied and can be restored after any changes.

The EnerVista SR3 Setup displays relay setpoints with the same hierarchy as the front panel display.

### 3.2.4.5 Downloading and saving setpoints files

Setpoints must be saved to a file on the local PC before performing any firmware upgrades. Saving setpoints is also highly recommended before making any setpoint changes or creating new setpoint files.

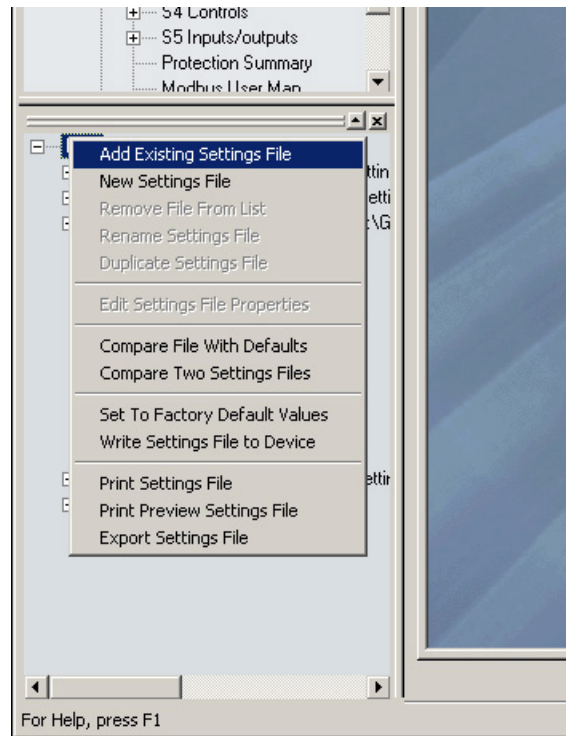
The setpoint files in the EnerVista SR3 Setup window are accessed in the Files Window. Use the following procedure to download and save setpoint files to a local PC.

1. Ensure that the site and corresponding device(s) have been properly defined and configured as shown in *Connecting EnerVista SR3 Setup to the Relay*, above.
2. Select the desired device from the site list.
3. Select the **Online > Read Device Settings** from Device menu item, or right-click on the device and select **Read Device Settings** to obtain settings information from the device.
4. After a few seconds of data retrieval, the software will request the name and destination path of the setpoint file. The corresponding file extension will be automatically assigned. Press **Receive** to complete the process. A new entry will be added to the tree, in the File pane, showing path and file name for the setpoint file.

### 3.2.4.6 Adding setpoints files to the environment

The EnerVista SR3 Setup software provides the capability to review and manage a large group of setpoint files. Use the following procedure to add an existing file to the list.

1. In the files pane, right-click on **Files** and select the **Add Existing Setting File** item as shown:



2. The Open dialog box will appear, prompting the user to select a previously saved setpoint file. As for any other MS Windows® application, browse for the file to be added then click **Open**. The new file and complete path will be added to the file list.

### 3.2.4.7 Creating a new setpoint file

The EnerVista SR3 Setup software allows the user to create new setpoint files independent of a connected device. These can be uploaded to a relay at a later date. The following procedure illustrates how to create new setpoint files.

1. In the File pane, right click on **File** and select the **New Settings File** item. The following box will appear, allowing for the configuration of the setpoint file for the correct firmware version. It is important to define the correct firmware version to ensure that setpoints not available in a particular version are not downloaded into the relay.

2. Select the Firmware Version, and Order Code options for the new setpoint file.
3. For future reference, enter some useful information in the **Description** box to facilitate the identification of the device and the purpose of the file.
4. To select a file name and path for the new file, click the button beside the File Name box.
5. Select the file name and path to store the file, or select any displayed file name to replace an existing file. All 350 setpoint files should have the extension 'SR3' (for example, 'feeder1.SR3').
6. Click **OK** to complete the process. Once this step is completed, the new file, with a complete path, will be added to the EnerVista SR3 Setup software environment.

### 3.2.4.8 Upgrading setpoint files to a new revision

It is often necessary to upgrade the revision for a previously saved setpoint file after the 350 firmware has been upgraded. This is illustrated in the following procedure:

1. Establish communications with the 350 relay.
2. Select the **Maintenance > M1 Relay Info** menu item and record the Firmware Revision.
3. Load the setpoint file to be upgraded into the EnerVista SR3 Setup environment as described in the section, *Adding Setpoints Files to the Environment*.
4. In the File pane, select the saved setpoint file.
5. From the main window menu bar, select the **Offline > Edit Settings File Properties** menu item and note the File Version of the setpoint file. If this version is different from the Firmware Revision noted in step 2, select a New File Version that matches the Firmware Revision from the pull-down menu.

- For example, if the firmware revision is LOL01MA120.000 (Firmware Revision 1.20) and the current setpoint file revision is 1.10, change the setpoint file revision to "1.2x".

**Edit Settings File**

STEP 1 2 3 4 5 6

File Name: 350 Feeder.sr3 : d:\

Description:

Old File Version: 110 New File Version: 1.1x

Old Serial # Lock: New Serial # Lock: 1.0x

Old Order Code: 350-EP1G1LSSNNSNDN New Order Code: 350-EP1G1LSSNNSNDN

Order Code: 350 E P1 G1 L S S N N S N D N

Ok Cancel

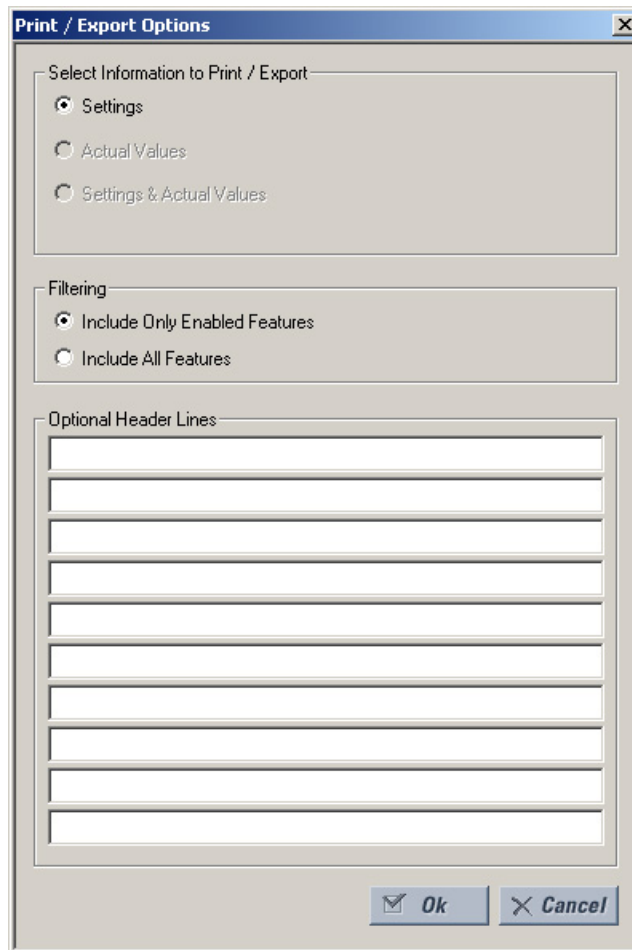
- Enter any special comments about the setpoint file in the "Description" field.
- Select the desired firmware version from the "New File Version" field.
- When complete, click **OK** to convert the setpoint file to the desired revision. See *Loading Setpoints from a File* below, for instructions on loading this setpoint file into the 350.

### 3.2.4.9 Printing setpoints and actual values

The EnerVista SR3 Setup software allows the user to print partial or complete lists of setpoints and actual values. Use the following procedure to print a list of setpoints:

- Select a previously saved setpoints file in the File pane or establish communications with a 350 device.
- From the main window, select the **Offline > Export Settings File** menu item.

- The Print/Export Options dialog box will appear. Select **Settings** in the upper section and select either **Include All Features** (for a complete list) or **Include Only Enabled Features** (for a list of only those features which are currently used) in the filtering section and click **OK**.



- The process for **Offline > Print Preview Settings File** is identical to the steps above.
- Setpoint lists can be printed in the same manner by right clicking on the desired file (in the file list) or device (in the device list) and selecting the **Print Device Information** or **Print Settings File** options.

#### 3.2.4.10 Printing actual values from a connected device

A complete list of actual values can also be printed from a connected device with the following procedure:

- Establish communications with the desired 350 device.
- From the main window, select the **Online > Print Device Information** menu item
- The Print/Export Options dialog box will appear. Select **Actual Values** in the upper section and select either **Include All Features** (for a complete list) or **Include Only Enabled Features** (for a list of only those features which are currently used) in the filtering section and click **OK**.

Actual values lists can be printed in the same manner by right clicking on the desired device (in the device list) and selecting the **Print Device Information** option

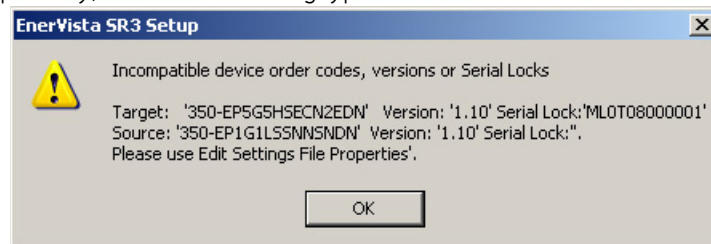
### 3.2.4.11 Loading setpoints from a file



An error message will occur when attempting to download a setpoint file with a revision number that does not match the relay firmware. If the firmware has been upgraded since saving the setpoint file, see *Upgrading Setpoint Files to a New Revision - section 3.2.4.8* - for instructions on changing the revision number of a setpoint file.

The following procedure illustrates how to load setpoints from a file. Before loading a setpoints file, it must first be added to the EnerVista SR3 Setup environment as described in the section, *Adding Setpoints Files to the Environment*.

1. Select the previously saved setpoints file from the File pane of the EnerVista SR3 Setup software main window.
2. Select the **Offline > Edit Settings File Properties** menu item and verify that the corresponding file is fully compatible with the hardware and firmware version of the target relay. If the versions are not identical, see *Upgrading Setpoint Files to a New Revision - section 3.2.4.6*, for details on changing the setpoints file version.
3. Right-click on the selected file and select the **Write Settings File to Device** item.
4. Select the target relay from the list of devices shown and click **Send**. If there is an incompatibility, an error of following type will occur:



If there are no incompatibilities between the target device and the settings file, the data will be transferred to the relay. An indication of the percentage completed will be shown in the bottom of the main window.

## 3.2.5 Upgrading relay firmware

To upgrade the 350 firmware, follow the procedures listed in this section. Upon successful completion of this procedure, the 350 will have new firmware installed with the factory default setpoints. The latest firmware files are available from the GE Multilin website at [http:// www.GEmultilin.com](http://www.GEmultilin.com).



NOTE

EnerVista SR3 Setup software prevents incompatible firmware from being loaded into a 350 relay.



NOTE

Before upgrading firmware, it is very important to save the current 350 settings to a file on your PC. After the firmware has been upgraded, it will be necessary to load this file back into the 350. Refer to *Downloading and Saving Setpoints Files* for details on saving relay setpoints to a file.

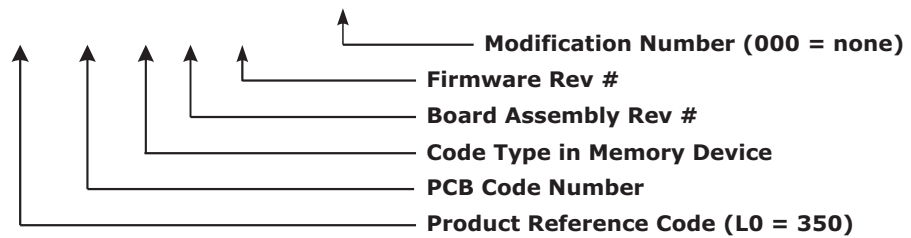
### 3.2.5.1 Loading new relay firmware

Loading new firmware into the 350 flash memory is accomplished as follows:

1. Connect the relay to the local PC and save the setpoints to a file as shown in *Downloading and Saving Setpoints Files on 3.2.4.5*.
2. Select the **Maintenance > Update Firmware** menu item.

- The EnerVista SR3 Setup software will request the new firmware file. Locate the folder that contains the firmware files to load into the 350. The firmware filename has the following format:

**L0 L01 M A 100 . 000**



- EnerVista SR3 Setup software now prepares the 350 to receive the new firmware file. The 350 front panel will momentarily display "SR BOOT PROGRAM Waiting for Message," indicating that it is in upload mode.
- While the file is being loaded into the 350, a status box appears showing how much of the new firmware file has been transferred and the upgrade status. The entire transfer process takes approximately 10 minutes.



- The EnerVista SR3 Setup software will notify the user when the 350 has finished loading the file. Carefully read any displayed messages and click **OK** to return the main screen. **Cycling power to the relay is recommended after a firmware upgrade.**

After successfully updating the 350 firmware, the relay will not be in service and will require setpoint programming. To communicate with the relay, the communication settings may have to be manually reprogrammed.

When communications is established, the saved setpoints must be reloaded back into the relay. See *Loading Setpoints from a File - section 3.2.4.11*, for details.

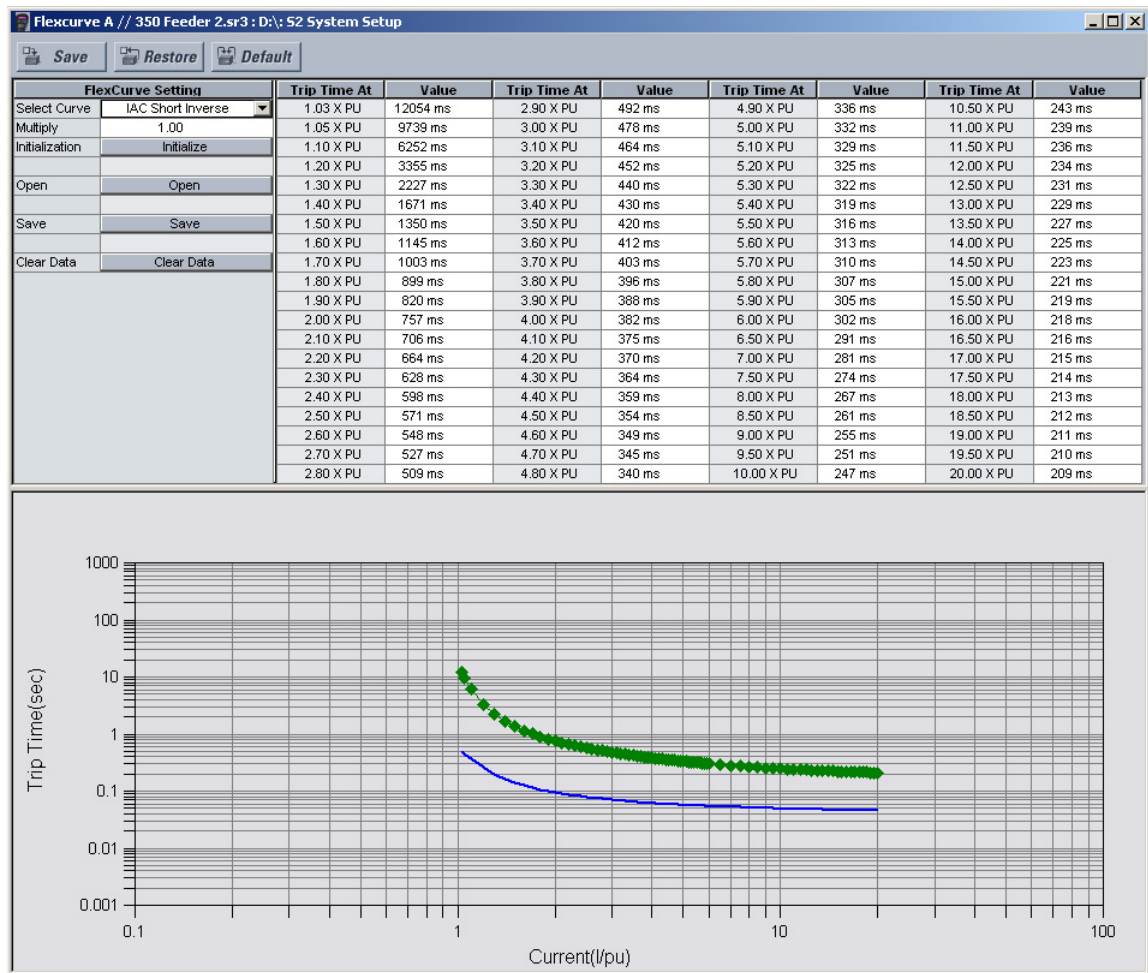
Modbus addresses assigned to firmware modules, features, settings, and corresponding data items (i.e. default values, min/max values, data type, and item size) may change slightly from version to version of firmware.

The addresses are rearranged when new features are added or existing features are enhanced or modified.

## 3.2.6 Advanced EnerVista SR3 Setup features

### 3.2.6.1 Flexcurve editor

The FlexCurve Editor is designed to allow the user to graphically view and edit the FlexCurve. The Flexcurve Editor screen is shown below:

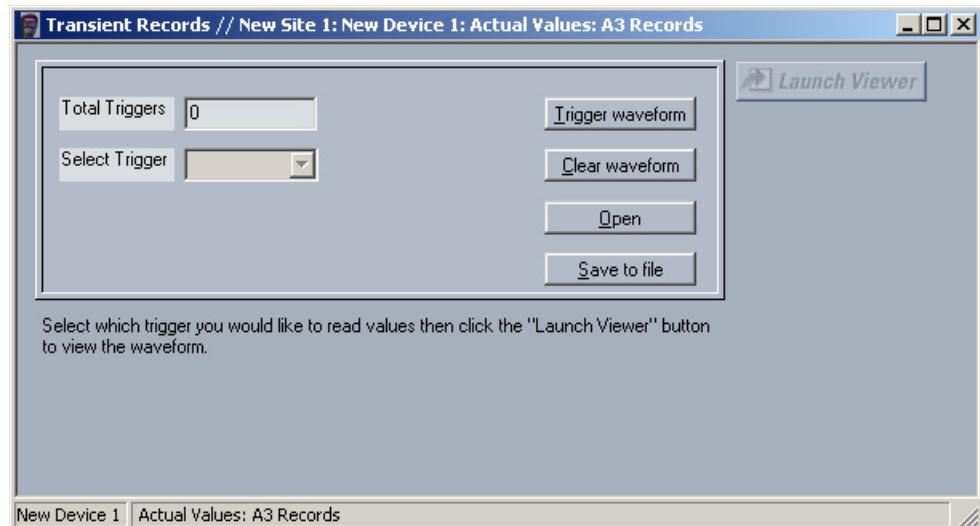


- The Operate Curves are displayed, which can be edited by dragging the tips of the curves
- A Base curve can be plotted for reference, to customize the operating curve. The Blue colored curve in the picture (in both curves) is a reference curve. It can be Extremely Inverse, Definite Time, etc.
- The Trip Times in the tables and curves work interactively i.e., changing the table value will affect the curve shape and vice versa.
- The user can save Configured Trip Times.
- The user can export Configured Trip Times to a CSV file
- The user can load Trip Times from a CSV File
- The screen above shows the model followed by 350 for viewing Flexcurves. Select **Initialize** to copy the trip times from the selected curve to the FlexCurve.

### 3.2.6.2 Transient recorder (Waveform capture)

The EnerVista SR3 Setup software can be used to capture waveforms (or view trace memory) from the relay at the instance of a pickup, trip, alarm, or other condition.

- With EnerVista SR3 Setup software running and communications established, select the **Actual Values > A3 Records > Transient Records** menu item to open the Transient Recorder Viewer window.



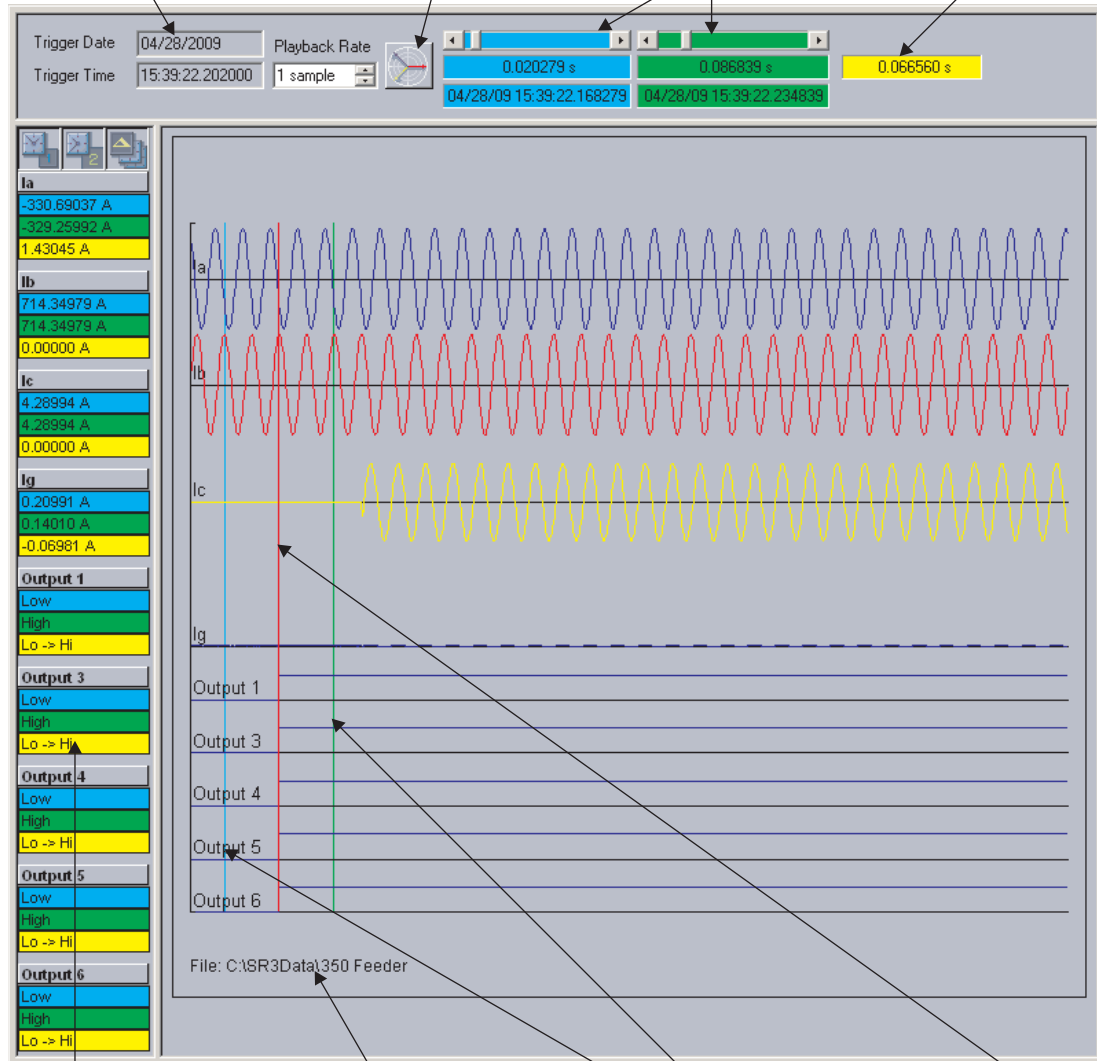
- Click on **Trigger Waveform** to trigger a waveform capture. Waveform file numbering starts with the number zero in the 350, so that the maximum trigger number will always be one less than the total number of triggers available.
- Click on the **Save to File** button to save the selected waveform to the local PC. A new window will appear, requesting the file name and path. One file is saved as a COMTRADE file, with the extension "CFG." The other file is a "DAT" file, required by the COMTRADE file for proper display of waveforms.
- To view a previously saved COMTRADE file, click the **Open** button and select the corresponding COMTRADE file.
- To view the captured waveforms, click on the **Launch Viewer** button. A detailed Waveform Capture window will appear as shown below.

**TRIGGER TIME & DATE**  
Displays the time and date of the Trigger.

**VECTOR DISPLAY SELECT**  
Click here to open a new graph to display vectors.

**CURSOR LINE POSITION**  
Indicates the cursor line position in time with respect to the beginning of the buffer.

**DELTA**  
Indicates time difference between the two cursor lines.



Display graph values at the corresponding cursor line. Cursor lines are identified by their colors.

**FILE NAME**  
Indicates the file name and complete path (if saved).

**CURSOR LINES**  
To move lines, locate the mouse pointer over the cursor line, then click and drag the cursor to the new position.

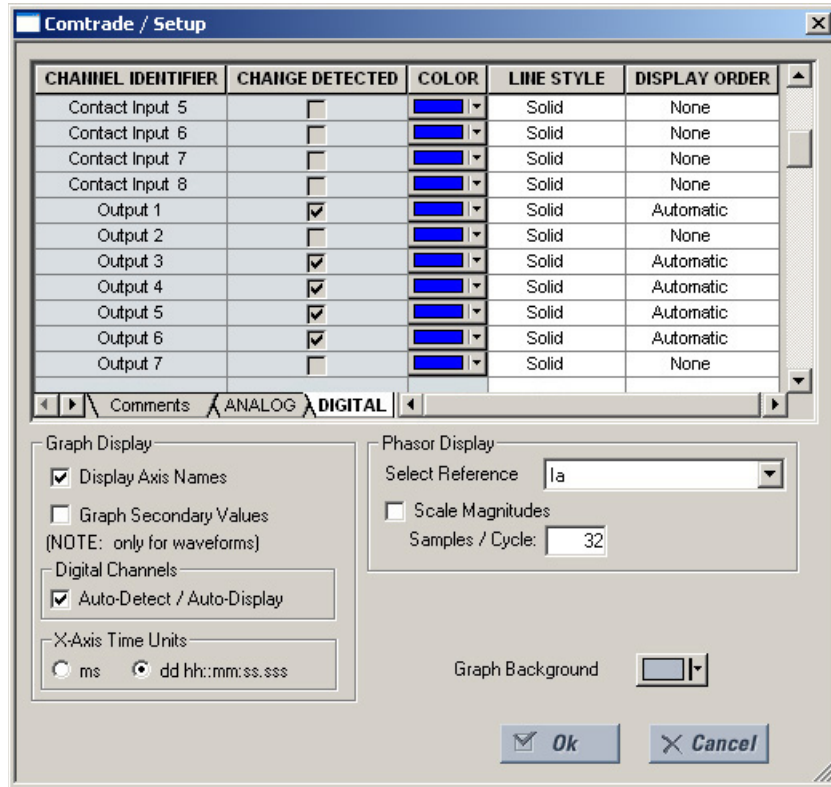
**TRIGGER LINE**  
Indicates the point in time for the trigger.

- The red vertical line indicates the trigger point.
- The date and time of the trigger are displayed at the top left corner of the window. To match the captured waveform with the event that triggered it, make note of the time and date shown in the graph, then find the event that matches the same time in the event recorder. The event record will provide additional information on the cause and system conditions at the time of the event.
- From the window main menu bar, press the **Preference** button to open the COMTRADE Setup page, in order to change the graph attributes.



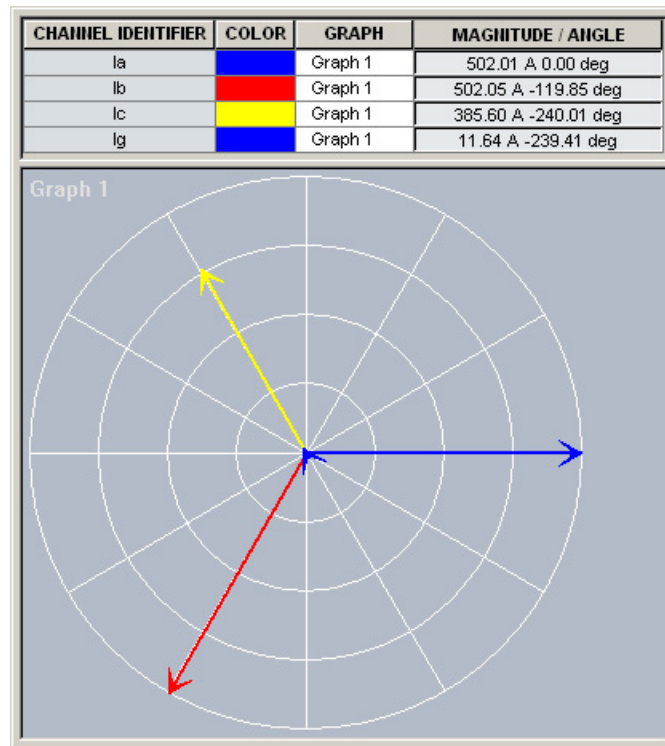
Preference Button

The following window will appear:



Change the color of each graph as desired, and select other options as required, by checking the appropriate boxes. Click **OK** to store these graph attributes, and to close the window. The Waveform Capture window will reappear based on the selected graph attributes.

To view a vector graph of the quantities contained in the waveform capture, press the **Vector Display** button to display the following window:



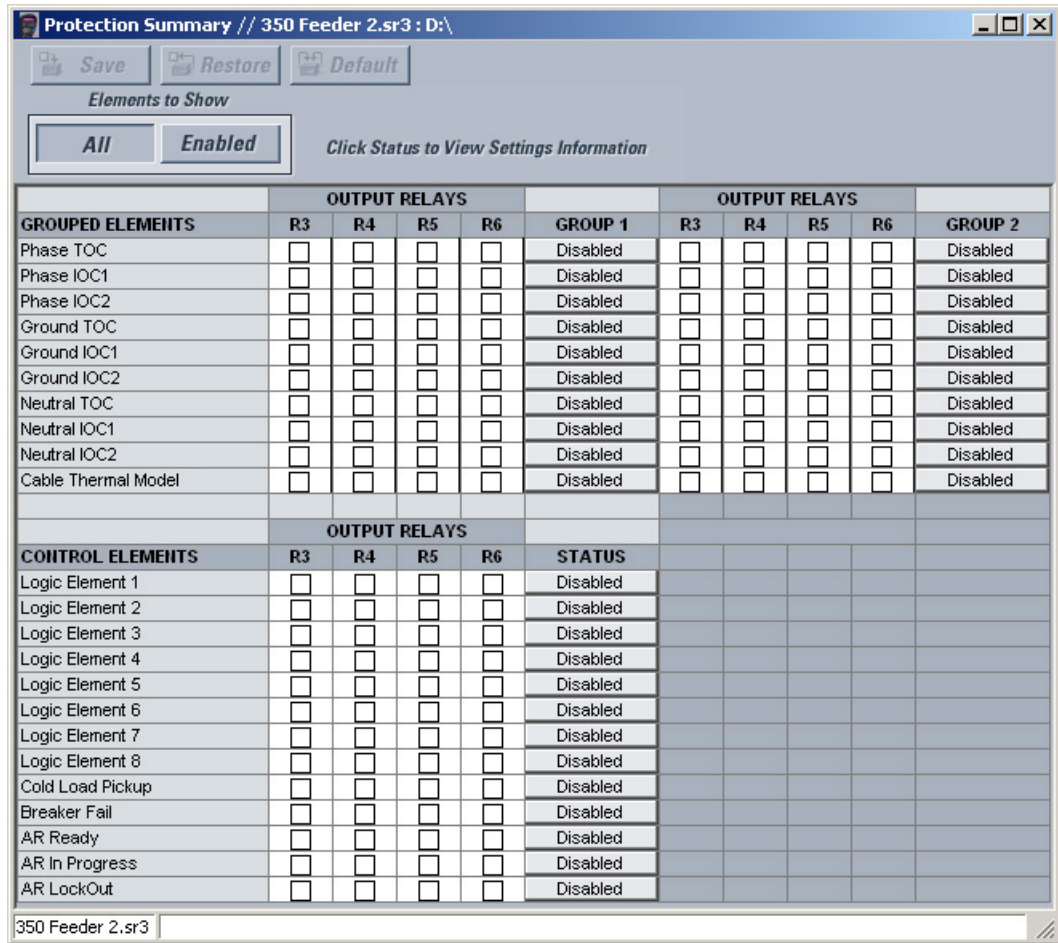
### 3.2.6.3 Protection summary

Protection Summary is a single screen which holds the summarized information of different settings from Grouped Elements, Control Elements and Maintenance screens.

Protection Summary Screen allows the User to:

- view the output relay assignments for the elements
- modify the output relay assignments for the elements
- view the enable/disable status of Control Elements
- navigate to the respected Protection Element screen on a button click.

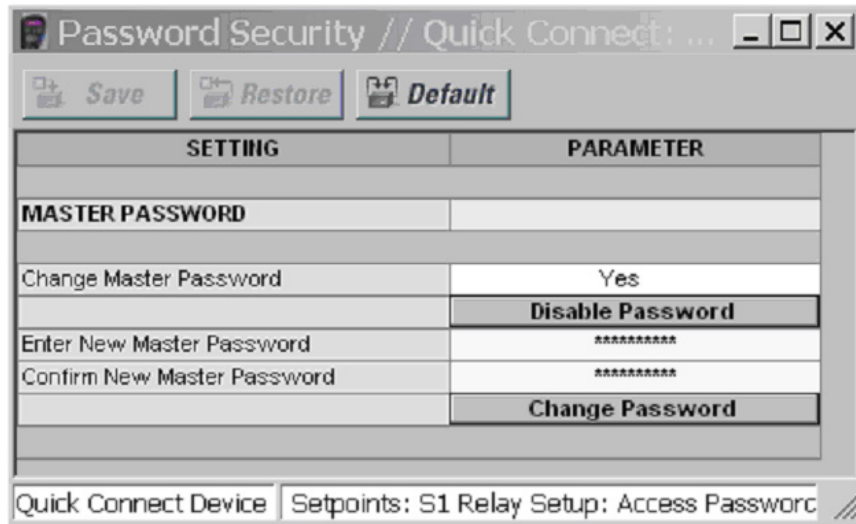
The Protection Summary screen is as follows:



### 3.2.6.4 Password security

Password security is an optional feature of the 350 which can be setup using the SR3 EnerVista Setup software. The password system has been designed to facilitate a hierarchy for centralized management. This is accomplished through a Master level access password which can be used for resetting lower level access passwords and higher level privileged operations. In cases where operational security is required as well as a central administrative authority then the use of the password system is highly encouraged. The feature robustness of this system requires it to be managed exclusively through the EnerVista setup software. This section describes how to perform the initial setup. For more details on the password security feature, refer to *section 6.2.2 - Password Security*.

1. 350 devices shipped from the factory are initially set with security disabled. If the password security feature is to be used, the user must first change the Master Reset Password from the initial Null setting, this can only be done over communications, not from the front panel keypad. The new Master Reset Password must be 8 to 10 characters in length, and must have minimum 2 letters and 2 numbers. The letters are case sensitive. After entering a valid Master Reset Password, enter the new Master Reset Password again to confirm, then select **Change Password**.



- Now that the Master Reset Password has been programmed, enter it again to log in to the Master Access level. The Master Level permits setup of the Remote and Local Passwords. If the Master Reset Password has been lost, record the Encrypted Key and contact the factory to have it decrypted.



- With Master Level access, the user may disable password security altogether, or change the Master Reset Password.
- The Master Access level allows programming of the Remote Setpoint and Remote Control passwords. These passwords are initially set to a Null value, and can only be set or changed from a remote user over RS485 or Ethernet communications. Remote Passwords must be 3 to 10 characters in length.

<b>REMOTE PASSWORDS</b>	
Change Remote Setting Password	Yes
Enter New Remote Setting Password	
Confirm New Remote Setting Password	
<b>Change Password</b>	
Change Remote Control Password	Yes
Enter New Remote Control Password	
Confirm New Remote Control Password	
<b>Change Password</b>	

- Initial setup of the Local Setpoint and Local Control passwords requires the Master Access level. If Overwrite Local Passwords is set to YES, Local passwords can be changed remotely only (over RS485 or Ethernet). If Overwrite Local Passwords is set to NO, Local passwords can be changed locally only (over USB or keypad). If changing Local Passwords is permitted locally, the keypad user can only change the Local Passwords if they have been changed from the initial NULL value to a valid one. Local Passwords must be 3 to 10 characters in length.

Overwrite Local Passwords	Yes
<b>LOCAL PASSWORDS</b>	
Overwrite Local Setting Password	Yes
Enter New Local Setting Password	
Confirm New Local Setting Password	
<b>Change Password</b>	
Overwrite Local Control Password	Yes
Enter New Local Control Password	
Confirm New Local Control Password	
<b>Change Password</b>	

Quick Connect Device | Setpoints: S1 Relay Setup: Access Passwords

- If any Remote password has never been set, that level will not be attainable except when logged in as the Master Level. The same logic applies to the Local passwords.
- When passwords have been set, the user will be prompted to enter the appropriate password depending on the interface being used (remote or local), and the nature of the change being made (setpoint or control). If the correct password is entered, the user is now logged into that access level over that interface only. The access level turns off after a period of 5 minutes of inactivity, if control power is cycled, or if the user enters an incorrect password.



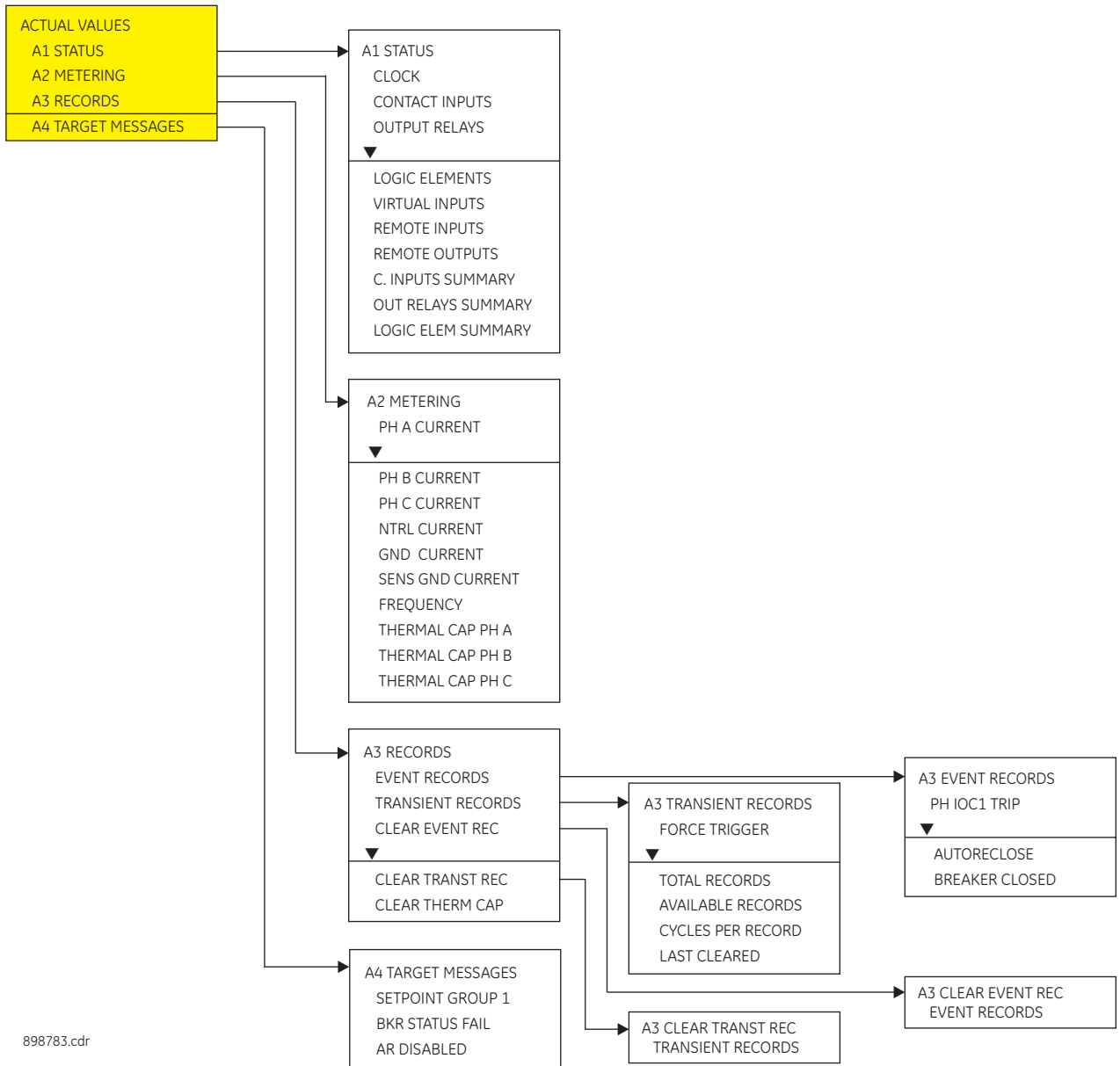
# 350 Feeder Protection System

## Chapter 4: Actual values

---

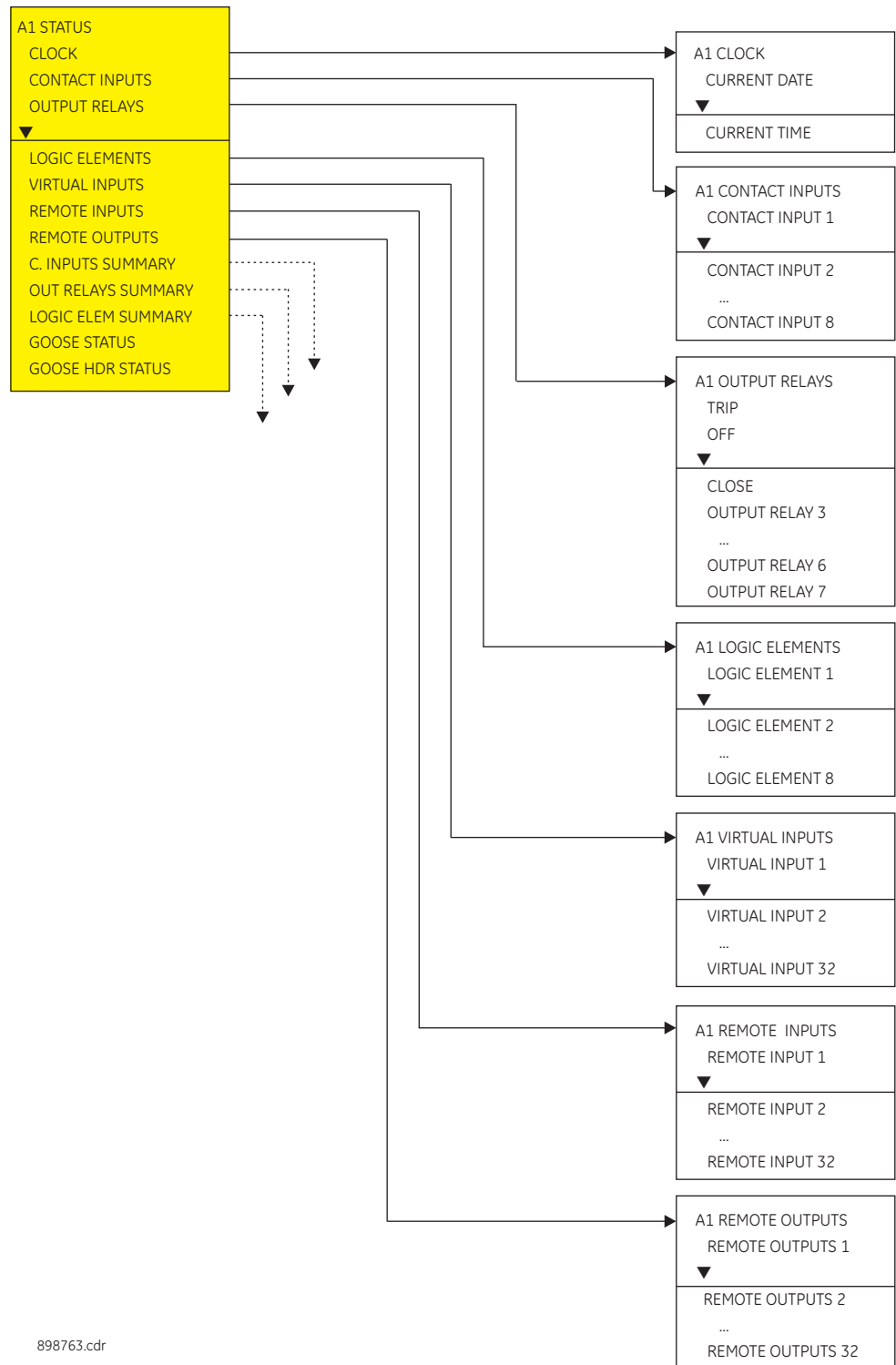
### 4.1 Actual values overview

Measured values, maintenance, and fault analysis information are accessed in actual values mode. Actual value messages are organized into logical groups for easy reference as shown below.



898783.cdr

## 4.2 A1 Status



898763.cdr

## 4.2.1 Clock

**PATH:** ACTUAL VALUES > A1 STATUS > CLOCK

**CURRENT DATE**

**Feb 12 2009**

*Range: Date in format shown*

Indicates today's date.

**CURRENT TIME**

**09:17:12**

*Range: Time in format shown*

Indicates the current time of day.

## 4.2.2 Contact inputs

**PATH:** ACTUAL VALUES > A1 STATUS > CONTACT INPUTS

**CI #1 (52a) (Contact Input 1)**

**OFF**

*Range: Off, On*

The status of this contact shows the breaker close/open state, when wired to a 52a breaker auxiliary contact.

**CI #2 (52b) (Contact Input 2)**

**OFF**

*Range: Off, On*

The status of this contact shows the breaker close/open state, when wired to a 52b breaker auxiliary contact.

**CONTACT INPUT 3 to 8**

**OFF**

*Range: Off, On*

Message displays the state of the contact input. The message "ON" indicates that the contact input is energized, and message "OFF" indicates a de-energized contact.

## 4.2.3 Output relays

**PATH:** ACTUAL VALUES > A1 STATUS > OUTPUT RELAYS

**TRIP (Output Relay #1)**

**OFF**

*Range: Off, On*

The "ON" state of Output Relay #1 (TRIP) shows that a TRIP command has been sent to the breaker.

**CLOSE (Output Relay #2)**

**OFF**

*Range: Off, On*

The "ON" state of Output Relay #2 (CLOSE) shows that a close command has been sent to the breaker.

**OUTPUT RELAY 3 to 6 (Auxiliary Output Relays)****OFF***Range: Off, On***OUTPUT RELAY 7 (Critical Failure Relay)***Range: Off, On*

The "ON" state indicates that the relay is in-service.

## 4.2.4 Logic elements

**PATH: [ACTUAL VALUES](#) > [A1 STATUS](#) > [LOGIC ELEMENTS](#)****LOGIC ELEMENT 1 to 8****OFF***Range: Off, On*

The state "ON" or "OFF" for each logic element depends on its programmed logic: triggering inputs, blocking inputs, plus any pickup, and/or reset time delay.

## 4.2.5 Virtual inputs

The state of all active virtual inputs is displayed here.

**PATH: [ACTUAL VALUES](#) > [A1 STATUS](#) > [VIRTUAL INPUTS](#)****VIRTUAL INPUTS 1 to 32****OFF***Range: Off, On*

## 4.2.6 Remote inputs

The state of all active remote inputs is displayed here.

**PATH: [ACTUAL VALUES](#) > [A1 STATUS](#) > [REMOTE INPUTS](#)****REMOTE INPUTS 1 to 32****OFF***Range: Off, On*

## 4.2.7 Remote outputs

The state of all active remote outputs is displayed here.

**PATH:** [ACTUAL VALUES](#) > [A1 STATUS](#) > [REMOTE OUTPUTS](#)

**REMOTE OUTPUTS 1 to 32**

**OFF**

*Range: Off, On*

## 4.2.8 Contact inputs summary

### C. INPUTS SUMMARY

52a	OFF	CI#5	OFF
52b	OFF	CI#6	OFF
CI#3	OFF	CI#7	OFF
CI#4	OFF	CI#8	OFF

The display shows a summary of the states of all contact inputs.

## 4.2.9 Output relays summary

**PATH:** [ACTUAL VALUES](#) > [A1 STATUS](#) > [OUT RELAYS SUMMARY](#)

### OUTPUT RELAYS SUMMARY

TRIP	OFF	RLY#5	OFF
CLOSE	OFF	RLY#6	OFF
RLY#3	OFF	RLY#7	ON
RLY#4	OFF		

This display shows a summary of the states of all output relays.



Output relay #7 is the Critical Failure relay, used to indicate the correct functioning of the 350 relay. This output relay shows the status "ON" when the 350 relay is powered up and set to "Ready" and no self-test alarms are active, under [SETPOINTS > S1 RELAY SETUP > S1 INSTALLATION > RELAY STATUS](#).

## 4.2.10 Logic elements summary

**PATH:** [ACTUAL VALUES](#) > [A1 STATUS](#) > [LOGIC ELEM SUMMARY](#)

### LOGIC ELEM SUMMARY

LE#1	OFF	LE#5	OFF
LE#2	OFF	LE#6	OFF
LE#3	OFF	LE#7	OFF
LE#4	OFF	LE#8	OFF

This display shows a summary of the states of all logic elements.

### 4.2.11 GOOSE status

**PATH:** ACTUAL VALUES > A1 STATUS > GOOSE STATUS

**GOOSE 1 TO 8 STATUS**

*Range: OFF, ON*

*Default: OFF*

### 4.2.12 GOOSE HDR status

**PATH:** ACTUAL VALUES > A1 STATUS > GOOSE HDR STATUS

**GOOSE 1 TO 8 H.STATUS**

*Range: OFF, ON*

*Default: OFF*

## 4.3 A2 Metering

The relay measures all RMS currents and frequency. All quantities are recalculated every power system cycle and perform protection and monitoring functions. Displayed metered quantities are updated approximately three (3) times a second for readability. All phasors and symmetrical components are referenced to the phase A current phasor.

By scrolling the Up/Down keys the relay shows one-by-one, all metered values as follows:

**PH A CURRENT**

**0.0 A 0° lag**

*Range: 1 to 6000 A, 0 to 359° lag*

**PH B CURRENT**

**0.0 A 0° lag**

*Range: 1 to 6000 A, 0 to 359° lag*

**PH C CURRENT**

**0.0 A 0° lag**

*Range: 1 to 6000 A, 0 to 359° lag*

**NTRL CURRENT**

**0.0 A 0° lag**

*Range: 1 to 6000 A, 0 to 359° lag*

**GND CURRENT**

**0.0 A 0° lag**

*Range: 1 to 6000 A, 0 to 359° lag*

**SENS GND CURRENT**

**0.0 A 0° lag**

*Range: 1 to 600 A, 0 to 359° lag*

**FREQUENCY**

**0.00 Hz**

*Range: 40 to 70 Hz*

**THERM CAP PH A**

**0.0%**

*Range: 1 to 150%*

**THERM CAP PH B**

**0.0%**

*Range: 1 to 150%*

**THERM CAP PH C**

**0.0%**

*Range: 1 to 150%*

## 4.4 A3 Records

The 350 has an event recorder which runs continuously. All event records are stored in memory such that information is maintained for up to 3 days even after losing relay control power. The events are displayed from newest to oldest event. Each event has a header message containing a summary of the event that occurred, and is assigned an event number equal to the number of events that have occurred since the recorder was cleared. The event number is incremented for each new event.

### 4.4.1 Event records

The Event Recorder runs continuously, capturing and storing the last 256 events. All events are stored in non-volatile memory, where the information is maintained, even in the case where relay control power is lost.

**PATH:** ACTUAL VALUES > A3 RECORDS > EVENT RECORDS

**Table 1: Example of Event Record**

A3 EVENT REC T:778 E778 Jan 30,2009 BKR Stat Open 16:30:23.324	▶	E778, CONTROL BKR Stat Open PHASE A CURRENT 0.0 A 0° Lag
		▼
		E778, CONTROL BKR Stat Open PHASE B CURRENT 0.0 A 0° Lag
		▼
		E778, CONTROL BKR Stat Open PHASE C CURRENT 0.0 A 0° Lag
		▼
		E778, CONTROL BKR Stat Open  GROUND CURRENT 0.0 A 0° Lag
		▼
		E778, CONTROL BKR Stat Open NTRL GND CURRENT 0.0 A
		▼
		E778, CONTROL BKR Stat Open THERM CAP PH A 0.0%
		▼
		E778, CONTROL BKR Stat Open THERM CAP PH B 0.0%
		▼
		E778, CONTROL BKR Stat Open THERM CAP PH C 0.0%

Each event is saved with event number, date and time, and contains information such as per phase current, ground current, and system frequency. The Event Recorder can be cleared from **ACTUAL VALUES > A3 RECORDS > CLEAR EVENT REC.** The following tables provide lists of the event types and event causes:

**Table 2: Event type**

Event Type	Display	Description
General Events	None	Events that occur when specific operation takes place
Pickup Events	PICKUP:	These are events that occur when a protection element picks up
Trip Events	TRIP:	These are events that occur when a breaker trip is initiated
Alarm and Latched Alarm Events	ALARM:	These are events that occur when an alarm is initiated
Control Events	CONTROL:	These are events that occur when a control element is activated
Dropout Events	DROPOUT:	These are events that occur when a protection element drops out after a corresponding pickup event
Contact Input Events	C. INPUT:	These are events that occur when a contact input changes its state
Virtual Input Events	V. INPUT	These are events that occur when a virtual input changes its state
Remote Input Events	R. INPUT	These are events that occur when a remote input changes its state
Logic Element Events	L. ELEMENT	These are events that occur when a logic element changes its state
Self-Test Warning Events	SELF-TEST WARNING	These are events that occur when a self-test warning is detected.

**Table 3: Event causes**

Displayed Event	Description	Displayed Event	Description
GENERAL EVENT CAUSES			
AR Close 1 to 4	The AR initiate closing	Open Breaker	Open breaker command
AR Lockout	The AR is in Lockout mode	Clear Event Record	Event record is cleared
AR In-Progress	The AR is in progress	Reset Trip Counter	The trip counter is reset
AR Reset	The AR resets	Reset	General reset
Breaker Closed	Breaker status "closed"	Date or Time Set	The Date or Time is set
Breaker Open	Breaker status "open"	Clear Transt Rec	Transient Recorder is cleared
BKR Not Connected	Breaker not connected	Clear Therm Cap	Thermal Capacity is cleared
Close Breaker	Close breaker command		
Quick Setup	The time and date when Quick Setup was used		
PICKUP, TRIP, DROPOUT, ALARM, LATCHED ALARM, AND CONTROL EVENT CAUSES			
Breaker Failure	The breaker failed to open	Phase IOC2 B DPO	Instantaneous OC2 Phase B dropped out

Displayed Event	Description	Displayed Event	Description
Breaker Operation	Breaker operated	Phase IOC2 C DPO	Instantaneous OC2 Phase C dropped out
Close Coil Alarm	The Close coil monitor detected open circuit	Phase IOC2 A OP	Instantaneous OC2 Phase A operated
Trip Coil Alarm	The Open coil monitor detected open circuit	Phase IOC2 B OP	Instantaneous OC2 Phase B operated
CLP ready	CLP set ready after outage timer	Phase IOC2 C OP	Instantaneous OC2 Phase C operated
Cold Load PKP Blk	CLP blocking initiated	Ground TOC PKP	Ground Timed OC picked up
Phase TOC A PKP	Timed OC Phase A picked up	Ground TOC DPO	Ground Timed OC dropped out
Phase TOC B PKP	Timed OC Phase B picked up	Ground TOC OP	Ground Timed OC operated
Phase TOC C PKP	Timed OC Phase C picked up	Sens Gnd TOC PKP	Sensitive Ground Timed OC picked up
Phase TOC A DPO	Timed OC Phase A dropped out	Sens Gnd TOC DPO	Sensitive Ground Timed OC dropped out
		Sens Gnd TOC OP	Sensitive Ground Timed OC operated
		Ground IOC1 PKP	Ground Instantaneous OC1 picked up
Phase TOC B DPO	Timed OC Phase B dropped out	Ground IOC1 DPO	Ground Instantaneous OC1 dropped out
Phase TOC C DPO	Timed OC Phase C dropped out	Ground IOC1 OP	Ground Instantaneous OC1 operated
Phase TOC A OP	Timed OC Phase A operated	Ground IOC2 PKP	Ground Instantaneous OC2 picked up
Phase TOC B OP	Timed OC Phase B operated	Ground IOC2 DPO	Ground Instantaneous OC2 dropped out
Phase TOC C OP	Timed OC Phase C operated	Ground IOC2 OP	Ground Instantaneous OC2 operated
Phase IOC1 A PKP	Instantaneous OC1 Phase A picked up	Sens Gnd IOC1 PKP	Sensitive Ground Instantaneous OC 1 picked up
Phase IOC1 B PKP	Instantaneous OC1 Phase B picked up	Sens Gnd IOC1 DPO	Sensitive Ground Instantaneous OC1 dropped out
Phase IOC1 C PKP	Instantaneous OC1 Phase C picked up	Sens Gnd IOC1 OP	Sensitive Ground Instantaneous OC1 operated
Phase IOC1 A DPO	Instantaneous OC1 Phase A dropped out	Sens Gnd IOC2 PKP	Sensitive Ground Instantaneous OC 2 picked up
Phase IOC1 B DPO	Instantaneous OC1 Phase B dropped out	Sens Gnd IOC2 DPO	Sensitive Ground Instantaneous OC2 dropped out
Phase IOC1 C DPO	Instantaneous OC1 Phase C dropped out	Sens Gnd IOC2 OP	Sensitive Ground Instantaneous OC2 operated

Displayed Event	Description		Displayed Event	Description
Phase IOC1 A OP	Instantaneous OC1 Phase A operated		Neutral IOC1 PKP	Neutral Instantaneous OC1 picked up
Phase IOC1 B OP	Instantaneous OC1 Phase B operated		Neutral IOC1 DPO	Neutral Instantaneous OC1 dropped out
Phase IOC1 C OP	Instantaneous OC1 Phase C operated		Neutral IOC1 OP	Neutral Instantaneous OC1 operated
Phase IOC2 A PKP	Instantaneous OC2 Phase A picked up		Neutral IOC2 PKP	Neutral Instantaneous OC2 picked up
Phase IOC2 B PKP	Instantaneous OC2 Phase B picked up		Neutral IOC2 DPO	Neutral Instantaneous OC2 dropped out
Phase IOC2 C PKP	Instantaneous OC2 Phase C picked up		Neutral IOC2 OP	Neutral Instantaneous OC2 operated
Phase IOC2 A DPO	Instantaneous OC2 Phase A dropped out			
LOGIC EVENTS				
52a c. input ON	52a contact input energized		Block Phase TOC	Phase Timed OC blocked
52b c. input ON	52b contact input energized		Block Gnd TOC	Ground Timed OC blocked
52a c. input OFF	52a contact input de-energized		Block Sens Gnd TOC	Sensitive Ground Timed OC blocked
52b c. input OFF	52b contact input de-energized		Block Ntrl TOC	Neutral Timed OC blocked
Cont. Input 3 to 8 ON	Contact Input 3 to 8 energized		Block Phase IOC1	Phase Instantaneous OC1 blocked
Cont. Input 3 to 8 OFF	Contact Input 3 to 8 de-energized		Block Phase IOC2	Phase Instantaneous OC2 blocked
Virtual Input 1 to 32 ON	Virtual Input 1 to 32 detected "ON"		Block Gnd IOC1	Ground Instantaneous OC1 blocked
Virtual Input 1 to 32 OFF	Virtual Input 1 to 32 detected "OFF"		Block Gnd IOC2	Ground Instantaneous OC2 blocked
Remote Input 1 to 32 ON	Remote Input 1 to 32 detected "ON"		Block Ntrl IOC1	Neutral Instantaneous OC1 blocked
Remote Input 1 to 32 OFF	Remote Input 1 to 32 detected "OFF"		Block Ntrl IOC2	Neutral Instantaneous OC2 blocked
Logic Element 1 to 8 ON	Logic Element 1 to 8 detected "ON"		Block Reclosure	Autoreclosure blocked
Logic Element 1 to 8 OFF	Logic Element 1 to 8 detected "OFF"			

Displayed Event	Description	Displayed Event	Description
Block 1 Trip	Trip command to the output relay 1 "TRIP" blocked	Breaker Connected	Detects breaker connected when the programmed breaker connected input energized
Block 2 Close	Close command to the output relay 2 "CLOSE" blocked	AR initiate	AR initiate input energized
		Setpoint Group 2	Switched to setpoint group 2
		Setpoint Group 1	Switched to setpoint group 1 from setpoint group 2

### 4.4.2 Transient records

PATH: [ACTUAL VALUES](#) > [A3 RECORDS](#) > [TRANSIENT RECORDS](#)

**FORCE TRIGGER?**

**No**

*Range: No, Yes*

**TOTAL RECORDS**

**1**

*Range: N/A*

**AVAILABLE RECORDS**

**1**

*Range: N/A*

**LAST CLEARED**

**Feb 08 2009**

*Range: N/A*

### 4.4.3 Clear event record

PATH: [ACTUAL VALUES](#) > [A3 RECORDS](#) > [CLEAR EVENT REC](#)

**CLEAR**

**No**

*Range: No, Yes*

When set to "Yes," pressing the ENTER key will clear all event records.

### 4.4.4 Clear transient record

PATH: [ACTUAL VALUES](#) > [A3 RECORDS](#) > [CLEAR TRANST REC](#)

**CLEAR**

**No**

*Range: No, Yes*

When set to "Yes," pressing the ENTER key will clear all transient records.

## 4.4.5 Clear thermal capacity record

**PATH:** ACTUAL VALUES > A3 RECORDS > CLEAR THERM CAP

**CLEAR**

**No**

*Range: No, Yes*

When set to "Yes," pressing the ENTER key will clear all thermal capacity records.

## 4.5 A4 Target messages

Target messages are automatically displayed for any active condition on the relay such as pickups, trips, or alarms. The target messages shown below are displayed.

The relay displays the most recent event first, and after 5 seconds starts rolling up the other target messages, until the Reset command is initiated. If the Reset command is not performed but the Menu pushbutton is pressed, the display will not show the target messages, unless the user navigates to [ACTUAL VALUES > A4 TARGET MESSAGES](#), where they can be reviewed.

The target messages can be reviewed by pressing **Up** and **Down** message pushbuttons from the relay keypad.

The following messages will appear on the relay display as long as their respective flags are active. The messages will disappear from the display, when the protection element drops out before operation, such as when the condition clears before reaching operation, or when the protection element operates.

Phase IOC1 PKP	Phase TOC PKP	Neutral IOC1 PKP
Phase A IOC1 PKP	Phase A TOC PKP	Neutral IOC2 PKP
Phase B IOC1 PKP	Phase B TOC PKP	
Phase C IOC1 PKP	Phase C TOC PKP	
Phase IOC2 PKP	Ground TOC PKP	
Phase A IOC2 PKP	Sens Gnd TOC PKP	
Phase B IOC2 PKP	Neutral TOC PKP	
Phase C IOC2 PKP		
Ground IOC1 PKP	Thermal Alarm	
Ground IOC2 PKP	Ph A Thermal Alarm	
Sens Gnd IOC1 PKP	Ph B Thermal Alarm	
Sens Gnd IOC2 PKP	Ph C Thermal Alarm	
	Logic Element 1 PKP	
Trip Coil Monitor PKP	Logic Element 2 PKP	
Close Coil Monitor PKP	Logic Element 3 PKP	
Trip Counter PKP	Logic Element 4 PKP	
	Logic Element 5 PKP	
	Logic Element 6 PKP	
	Logic Element 7 PKP	
	Logic Element 8 PKP	

The following message will appear on the relay display, when the respective element operates, with the element function set to "TRIP", or "LATCHED ALARM". The message will stay on the display after the condition clears, and will disappear upon Reset command.

If the element function is selected to "ALARM", or "CONTROL", the message will disappear from the display, when the condition causing operation clears.

Phase IOC1 OP	Phase TOC OP	Neutral IOC1 OP
Phase A IOC1 OP	Phase A TOC OP	Neutral IOC2 OP
Phase B IOC1 OP	Phase B TOC OP	
Phase C IOC1 OP	Phase C TOC OP	
Phase IOC2 OP	Ground TOC OP	
Phase A IOC2 OP	Sens Gnd TOC OP	
Phase B IOC2 OP	Neutral TOC OP	
Phase C IOC2 OP		
Ground IOC1 OP	Thermal OP	
Ground IOC2 OP	Ph A Thermal OP	
Sens Gnd IOC1 OP	Ph B Thermal OP	
Sens Gnd IOC2 OP	Ph C Thermal OP	
Cold Load PKP BLK	Logic Element 1 OP	
BKR Failure OP	Logic Element 2 OP	
	Logic Element 3 OP	
Trip Coil Monitor OP	Logic Element 4 OP	
Close Coil Monitor OP	Logic Element 5 OP	
Trip Counter OP	Logic Element 6 OP	
	Logic Element 7 OP	
	Logic Element 8 OP	
BKR Status Unknown		
BKR Status Fail		

The following messages will appear on the display and stay for 5 seconds only, unless the reset command is initiated, or the element changes its state. For example, if the breaker is detected "Open", the message "Breaker Open OK" will appear on the display and will stay for 5 seconds, unless the breaker status changes to "Close". If the breaker status changes to "Close" within 5 seconds after the breaker has been detected open, the message "Breaker Open OK" will disappear, and the message "Breaker Close OK" will appear and stay for 5 seconds.

Breaker Open		
Breaker Close		

The following messages will not appear as target messages, upon change of state. The state change however will be logged in the Event recorder

Contact Input 1 ON		
.		
.	Remote Input 1 ON	
Contact Input 8 ON	.	
Virtual Input 1 ON	.	
.	Remote Input 32 ON	
.		
Virtual Input 32 ON		
	Setpoint Group 1	
Contact Input 1 OFF	Setpoint Group 2	
.		
.	Remote Input 1 OFF	
Contact Input 8 OFF	.	
Virtual Input 1 OFF	.	
.	Remote Input 32 OFF	
.		
Virtual Input 32 OFF		

#### Autoreclose target messages

AR Ready	Appears on the display when the AR is Ready, i.e. breaker closed, AR function enabled, and no AR initiation.	The message appears on the display for 5 seconds, when the AR is detected Ready.
AR IN-PROGRESS	Appears on the display when the AR is in progress	Self-Reset message
AR LOCKOUT	Appears on the display when the AR is in lockout mode	Latched message. The message disappears upon Reset command

Examples of how the messages appear on the display:

#### Example 1:

Phase IOC1 Settings:

- PH IOC1 FUNCTION = Trip
- PH IOC1 PICKUP = 1.00 x CT
- PH IOC1 DELAY = 0.20 s

When current greater than the IOC1 pickup level is applied, the 350 display shows the following target message:

**A4 TARGET MESSAGES**  
**Ph IOC1 Trip**  
**STATE: PKP**

After the 200 ms time delay expires, the display shows the following message only:

**A4 TARGET MESSAGES**  
**Ph IOC1 Trip**  
**STATE: OP**

#### Example 2:

Phase IOC1 Settings:

- PH IOC1 FUNCTION = Latched Alarm
- PH IOC1 PICKUP = 1.00 x CT

- PH IOC1 DELAY = 0.20 s

When current greater than the IOC1 pickup level is applied, the 350 display shows the following target message:

**A4 TARGET MESSAGES**  
**Ph IOC1 Alarm**  
**STATE: PKP**

After the 200 ms time delay expires, the display shows the following message only:

**A4 TARGET MESSAGES**  
**Ph IOC1 Alarm**  
**STATE: OP**

**Example 3:**

Phase IOC1 Settings:

- PH IOC1 FUNCTION = Alarm
- PH IOC1 PICKUP = 1.00 x CT
- PH IOC1 DELAY = 0.20 s

When current greater than the IOC1 pickup level is applied, the 350 display shows the following target message:

**A4 TARGET MESSAGES**  
**Ph IOC1 Alarm**  
**STATE: PKP**

After the 200 ms time delay expires, the display shows the following message only:

**A4 TARGET MESSAGES**  
**Ph IOC1 Alarm**  
**STATE: OP**



## 350 Feeder Protection System

### Chapter 5: Quick setup - Front control panel

The "Quick Setup" utility is part of the 350 relay main menu, and can be used for quick and easy programming. Power system parameters, and settings for some simple over-current elements can be easily set. Use the "Quick Setup" utility to program the following:

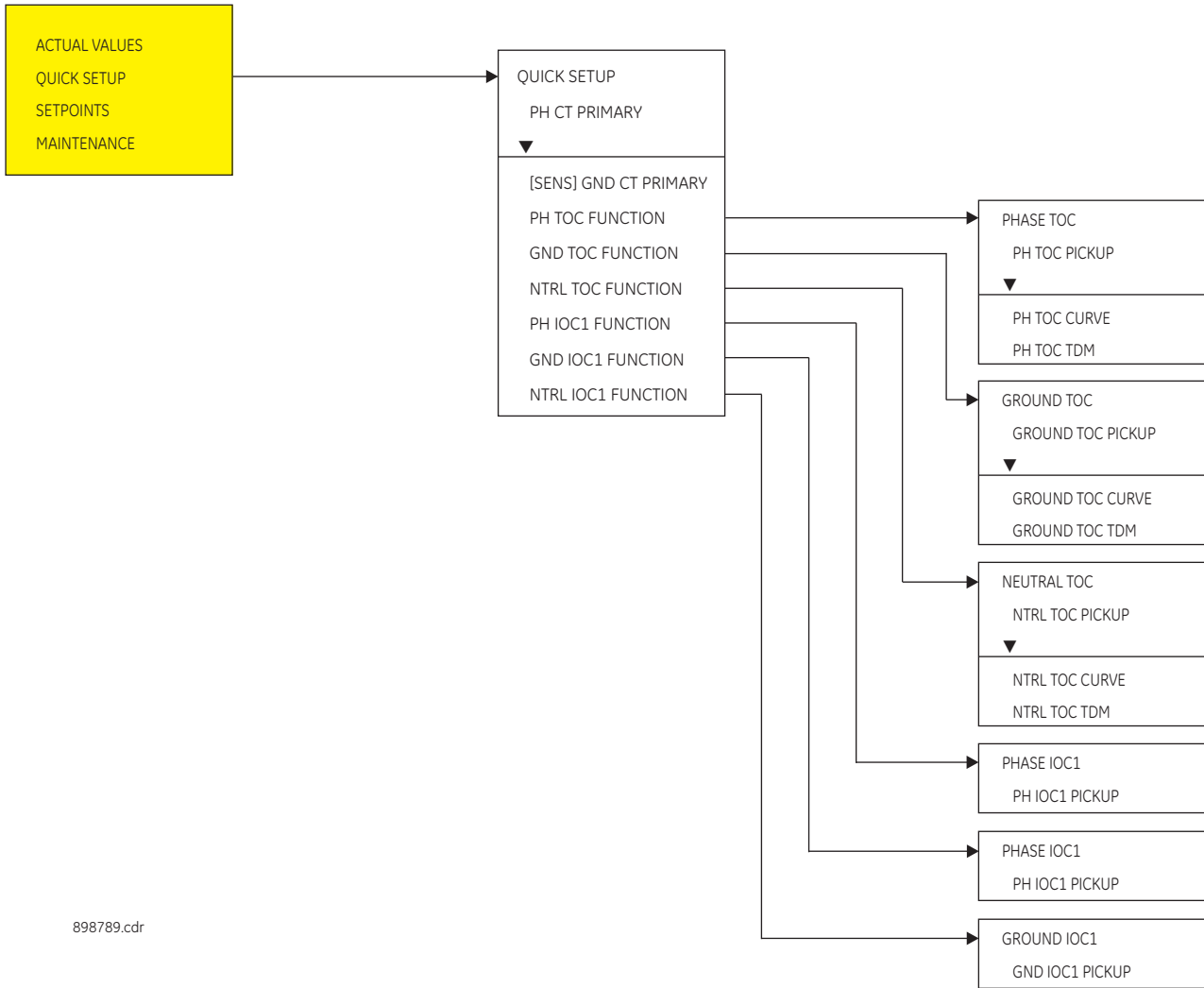
Power System data:

- Phase CT Primary
- Ground CT Primary
- Phase TOC
- Ground TOC
- Neutral TOC
- Phase IOC
- Ground IOC
- Neutral IOC



NOTE

Ensure the relay is in "Relay Ready" state before using Quick Setup.



898789.cdr

## 5.1 Quick Setup settings

This section provides an overview of the interfacing methods available with the 350 using the front control panel. For additional details on interface parameters (for example, settings, actual values, etc.), refer to the individual chapters.

**PATH: QUICK SETUP >**

### **PH CT PRIMARY**

*Range: 1 A to 6000 A in steps of 1  
Default: 500 A*

### **GND CT PRIMARY**

*Range: 1 A to 6000 A in steps of 1  
Default: 50 A*

### **PH TOC FUNCTION**

*Range: Trip, Disabled, Latched Alarm, Alarm  
Default: Trip*  
↳

### **PH TOC PICKUP**

*Range: 0.04 to 20.00 x CT  
Default: 1.00 x CT*

### **PH TOC CURVE**

*Range: ANSI Extremely/Very/Moderately/Normally Inverse, Definite Time, IEC Curve A/B/C and Short, IAC Extreme/Very/Inverse/Short, User Curve, FlexCurve™ A/B (programmable curves)  
Default: Extremely Inverse*

### **PH TOC TDM**

*Range: 0.50 to 20.00  
Default: 1.00*

### **GND TOC FUNCTION**

*Range: Disabled, Trip, Latched Alarm, Alarm  
Default: Disabled*  
↳

### **GND TOC PICKUP**

*Range: 0.04 to 20 x CT  
Default: 1.00 x CT*

### **GND TOC CURVE**

*Range: ANSI Extremely/Very/Moderately/Normally Inverse; Definite Time; IEC Curve A/B/C /Short Inverse; IAC Extreme/Very/Inverse/Short Inverse; User Curve, FlexCurve™ A/B (programmable curves)  
Default: Extremely Inverse*

### **GND TOC TDM**

*Range: 0.50 to 20.00  
Default: 1.00*

### **SENS GND TOC FUNCTION [WHEN SPECIFICALLY ORDERED]**

*Range: Disabled, Trip, Latched Alarm, Alarm  
Default: Disabled*  
↳

**SENS GND TOC PICKUP***Range: 0.005 to 3.000 x CT**Default: 1.000 x CT***SENS GND TOC CURVE***Range: ANSI Extremely/Very/Moderately/Normally Inverse; Definite Time; IEC Curve A/B/C /Short Inverse; IAC Extreme/Very/Inverse/Short Inverse; User Curve, FlexCurve™ A/B (programmable curves)**Default: Extremely Inverse***SENS GND TOC TDM***Range: 0.50 to 20.00**Default: 1.0***NTRL TOC FUNCTION***Range: Disabled, Trip, Latched Alarm, Alarm**Default: Disabled*

↳

**NTRL TOC PICKUP***Range: 0.04 to 20.00 x CT**Default: 1.00 x CT***NTRL TOC CURVE***Range: ANSI Extremely/Very/Moderately/Normally Inverse, Definite Time, IEC Curve A/B/C and Short, IAC Extreme/Very/Inverse/Short, User Curve, FlexCurve™ A/B (programmable curves)**Default: Extremely Inverse***NTRL TOC TDM***Range: 0.50 to 20.00**Default: 1.00***PH IOC1 FUNCTION***Range: Disabled, Trip, Latched Alarm, Alarm**Default: Disabled*

↳

**PH IOC1 PICKUP***Range: 0.05 to 20.00 x CT**Default: 1.00 x CT***GND IOC1 FUNCTION***Range: Disabled, Trip, Latched Alarm, Alarm**Default: Disabled*

↳

**GND IOC1 PICKUP***Range: 0.05 to 20.00 x CT**Default: 1.00 x CT***SENS GND IOC1 FUNCTION [WHEN SPECIFICALLY ORDERED]***Range: Disabled, Trip, Latched Alarm, Alarm**Default: Disabled*

↳

**SENS GND IOC1 PICKUP***Range: 0.005 to 3.000 x CT**Default: 1.00 x CT*

**NTRL IOC1 FUNCTION**

*Range: Disabled, Trip, Latched Alarm, Alarm*

*Default: Disabled*

↳

**NTRL IOC1 PICKUP**

*Range: 0.05 to 20.00 x CT*

*Default: 1.00 x CT*



The settings changed using the Quick Setup menu, are available for review and modification by navigating through **S2 SYSTEM SETUP** and **S3 PROTECTION > SETPOINT GROUP 1** in the **SETPOINTS** main menu.





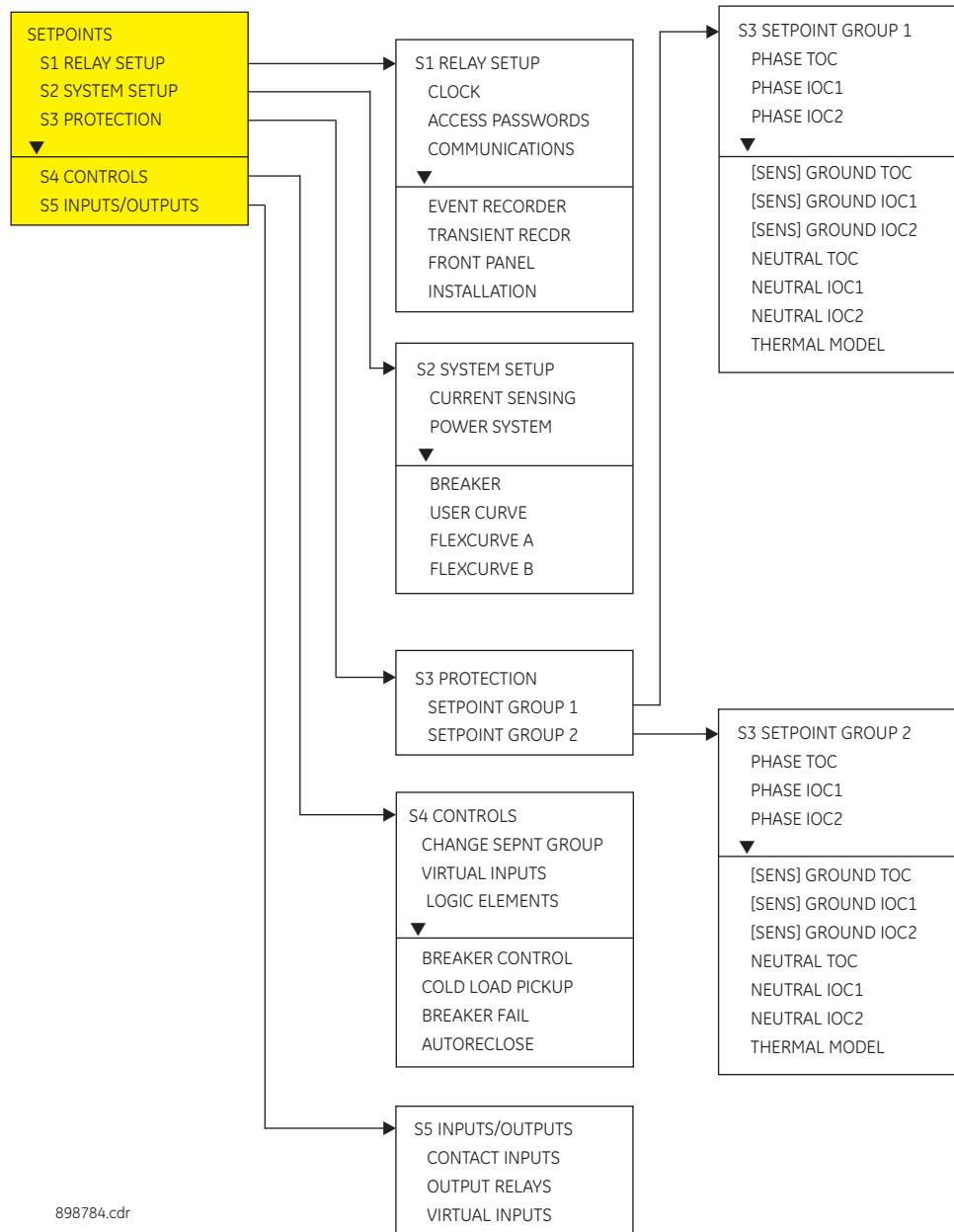
# 350 Feeder Protection System

## Chapter 6: Setpoints

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### 6.1 Setpoints Main Menu

The 350 has a considerable number of programmable setpoints, all of which make the relay extremely flexible. These setpoints have been grouped into a variety of pages and subpages as shown below. Each setpoints menu has a section that describes in detail the setpoints found on that menu.



### 6.1.1 Setpoint entry methods

Before placing the relay into “**IN SERVICE**” mode, setpoints defining system characteristics, inputs, relay outputs, and protection settings must be entered using one of the following methods:

- Front panel, using the keypad and the display.
- Front USB port, or rear RS485, Ethernet 100 FX, Ethernet 10/100 BaseT (optional) port, and a computer running the EnerVista SR3 Setup software supplied with the relay.
- Rear serial RS485, and a SCADA system running user-written software.

Any of these methods can be used to enter the same information. A computer, however, makes entry much easier. Files can be stored and downloaded for fast, error free entry when a computer is used. To facilitate this process, the GE EnerVista CD with the EnerVista SR3 Setup software is supplied with the relay.

The relay leaves the factory with setpoints programmed to default values, and these values are shown throughout the setpoint message illustrations. Some of these factory default values can be left unchanged whenever they satisfy the application.

At a minimum, the **S2 SYSTEM SETUP** setpoints must be entered for the system to function correctly. To safeguard against the installation of a relay into which setpoints have not been entered, the **Relay Not Ready** self-test warning is displayed. In addition, the critical failure relay will be de-energized. Once the relay has been programmed for the intended application, the **S1 RELAY SETUP/ INSTALLATION/ RELAY STATUS** setpoint should be changed from “Not Ready” (the default) to “Ready”.

## 6.1.2 Common setpoints

To make the application of this device as simple as possible, similar methods of operation and similar types of setpoints are incorporated in various features. Rather than repeat operation descriptions for this class of setpoint throughout the manual, a general description is presented in this overview. Details that are specific to a particular feature are included in the discussion of the feature. The form and nature of these setpoints is described below.

- FUNCTION setpoint:** The **<ELEMENT\_NAME> FUNCTION** setpoint determines the operational characteristic of each feature. The range for these setpoints is two or more of: “Disabled”, “Enabled”, “Trip”, “Alarm”, “Latched Alarm”, and “Control”.

If **<ELEMENT\_NAME > FUNCTION**: “Disabled”, the feature is not operational.

If **<ELEMENT\_NAME > FUNCTION**: “Enabled”, the feature is operational.


If **<ELEMENT\_NAME > FUNCTION**: “Trip”, then the feature is operational. When an output is generated, the feature declares a Trip condition, and operates the Trip relay (output relay 1), any other selected aux. output relays, and displays the appropriate trip message.

If **<ELEMENT\_NAME> FUNCTION**: “Alarm” or “Latched Alarm”, then the feature is operational. When an output is generated, the feature declares an “Alarm” condition which operates any selected aux.output relays and displays the appropriate alarm message.

If **<ELEMENT\_NAME> FUNCTION**: “Control” the feature is operational. When an output is generated, the feature operates any selected output relays. The “Trip”, “Alarm”, and “Control” function setpoint values are also used to select those operations that will be stored in the Event Recorder.
- RELAYS (3–6) setpoint:** The **<ELEMENT\_NAME> RELAYS (3-6)** setpoint selects the relays required to operate when the feature generates an output. The range is any combination of the Auxiliary relays (Auxiliary Relays 3 to 6).
- PICKUP setpoint:** The **<ELEMENT\_NAME> PICKUP** setpoint selects the threshold above which the measured parameter causes an output from the measuring element.
- DELAY setpoint:** The **<ELEMENT\_NAME> DELAY** setpoint selects a fixed time interval to delay an input signal from appearing at the output. The time from a contact input change of state or an AC parameter input level change to a contact closure of the 1 Trip relay, is the time selected as time delay in this setpoint plus approximately up to 2 power frequency periods.

### 6.1.3 Logic diagrams

The logic diagrams provide a complete comprehensive understanding of the operation of each feature. These sequential logic diagrams illustrate how each setpoint, input parameter, and internal logic is used in the feature to obtain an output. In addition to these logic diagrams, written descriptions are provided in the setpoints chapter which includes each feature.

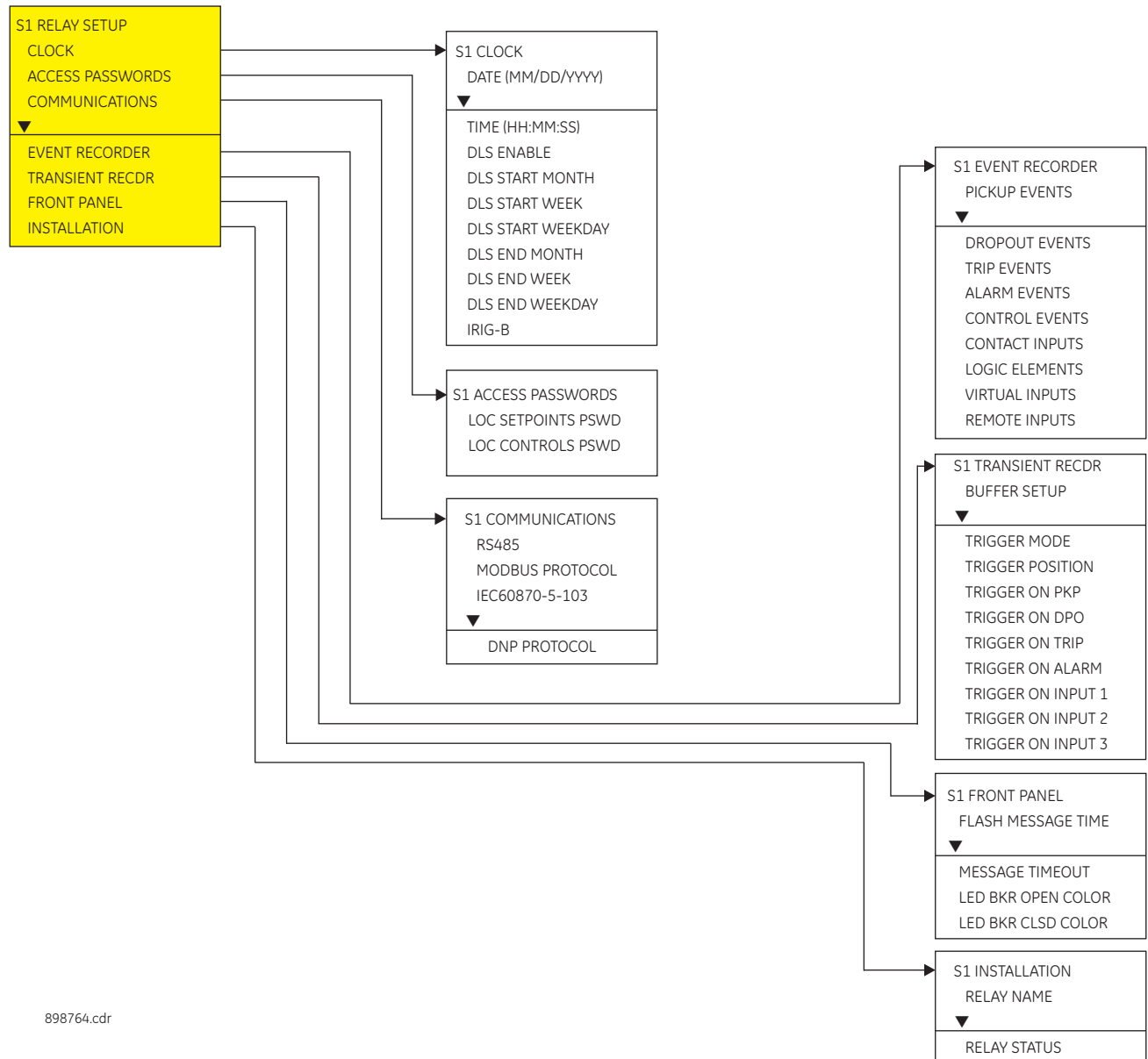
- **Setpoints:** Shown as a block with a heading labeled '**SETPOINT**'. The exact wording of the displayed setpoint message identifies the setpoint. Major functional setpoint selections are listed below the name and are incorporated in the logic.
- **Compensator Blocks:** Shown as a block with an inset box labeled '**RUN**' with the associated pickup/dropout setpoint shown directly above. Element operation of the detector is controlled by the signal entering the '**RUN**' inset. The measurement/comparison can only be performed if a logic '1' is provided at the '**RUN**' input. The relationship between setpoint and input parameter is indicated by the following symbols: "<" (less than) ">" (greater than), etc.
- **Time Delays:** Shown as a block with either pickup, drop-out, or both; times in milliseconds or seconds. If the delay is adjustable, associated delay setpoint is shown with block **SETPOINT** on the top of the delay block.
- **LED Indicators:** Shown as the following schematic symbol, . The exact wording of the front panel label identifies the indicator.
- **Logic:** Described with basic logic gates (**AND, OR, XOR, NAND, NOR**). The inverter (**logical NOT**), is shown as a circle: .

### 6.1.4 Setting text abbreviations

The following abbreviations are used in the setpoints pages.

- A: amperes
- kA: kiloamperes
- AUX: auxiliary
- COM, Comms: communications
- CT: current transformer
- GND: ground
- Hz: Hertz
- MAX: maximum
- MIN: minimum
- SEC, s: seconds
- Ctrl: control
- Hr & hr: hour
- O/L: overload

## 6.2 S1 Relay setup



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### 6.2.1 Clock

The 350 relay has an internal real time clock that performs time stamping for various features such as the event and transient recorders. Time stamping on the relay is also available with the IRIG-B signal connected to the relay terminals and set to "Enabled". When an IRIG-B device is connected to the relay terminals, the relay detects the DC shift or the Amplitude Modulated signal automatically. Time stamping on multiple relays can be synchronized to  $\pm 1.0$  ms with the use of IRIG-B input.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > S1 RELAY SETUP > CLOCK****DATE: (MM/DD/YYYY)**

Range: Month: Jan, Feb, Mar, Apr, May, Jun, Jul, Aug, Sep, Oct, Nov, Dec Day: 1 to 31 Year: 2009 to 2099

Default: Jan 15 2009

This setting sets the date in the specified format.

**TIME: (HH:MM:SS)**

Range: 0 to 23: 0 to 59: 0 to 59

Default: 03:15:50

This setting sets the time in the specified format.

**DLS ENABLE**

Range: Disabled, Enabled

Default: Disabled

**PATH: SETPOINTS > S1 RELAY SETUP > CLOCK > DLS ENABLE [ENABLED]****DLS START MONTH:**

Range: Not Set, January, February, March, April, May, June, July, August, September, October, November, December

Default: Not Set

This setting sets the month for the DLS start time.

**DLS START WEEK:**

Range: Not Set, 1<sup>st</sup>, 2<sup>nd</sup>, 3<sup>rd</sup>, 4<sup>th</sup>, Last

Default: Not Set

This setting sets the week of the month for the DLS start time.

**DLS START WEEKDAY:**

Range: Not Set, Mon, Tue, Wed, Thu, Fri, Sat, Sun

Default: Not Set

This setting sets the weekday for the DLS start time.

**DLS END MONTH:**

Range: Not Set, January, February, March, April, May, June, July, August, September, October, November, December

Default: Not Set

This setting sets the month for the end of the DLS time.

**DLS END WEEK:**

Range: Not Set, 1<sup>st</sup>, 2<sup>nd</sup>, 3<sup>rd</sup>, 4<sup>th</sup>, Last

Default: Not Set

This setting sets the week of the month for the end of the DLS time.

**DLS END WEEKDAY:**

Range: Not Set, Mon, Tue, Wed, Thu, Fri, Sat, Sun

Default: Not Set

This setting sets the weekday for the end of the DLS time.

**PATH: SETPOINTS > S1 RELAY SETUP > CLOCK****IRIG-B:**

Range: Disabled, Enabled

Default: Disabled

This setting enables the IRIG-B signal for time stamp synchronization.

1. Set the IRIG-B to “Enabled” if the IRIG-B device is connected to the relay IRIG-B terminals. The relay will display the message “IRIG-B failure” in the case of either no IRIG-B signal from the connected IRIG-B device, or when the signal cannot be decoded.
2. Set the date and time per the specified date and time format.
3. Set the start time of the Daylight Saving (DLS) time, by selecting the Month, the Week of the month, and the Weekday defining the beginning of the Daylight Saving time.
4. Set the end of the Daylight Saving time, by selecting the Month, the Week of the month, and the Weekday defining the end of the Daylight Saving time.

The clock has a super-capacitor back-up, so that time, date, and events will be kept for up to 3 days in cases of loss of relay control power.

## 6.2.2 Password security

Password security features are designed into the relay to provide protection against unauthorized setpoint changes and control. The relay has programmable passwords for both Local and Remote access, which can be used to allow setpoint changes and command execution from both the front panel and the communications ports. These passwords consist of 3 to 10 alphanumeric characters. The Local and the Remote passwords are initially set after entering in a Master Reset Password (MRP). The Master Reset Password (MRP) is set to “NULL” when the relay is shipped from the factory. When the MRP is programmed to “NULL” all password security is disabled.. The remote user may choose to allow the local user to change the local passwords.

Each interface (RS485, Ethernet, USB, and front panel keypad) is independent of one another, meaning that enabling setpoint access on one interface does not enable access for any of the other interfaces (i.e., the password must be explicitly entered via the interface from which access is desired).

The EnerVista SR3 Setup software incorporates a facility for programming the relay's passwords as well as enabling/disabling setpoint access. For example, when an attempt is made to modify a setpoint but access is restricted, the program will prompt the user to enter the password and send it to the relay before the setpoint can actually be written to the relay. If a SCADA system is used for relay programming, it is up to the programmer to incorporate appropriate security for the application.

Aside from being logged out of security, which allows the user to read setpoints and actual values only, three levels of security access are provided: Setpoint Level, Control Level, and Master Level. The Setpoint and Control Levels can be attained either locally using the Local passwords (USB port and keypad), or remotely using the Remote passwords (RS485 and Ethernet ports). The user can have either Setpoint or Control Level active, but not both simultaneously from the same interface. The Master Level is used for setting and resetting of passwords, and includes all Setpoint and Control Level access rights. The Master Level cannot be attained from the keypad. The Master Reset Password must be 8 to 10 characters in length, and must contain at least 2 letters and 2 numbers. The Master Level can define whether the local user is permitted to change Local Passwords without having to enter the Master Level. The Master Reset Password is encrypted, and is not viewable from the keypad. If the Master Reset Password is lost, the user should contact the factory to decrypt the Master Reset Password.

After password entry, the access level is maintained until a period of 5 minutes of inactivity has elapsed, after which the password must be re-entered. A power-loss or entering in the wrong password will log the user out of security.

Further definition of the access levels is described as follows:

**SETPOINT LEVEL**

- Changing settings under QUICK SETUP menu
- Changing settings under the SETPOINTS menu except the features requiring control access listed below
- Changing any setting under MAINTENANCE such as trip and close coil monitoring and breaker maintenance settings, except the features requiring control access listed below
- Changing the Local or Remote Setpoint Password, depending on the interface being accessed

**CONTROL LEVEL**

- Reset command
- Open and Close Breaker commands
- Virtual Input commands
- Clearing of event records, transient records, and other data
- Uploading new firmware
- Changing the Local or Remote Control Password, depending on the interface being accessed

**MASTER LEVEL**

- Setting and changing of all passwords including the Master Reset Password
- Disabling password security
- All Setpoint and Control Level access rights

For details on Password Security setup and handling using the EnerVista Setup software, refer to *section 3.2.6.4*.

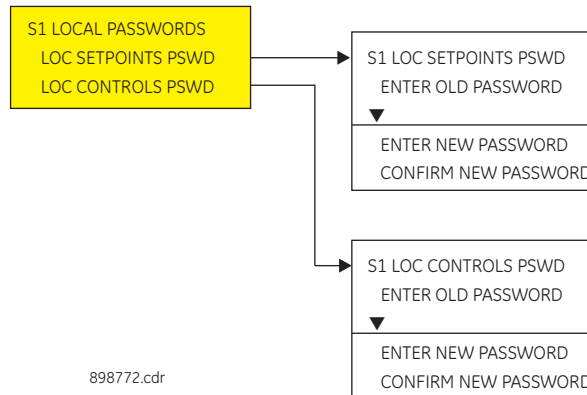
**6.2.2.1 Access passwords**

This section allows the user to change the Local Setpoint and Local Control Passwords. The local user may change a local password from the keypad if all of the following are true:

- Security is enabled
- A valid local setpoint (or local control) password has initially been set
- The remote user has the Overwrite Local Passwords setpoint set to **NO**
- The local user knows the current local password.

For more details on the Password Security feature, refer to *section 3.2.6.4*.

**Figure 6-1: Menu for handling password security using 350 keypad**



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The following steps describe how to change the Local Setpoints Password from the keypad. Similar steps are followed to change the Local Control Password.

**ENTER OLD PASSWORD**

The user is prompted to enter the current Local Setpoints Password. Use the value up/down keys to select characters, and use the message left/right keys to move the cursor. Press the Enter key when done. An INVALID PASSWORD message will appear if a wrong password is entered, security is disabled, the password has not been originally set, or the local user does not have the rights to change the password. In addition, the user will be automatically logged out of security from the keypad. If the correct password was entered, the user is now logged in to the Setpoints Level from the keypad, and will be prompted to enter a new password.

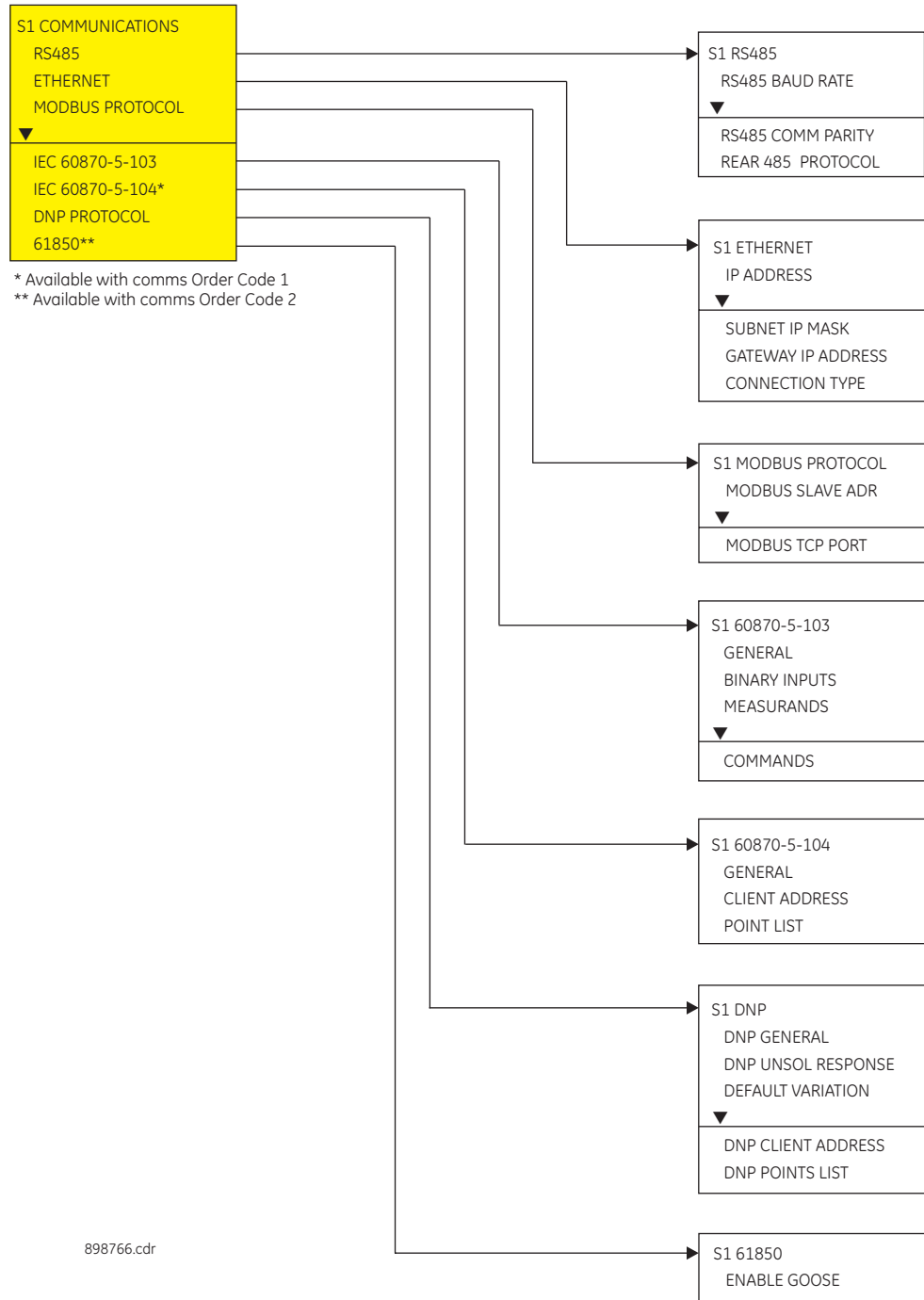
**ENTER NEW PASSWORD**

The user is prompted to enter a new Local Setpoints Password. A valid password is alphanumeric, and is 3 to 10 characters in length. An INVALID PASSWORD message will appear if the new password does not meet the password requirements. If a valid password was entered, the user will be prompted to re-enter the new password.

**CONFIRM PASSWORD**

The user is prompted to re-enter the new Local Setpoints Password. If the passwords do not match, an ENTRY MISMATCH message will appear, the password will remain unchanged, and the user will be returned to the Enter New Password page. If the passwords match, a PASSWORD CHANGED message will appear indicating the Local Setpoints Password has successfully been updated.

### 6.2.3 Communications



#### 6.2.3.1 RS485 interface

The 350 is equipped with one serial RS485 communication port. The RS485 port has settings for baud rate and parity. It is important that these parameters agree with the settings used on the computer or other equipment that is connected to these ports. This port may be connected to a computer running the EnerVista SR3 Setup software. This

software can download and upload setting files, view measured parameters, and upgrade the device firmware. A maximum of 32 350-series devices can be daisy-chained and connected to a DCS, PLC, or PC using the RS485 port.

Select the **Settings > Communications > Serial Ports** menu item in the EnerVista SR3 Setup program, or the **SETPOINTS > S1 RELAY SETUP > COMMUNICATIONS > RS485** path on the display, to configure the serial port.

**Figure 6-2: Serial port configuration settings**

SETTING	PARAMETER
Baud Rate	19200
Parity	None

The following settings are available to configure the RS485 port.

**BAUD RATE**

*Range: 9600, 19200, 38400, 57600, 115200*

*Default: 115200*

This setting specifies the baud rate (bits per second) for the RS485 port.

**PARITY**

*Range: None, Odd, Even*

*Default: None*

This setting specifies the parity for the RS485 port.

### 6.2.3.2 Ethernet

Select the **Setpoints > S1 Relay Setup > Communications > Ethernet** menu item in the EnerVista SR3 Setup program, or the **SETPOINTS > S1 RELAY SETUP > COMMUNICATIONS > ETHERNET** path on the display, to configure the Ethernet port.

The following settings are available to configure the Ethernet port.

**IP Address**

*Range: Standard IP Address format*

*Default: 000.000.000.000*

This setting specifies the IP Address for the Ethernet port.

**Subnet IP Mask**

*Range: Standard IP Address format*

*Default: 255.255.255.000*

This setting specifies the Subnet IP Mask setting for the Ethernet port.

**Gateway IP Address**

*Range: Standard IP Address format*

*Default: 000.000.000.000*

This setting specifies the Gateway IP Address for the Ethernet port.

**Connection Type**

*Range: Copper, fiber*

*Default: Copper*

This setting specifies the connection type (Copper or Fiber) used for Ethernet communication.

### 6.2.3.3 Modbus

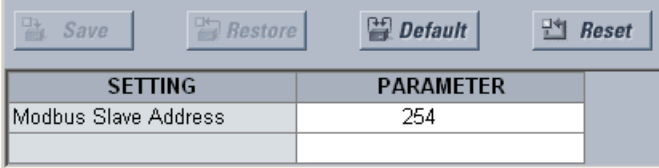
The Modicon Modbus protocol is supported by the 350. Modbus is available via the RS485 serial link (Modbus RTU). The 350 always acts as a slave device, meaning that it never initiates communications; it only listens and responds to requests issued by a master device. A subset of the Modbus protocol format is supported that allows extensive monitoring, programming, and control functions using read and write register commands. Refer to the *350 Feeder Protection System Communications Guide* for additional details on the Modbus protocol and the Modbus memory map.

The Modbus server can simultaneously support two clients over serial RS485. The server is capable of reporting any indication or measurement and operating any output present in the device. A user-configurable input and output map is also implemented.

The 350 operates as a Modbus slave device only

Select the **Settings > Communications > Modbus > Protocol** menu item in EnerVista SR3 Setup software, or the **SETPOINTS > S1 RELAY SETUP > COMMUNICATIONS > MODBUS PROTOCOL** path to set up the modbus protocol as shown below.

**Figure 6-3: Modbus protocol configuration settings**



SETTING	PARAMETER
Modbus Slave Address	254

The following Modbus settings are available:

#### **MODBUS SLAVE ADDRESS**

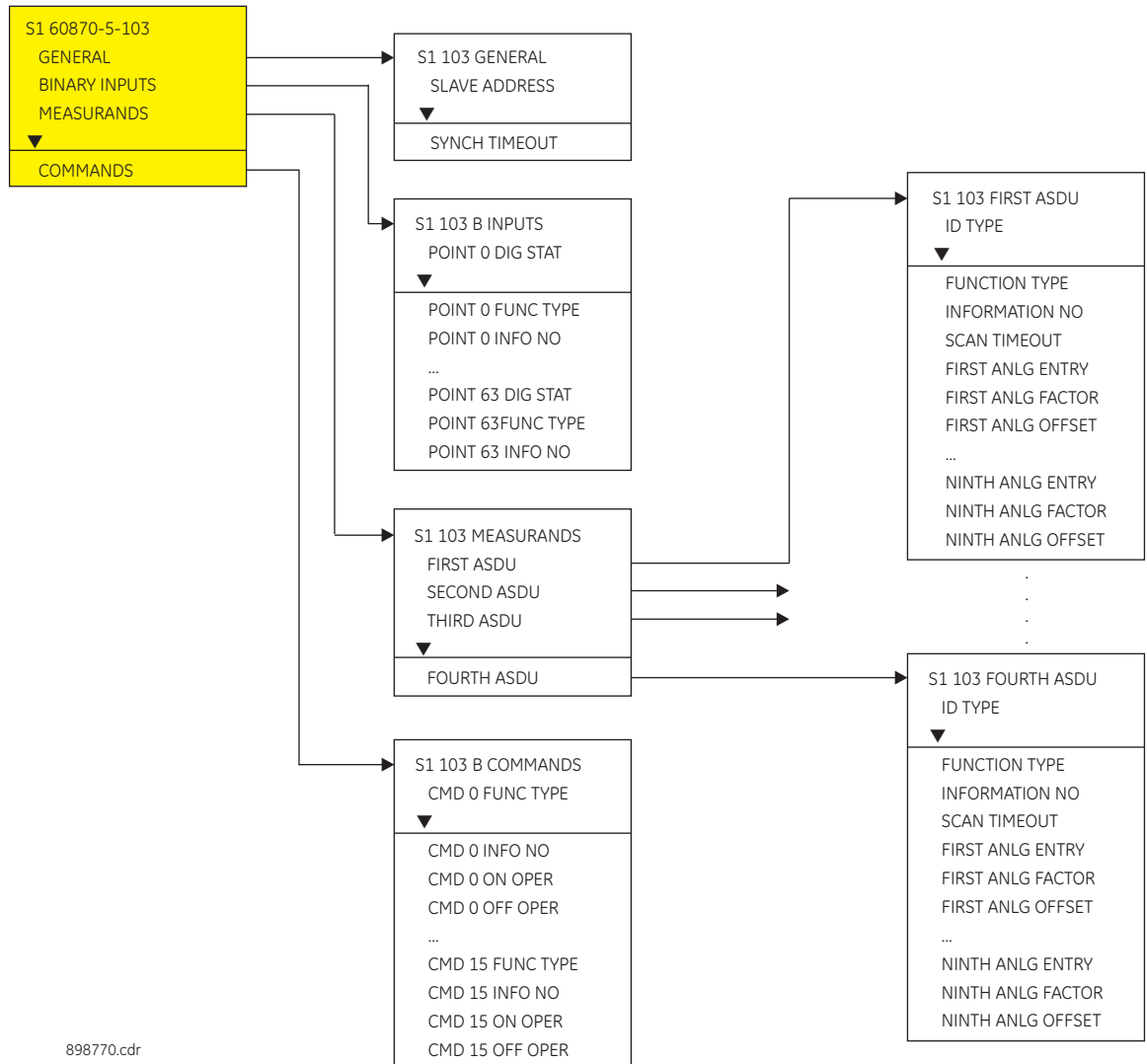
*Range: 1 to 254 in steps of 1*

*Default: 254*

This setting specifies the Modbus slave address. Each device must have a unique address from 1 to 254. Address 0 is the broadcast address to which all Modbus slave devices listen. Addresses do not have to be sequential, but no two devices can have the same address or conflicts resulting in errors will occur. Generally, each device added to the link should use the next higher address starting at 1.

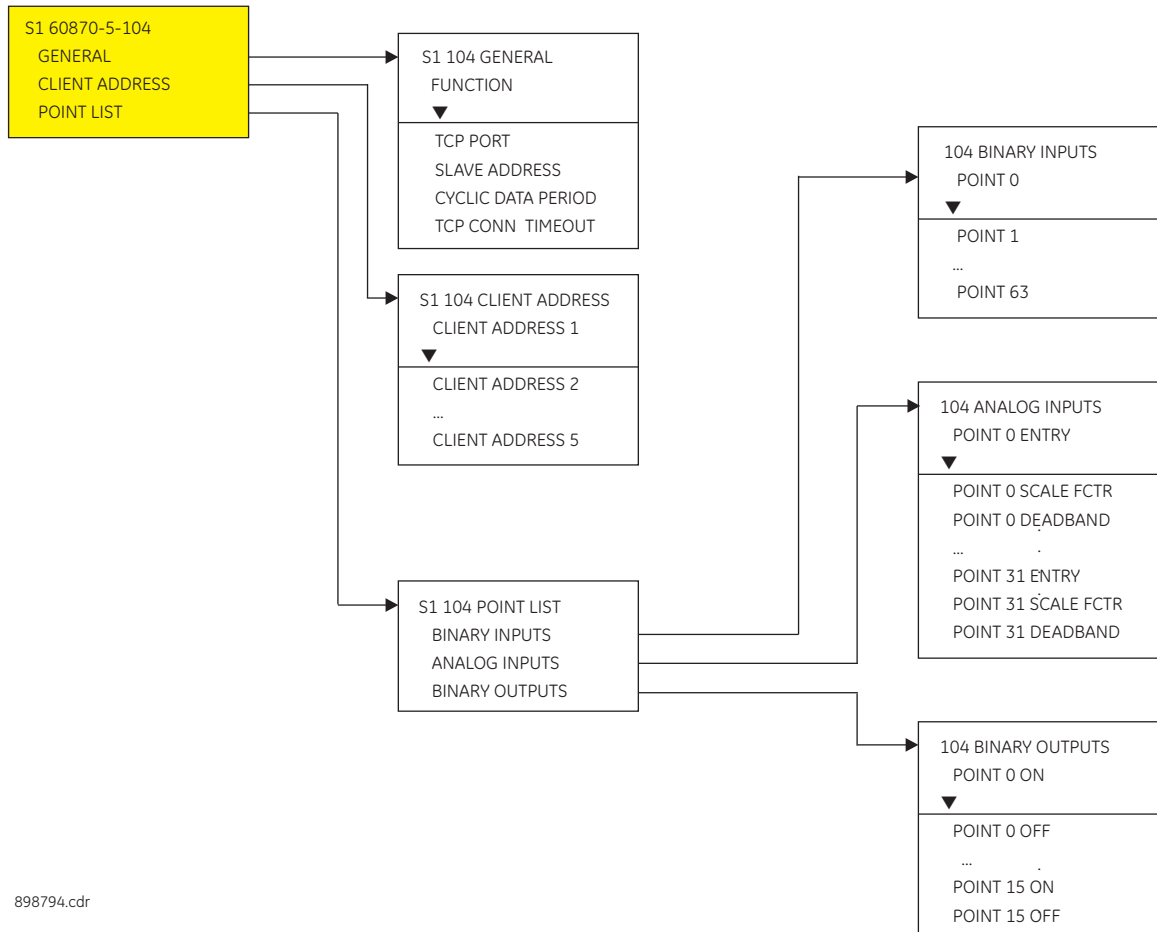
Please refer to the *350 Communications Guide* for details on how to set up the Modbus communications protocol.

6.2.3.4 IEC 60870-5-103 serial communication



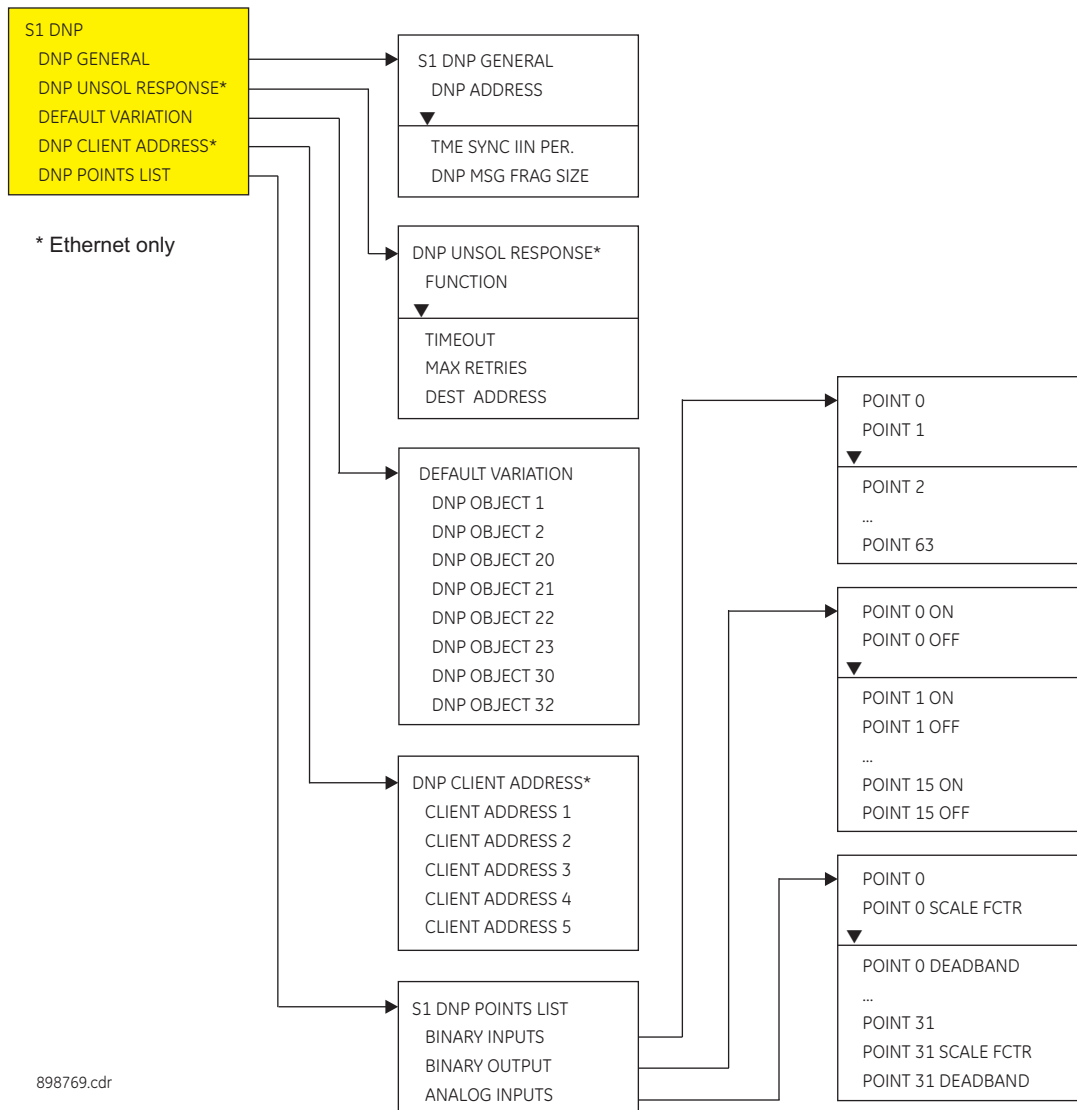
PATH: SETPOINTS > S1 RELAY SETUP > COMMUNICATIONS > IEC61870-5-103

### 6.2.3.5 IEC60870-5-104 protocol



### 6.2.3.6 DNP communication

The menu structure for the DNP protocol is shown below.



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The following path is available using the keypad. For instructions on how to use the keypad, please refer to the *350 Instruction Manual, Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > RELAY SETUP > COMMUNICATIONS > DNP PROTOCOL > DNP GENERAL**

### 6.2.3.7 IEC 61850 GOOSE communications

The 350 firmware supports IEC61850 GOOSE communications on the optional communications daughter board.

Portions of the IEC61850 standard not pertaining to GOOSE, are not implemented in the 350 relay.

The 350 relay does not support

- an IEC61850 MMS server
- the mapping of analogue values to data points in data sets in either the transmit or receive direction

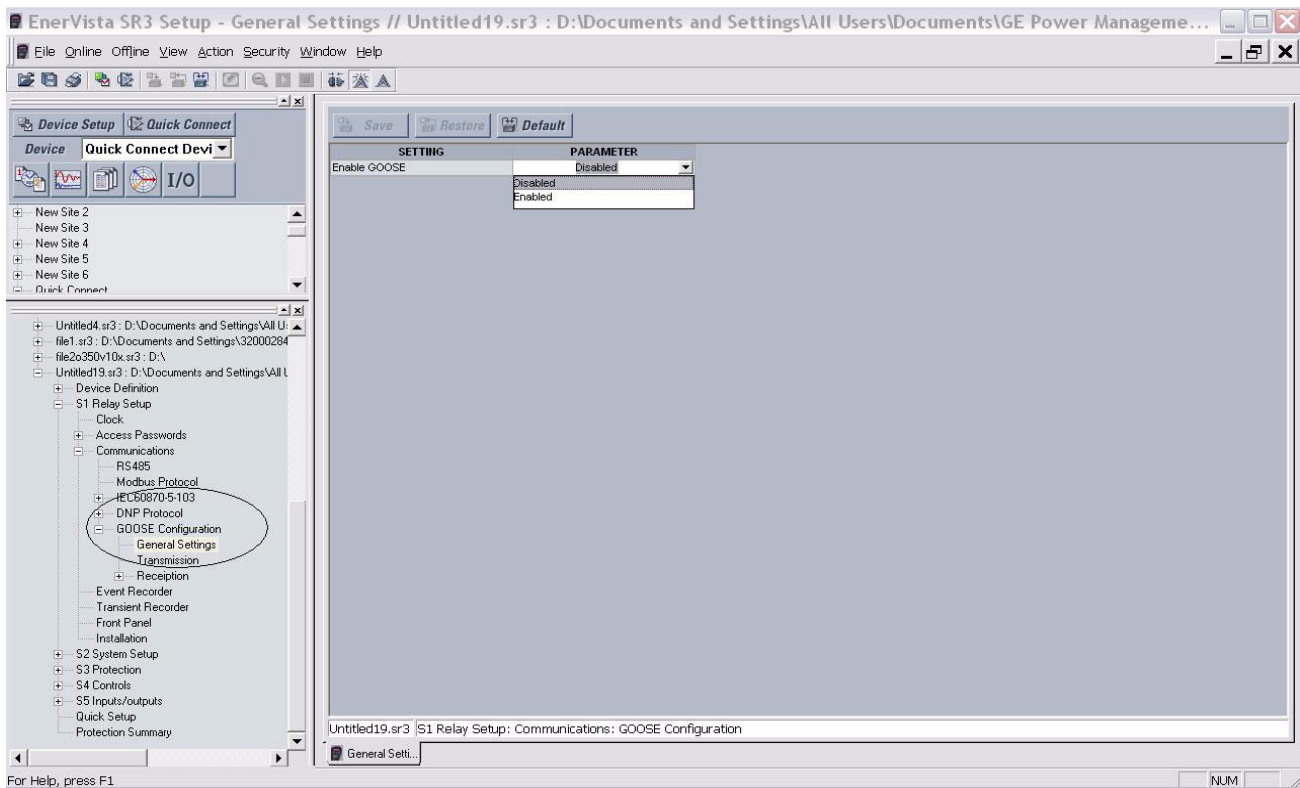
- a file system to maintain SCL, ICD or CID files, for IEC61850 GOOSE. As such the implementation stores GOOSE configuration using MODBUS set points.

Configuration of transmission and reception settings for the GOOSE feature are performed using EnerVista SR3 Setup Software.

The 350 firmware accepts GOOSE messages from UR, F650 and UR Plus. The interoperability with other manufacturers will be guaranteed in almost all cases, by implementing the reception side with nested structures (one level of nesting) and all the standard data types.

GOOSE settings changes will take effect only after the 350 relay is re-booted. One setting is available to Enable/Disable both Transmission and Reception. It is possible to change this setting from the Front Panel of the relay.

Figure 6-4: EnerVista SR3 GOOSE General Settings



## 6.2.4 Event recorder

The Event Recorder runs continuously, capturing and storing the last 256 events. All events are stored in a non-volatile memory where the information is maintained for up to 3 days in case of lost relay control power.

**PATH:** SETPOINTS > S1 RELAY SETUP > EVENT RECORDER

### PICKUP EVENTS

*Range: Disabled, Enabled*

*Default: Enabled*

When set to "Enabled", the event recorder records the events that occur when a protection element picks up.

**DROPOUT EVENTS**

*Range: Disabled, Enabled*

*Default: Disabled*

When set to "Enabled" the event recorder records the dropout state of a protection element.

**TRIP EVENTS**

*Range: Disabled, Enabled*

*Default: Enabled*

The trip events include all programmed relay elements set to trip the breaker. The text "TRIP" followed by the name of the operated element is recorded.

**ALARM EVENTS**

*Range: Disabled, Enabled*

*Default: Enabled*

These events include the elements programmed as an "ALARM" or "LATCHED ALARM" function, which detect power system conditions considered as an alarm.

**CONTROL EVENTS**

*Range: Disabled, Enabled*

*Default: Enabled*

If set to "Enabled", the event recorder records events caused by the performance of the programmed control elements.

**CONTACT INPUTS**

*Range: Disabled, Enabled*

*Default: Enabled*

When set to "Enabled", the event recorder will record the event, when a contact input changes its state.

**LOGIC ELEMENT**

*Range: Disabled, Enabled*

*Default: Enabled*

When set to "Enabled", the event recorder records the events, which occur upon state change of any programmed remote input.

**VIRTUAL INPUTS**

*Range: Disabled, Enabled*

*Default: Enabled*

When set to "Enabled", the event recorder records the events, which occur upon state changes of any logic element.

**REMOTE INPUTS**

*Range: Disabled, Enabled*

*Default: Enabled*

When set to "Enabled", the event recorder records the events, which occur upon state change of any programmed remote input.

## 6.2.5 Transient recorder

The Transient Recorder contains waveforms captured at the same sampling rate as the other relay data at the point of trigger. By default, data is captured for the analog current inputs - Ia, Ib, Ic, Ig. Triggering of the transient recorder occurs, when an event is detected "high," causing a pickup, trip, dropout, or alarm, any one of which has been "Enabled" to activate the trigger. The transient recorder trigger may also be activated when any of the selected trigger inputs 1 to 3 is detected as having "On" status.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH:** SETPOINTS > S1 RELAY SETUP > TRANSIENT RECDR

**BUFFER SETUP**

*Range: 1 x 192, 3 x 64, 6 x 32*

*Default: 3 x 64*

Each selection from the range is expressed by two numbers; the first identifies the number of records, whereas the second stands for the number of cycles per record.

**TRIGGER MODE**

*Range: Overwrite, Overwrite protected*

*Default: Overwrite*

When the "Overwrite" setting is selected, the new records overwrite the old ones, meaning the relay will always keep the newest records. In "Protected" mode, the relay will keep the number of records corresponding to the selected number, only without overwriting.

**TRIGGER POSITION**

*Range: 0 to 100% in steps of 1%*

*Default: 0%*

This setting indicates the location of the trigger with respect to the selected length of record. For example at 20% selected trigger position, the length of each record will be split on 20% pre-trigger data, and 80% post-trigger data.

**TRIGGER ON PKP**

*Range: Off, On*

*Default: Off*

Selection of "Yes" setting enables triggering for the recorder upon Pickup condition detected from any protection or control element.

**TRIGGER ON DPO**

*Range: Off, On*

*Default: Off*

Selection of "Yes" setting enables triggering for the recorder upon Pickup condition detected from any protection or control element.

**TRIGGER ON TRIP**

*Range: Off, On*

*Default: Off*

Selection of "Yes" setting enables triggering for the recorder upon Trip condition detected from any protection or control element.

**TRIGGER ON ALARM**

*Range: Off, On*

*Default: Off*

Selection of "Yes" setting enables triggering for the recorder upon Alarm condition detected from any protection or control element.

**TRIGGER ON INPUT 1 to 3**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Element 1 to 8*

*Default: Off*

Selection of input or logic element from the settings range enables triggering input for the recorder. A record will be triggered if the status of the selected input changes to "On".

## 6.2.6 Front panel

The user can send a message to the display, that will override any normal message by sending text through Modbus. Refer to the *350 Feeder Protection System Communications Guide* for register details.

**PATH:** [SETPOINTS > S1 RELAY SETUP > FRONT PANEL](#)

### FLASH MESSAGE TIME

*Range: 1 s to 65535 s*

*Default: 5 s*

Flash messages are status, warning, error, or information messages displayed for several seconds in response to certain key presses during setting programming. These messages override any normal messages. The duration of a flash message on the display can be changed to accommodate different reading rates.

### MESSAGE TIMEOUT

*Range: 1 s to 65535 s*

*Default: 30 s*

If the keypad is inactive for a period of time, the relay automatically reverts to a default message. The inactivity time is modified via this setting to ensure messages remain on the screen long enough during programming or reading of actual values.

### SCREEN SAVER

*Range: Off, 1 min to 10000 min*

*Default: Off*

The life of the LCD backlight can be prolonged by enabling the Screen Saver mode.

If the keypad is inactive for the selected period of time, the relay automatically shuts off the LCD screen. Any activity (keypress, alarm, trip, or target message) will restore screen messages.

### LED BKR OPEN COLOR

*Range: Red, Green*

*Default: Green*

Allows the user to select the color of the LED indicator under Breaker Open conditions.

### LED BKR CLSD COLOR

*Range: Red, Green*

*Default: Red*

Allows the user to select the color of the LED indicator under Breaker Closed conditions.

## 6.2.7 Installation

**PATH:** [SETPOINTS > S1 RELAY SETUP > INSTALLATION](#)

### RELAY NAME

*Range: Feeder Name, Alpha-numeric (18 characters)*

*Default: Feeder Name*

The RELAY NAME setting allows the user to uniquely identify a relay. This name will appear on generated reports. This name is also used to identify specific devices which are engaged in automatically sending/receiving data over the communications channel.

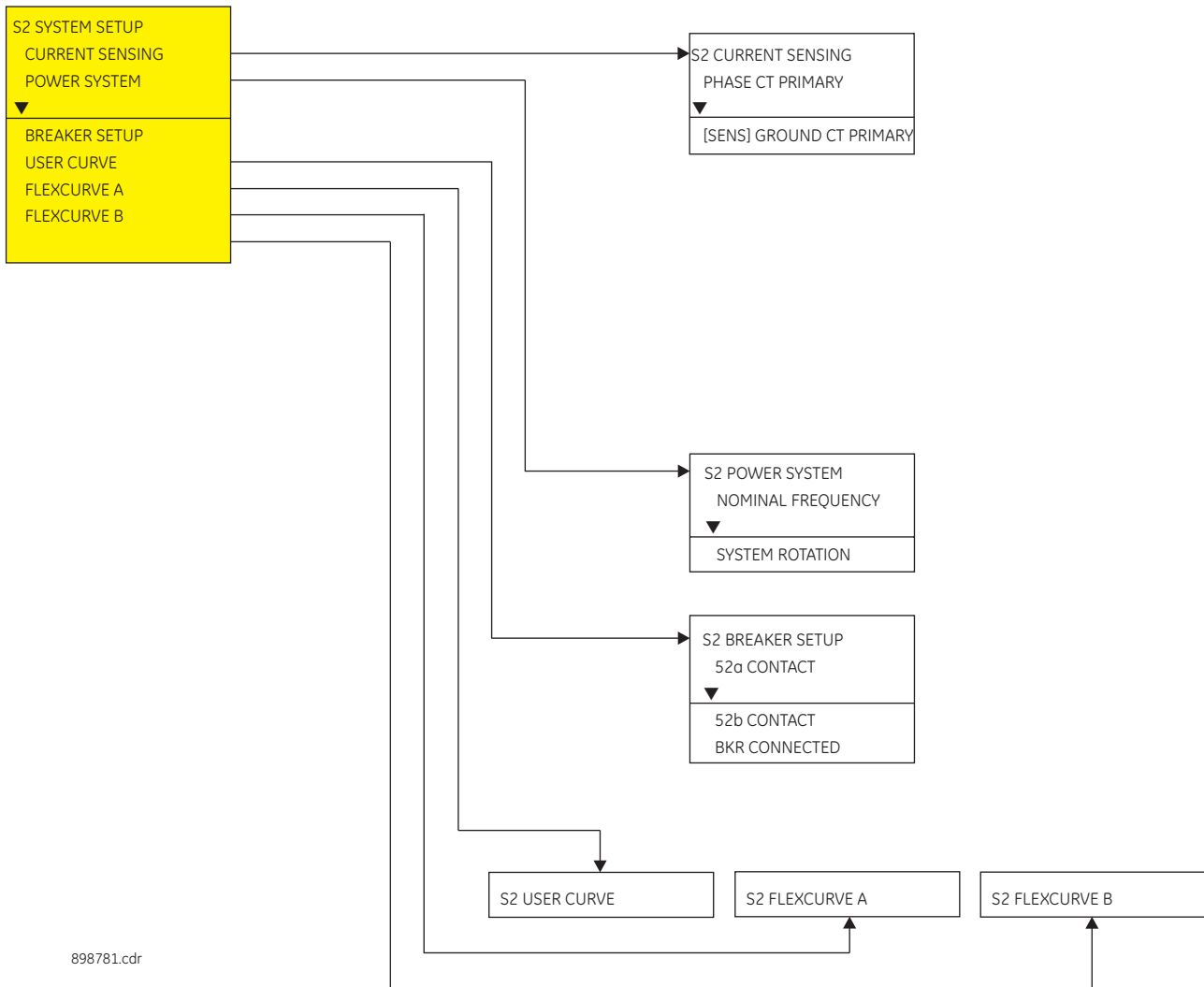
### RELAY STATUS

*Range: Not Ready, Ready*

*Default: Not Ready*

Allows the user to activate/deactivate the relay. The relay is not operational when set to "Not Ready."

## 6.3 S2 System Setup



### 6.3.1 Current sensing

**PATH:** SETPOINTS > S2 SYSTEM SETUP > CURRENT SENSING

**PHASE CT PRIMARY**

*Range: 1 A to 6000 A*

*Default: 500 A*

Enter the primary rating of the three-phase feeder CTs wired to the relay phase CT terminals (see above). For correct operation, the relay CT tap must match the feeder CT tap (5 A or 1 A).

As the phase CTs are connected in wye (star), the calculated phosor sum of the three phase currents ( $I_a + I_b + I_c = \text{Neutral Current} = 3I_0$ ) is used as the input for the neutral overcurrent. In addition, a zero-sequence (core balance) CT which senses current in all of the circuit primary conductors, or a CT in a neutral grounding conductor may also be used.

**GROUND [SENS GND] CT PRIMARY**

*Range: [1 A to 600 A] 1 A to 6000 A*

*Default: 50 A*

For the above configuration, the ground CT primary rating must be entered. To detect low level ground fault currents, the sensitive ground input may be used. In this case, the sensitive ground CT primary rating must be entered. The Sens GND CT primary range is 1 A to 600 A

The relay phase and ground CT types (5 A, 1 A) must match the feeder phase and ground CT taps.

## 6.3.2 Power system

**PATH:** SETPOINTS > S2 SYSTEM SETUP > POWER SYSTEM

**NOMINAL FREQUENCY**

*Range: 60 Hz, 50 Hz*

*Default: 60 Hz*

Enter the nominal power system frequency. This value is used as a default to set the optimal digital sampling rate.

**SYSTEM ROTATION**

*Range: ABC, ACB,*

*Default: ABC*

Enter the phase sequence of the power system.

## 6.3.3 Breaker

The status of the feeder breaker is monitored by the 350 relay using the status of either one or two contact inputs named 52a (CI#1) and 52b (CI#2) wired to the breaker auxiliary contacts 52a and 52b respectively (see below).

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH:** SETPOINTS > S2 SYSTEM SETUP > BREAKER

**52a CONTACT**

*Range: Disabled, 52a (CI#1)*

*Default: Disabled*

Select contact input 52a (CI#1) if connected to breaker auxiliary contact 52a.

**52b CONTACT**

*Range: Disabled, 52b (CI#2)*

*Default: Disabled*

Select contact input 52b (CI#2) if connected to breaker auxiliary contact 52b.

**BKR CONNECTED**

*Range: Contact Input 3 to 8, Disabled*

*Default: Disabled*

Select a contact input to show whether the breaker is connected (Racked-in, or disconnect switches switched-on), or disconnected (racked-out, or disconnect switches switched-off) to the system.



NOTE

It is highly recommended to monitor the status of the feeder breaker using both breaker auxiliary contacts 52a, and 52b, however using only one of them is also acceptable.

The breaker status when disconnected from the main power circuit, such by drawout breaker racking mechanism, or isolated by the associated disconnect switches on a fixed circuit breaker, is provided by monitoring the contact input setting for “BKR CONNECTED”. The logic for Breaker Open, and Breaker Close status is shown in the table below:

**Table 1: Breaker open / Breaker closed status logic**

52a contact configured	52b contact configured	Breaker status	
		Open	Close
Yes	Yes	52a contact open 52b contact closed	52a contact closed 52b contact open
Yes	No	52a contact open	52a contact closed
No	Yes	52b contact closed	52b contact open
No	No	Status unknown	

If the contact input selected under BKR CONNECTED setting is asserted, the breaker is considered connected to the primary system. When the breaker is determined disconnected, the breaker state is shown to be neither open, nor closed.

**Table 2: Breaker status with both contacts configured**

52a contact status	52b contact status	Breaker status
Off	On	open
On	Off	closed
On	On	BKR status failure
Off	Off	BKR status failure

### 6.3.4 User curve

There is one user-programmable User Curve available with the 350 system. Refer to the S3 *Protection/Current Elements/TOC Curves* section for details on how to set the User Curve. Due to the complexity of the configuration, the User Curve is available only through the EnerVista SR3 Setup program.

### 6.3.5 Flexcurves™

There are two user-programmable FlexCurves™ available with the 350 system, labeled A and B.

For details on FlexCurves™ please refer to S3 *Protection/Current Elements/TOC Curves* in this manual.



NOTE

The **User Curve** and **Flexcurves A and B** are available for programming under *EnerVista SR3 Setup software*.

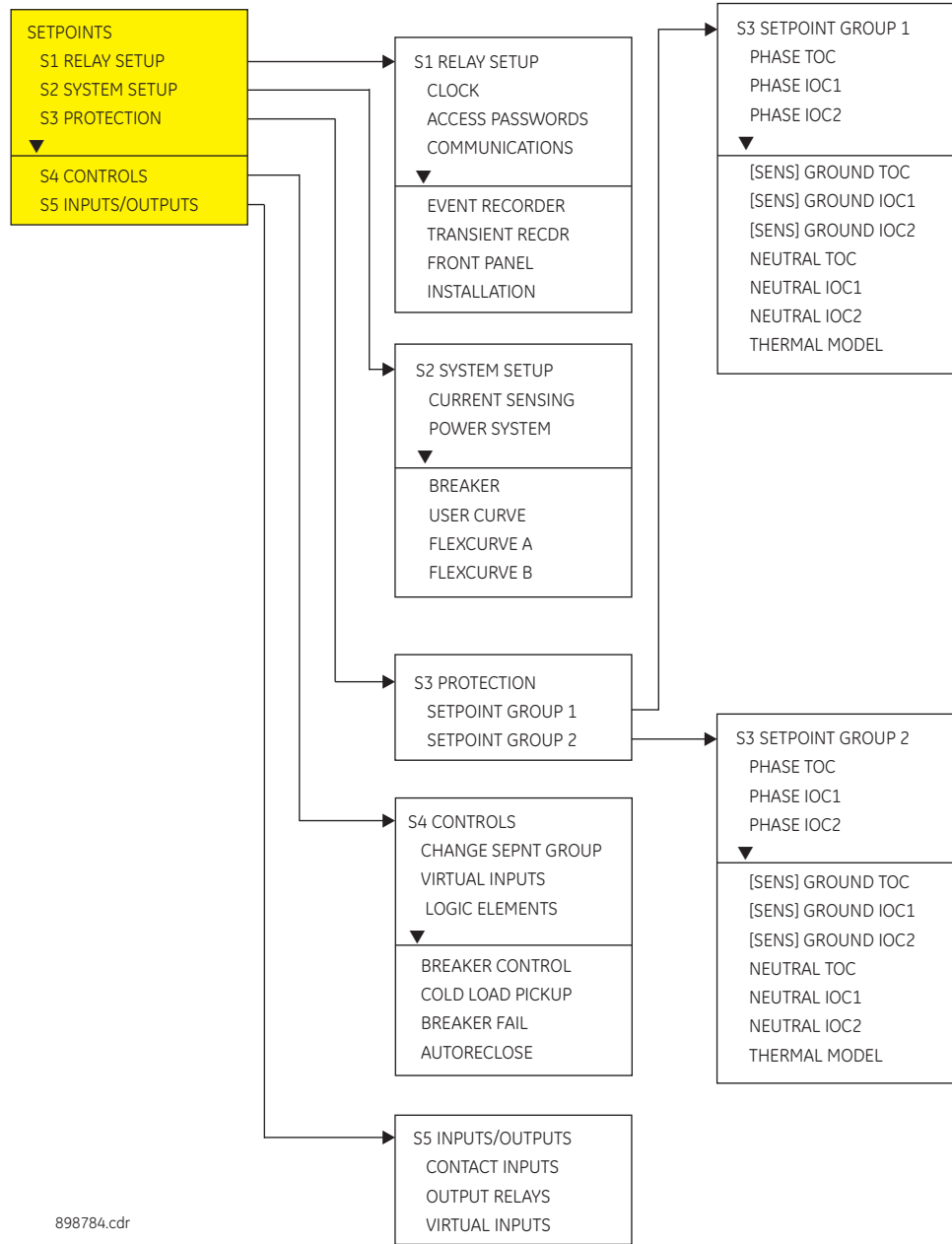
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## 6.4 S3 Protection

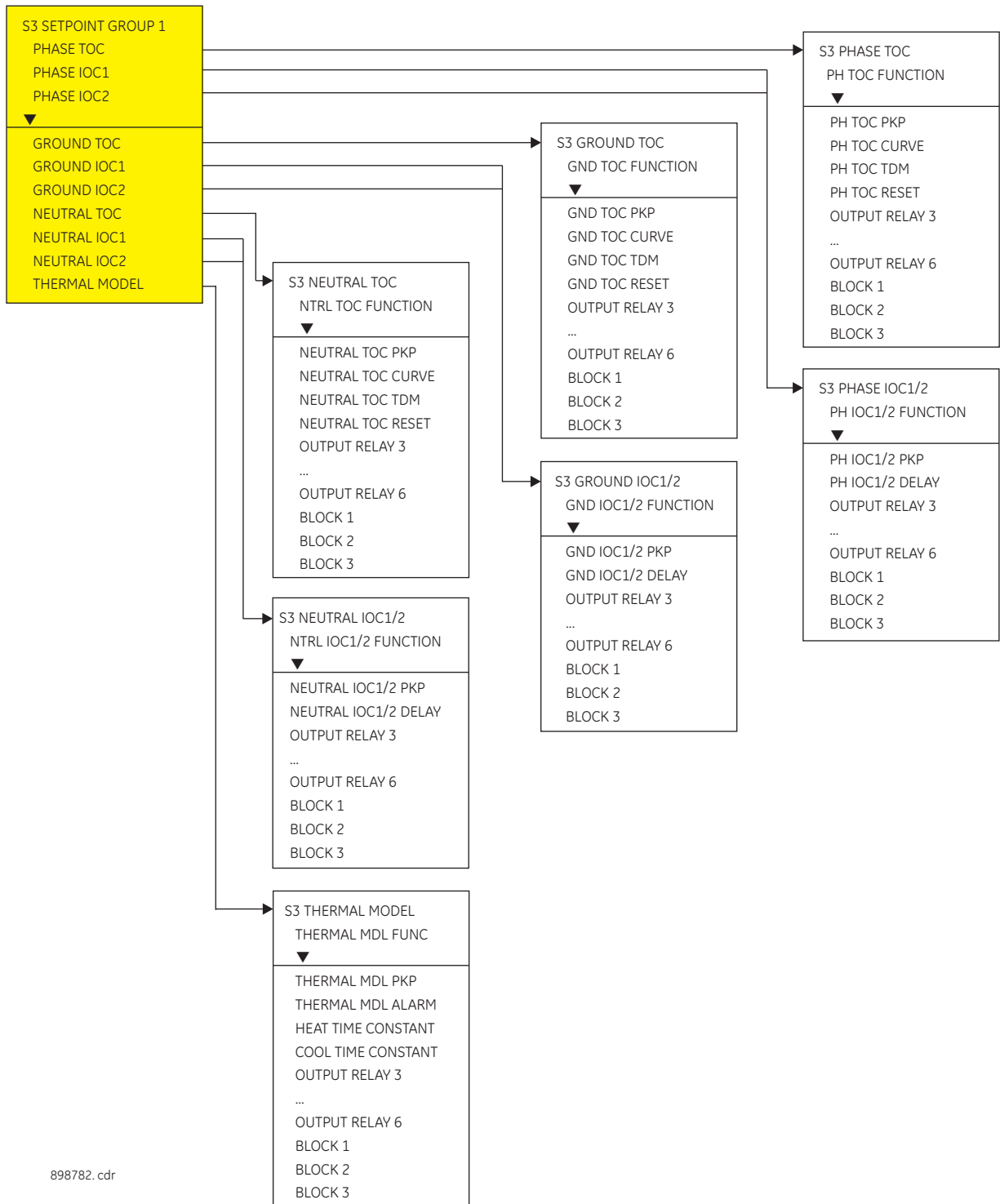
The 350 protection elements are organized in two identical setpoint groups: Setpoint Group 1 and Setpoint Group 2.

Each Setpoint Group has the same protection functions, depending on the relay order code. These protection functions include:

- Phase Timed Overcurrent (Phase TOC)
- Phase Instantaneous Overcurrent (Phase IOC)
- Ground Timed Overcurrent (Ground TOC)
- Ground Instantaneous Overcurrent (Ground IOC1, Ground IOC2)
- Neutral Timed Overcurrent (Neutral TOC)
- Neutral Instantaneous Overcurrent (Neutral IOC1, Neutral IOC2)
- Thermal Model



### 6.4.1 Current elements



898782.cdr

### 6.4.1.1 TOC curves

#### DESCRIPTION

The relay has a total of two phase, two neutral, and two ground/sensitive ground time overcurrent elements. The programming of the time-current characteristics of these elements is identical in all cases and will only be covered in this section. The required curve is established by programming a Pickup Current, Curve Shape, Curve Multiplier, and Reset Time. The Curve Shape can be either a standard shape or a user-defined shape programmed with the FlexCurve™ feature.

Accurate coordination may require changing the time overcurrent characteristics of particular elements under different conditions. For picking up a cold load, a different time-current characteristic can be produced by increasing the pickup current value. The following setpoints are used to program the time-current characteristics.

- **<Element\_Name> PICKUP:** The pickup current is the threshold current at which the time overcurrent element starts timing. There is no intentional 'dead band' when the current is above the pickup level. However, accuracy is only guaranteed above a 1.5 per unit pickup level. The dropout threshold is 98% of the pickup threshold. Enter the pickup current corresponding to 1 per unit on the time overcurrent curves as a multiple of the source CT. For example, if 100: 5 CTs are used and a pickup of 90 amps is required for the time overcurrent element, enter "0.9 x CT".
- **<Element\_Name> CURVE:** Select the desired curve shape. If none of the standard curve shapes is appropriate, a custom FlexCurve™ can be created by entering the trip times at 80 different current values; see S2 SYSTEM SETUP > FLEXCURVE A. Curve formulas are given for use with computer based coordination programs. Calculated trip time values are only valid for  $I / I_{pu} > 1$ . Select the appropriate curve shape and multiplier, thus matching the appropriate curve with the protection requirements. The available curves are shown in the table below.

ANSI	GE TYPE IAC	IEC	OTHER
Extremely Inverse	Extremely Inverse	Curve A (BS142)	Definite Time
Very Inverse	Very Inverse	Curve B (BS142)	Flexcurve A™
Normally Inverse	Inverse	Curve C (BS142)	Flexcurve B™
Moderately Inverse	Short Inverse	IEC Short Inverse	User Curve

- **<Element\_Name> MULTIPLIER:** A multiplier setpoint allows shifting of the selected base curve in the vertical time direction. Unlike the electromechanical time dial equivalent, trip times are directly proportional to the value of the time multiplier setpoint. For example, all trip times for a multiplier of 10 are 10 times the multiplier 1 or base curve values.
- **<Element\_Name> RESET:** Time overcurrent tripping time calculations are made with an internal 'energy capacity' memory variable. When this variable indicates that the energy capacity has reached 100%, a time overcurrent trip is generated. If less than 100% is accumulated in this variable and the current falls below the dropout threshold of 97 to 99% of the pickup value, the variable must be reduced. Two methods of this resetting operation are available, Instantaneous and Linear. The Instantaneous selection is intended for applications with other relays, such as most static units, which set the energy capacity directly to zero when the current falls below the reset threshold. The Linear selection can be used where the relay must coordinate with electromechanical units. With this setpoint, the energy capacity variable is decremented according to the following equation.

$$T_{RESET} = E \times M \times C_R$$

where:  $T_{RESET}$  = reset time in seconds; E = energy capacity reached (per unit); M = curve multiplier; CR = characteristic constant (5 for ANSI, IAC, Definite Time, and FlexCurves™; 8 for IEC)

**TOC CURVE CHARACTERISTICS**

**ANSI Curves**

The ANSI time overcurrent curve shapes conform to industry standards and the ANSI C37.90 curve classifications for extremely, very, normally, and moderately inverse. The ANSI curves are derived from the following formula:

$$T = M \times \left( A + \frac{B}{(I/I_{pu}) - C} + \frac{D}{((I/I_{pu}) - C)^2} + \frac{E}{((I/I_{pu}) - C)^3} \right)$$

where: T = trip time (seconds); M = multiplier value; I = input current;  $I_{pu}$  = pickup current setpoint; A, B, C, D, E = constants

**Table 3: ANSI Curve Constants**

ANSI Curve Shape	A	B	C	D	E
ANSI Extremely Inverse	0.0399	0.2294	0.5000	3.0094	0.7222
ANSI Very Inverse	0.0615	0.7989	0.3400	-0.2840	4.0505
ANSI Normally Inverse	0.0274	2.2614	0.3000	-4.1899	9.1272
ANSI Moderately Inverse	0.1735	0.6791	0.8000	-0.0800	0.1271

**Table 4: ANSI Curve Trip Times (in seconds)**

Multiplier (TDM)	Current (I/Ipickup)									
	1.5	2.0	3.0	4.0	5.0	6.0	7.0	8.0	9.0	10.0
ANSI Extremely Inverse										
0.5	2.000	0.872	0.330	0.184	0.124	0.093	0.075	0.063	0.055	0.049
1.0	4.001	1.744	0.659	0.368	0.247	0.185	0.149	0.126	0.110	0.098
2.0	8.002	3.489	1.319	0.736	0.495	0.371	0.298	0.251	0.219	0.196
4.0	16.004	6.977	2.638	1.472	0.990	0.742	0.596	0.503	0.439	0.393
6.0	24.005	10.466	3.956	2.208	1.484	1.113	0.894	0.754	0.658	0.589
8.0	32.007	13.955	5.275	2.944	1.979	1.483	1.192	1.006	0.878	0.786
10.0	40.009	17.443	6.594	3.680	2.474	1.854	1.491	1.257	1.097	0.982
ANSI Very Inverse										
0.5	1.567	0.663	0.268	0.171	0.130	0.108	0.094	0.085	0.078	0.073
1.0	3.134	1.325	0.537	0.341	0.260	0.216	0.189	0.170	0.156	0.146
2.0	6.268	2.650	1.074	0.682	0.520	0.432	0.378	0.340	0.312	0.291
4.0	12.537	5.301	2.148	1.365	1.040	0.864	0.755	0.680	0.625	0.583
6.0	18.805	7.951	3.221	2.047	1.559	1.297	1.133	1.020	0.937	0.874
8.0	25.073	10.602	4.295	2.730	2.079	1.729	1.510	1.360	1.250	1.165
10.0	31.341	13.252	5.369	3.412	2.599	2.161	1.888	1.700	1.562	1.457
ANSI Normally Inverse										
0.5	2.142	0.883	0.377	0.256	0.203	0.172	0.151	0.135	0.123	0.113
1.0	4.284	1.766	0.754	0.513	0.407	0.344	0.302	0.270	0.246	0.226
2.0	8.568	3.531	1.508	1.025	0.814	0.689	0.604	0.541	0.492	0.452
4.0	17.137	7.062	3.016	2.051	1.627	1.378	1.208	1.082	0.983	0.904
6.0	25.705	10.594	4.524	3.076	2.441	2.067	1.812	1.622	1.475	1.356
8.0	34.274	14.125	6.031	4.102	3.254	2.756	2.415	2.163	1.967	1.808
10.0	42.842	17.656	7.539	5.127	4.068	3.445	3.019	2.704	2.458	2.260

Multiplier (TDM)	Current (I/Ipickup)									
	1.5	2.0	3.0	4.0	5.0	6.0	7.0	8.0	9.0	10.0
ANSI Moderately Inverse										
0.5	0.675	0.379	0.239	0.191	0.166	0.151	0.141	0.133	0.128	0.123
1.0	1.351	0.757	0.478	0.382	0.332	0.302	0.281	0.267	0.255	0.247
2.0	2.702	1.515	0.955	0.764	0.665	0.604	0.563	0.533	0.511	0.493
4.0	5.404	3.030	1.910	1.527	1.329	1.208	1.126	1.066	1.021	0.986
6.0	8.106	4.544	2.866	2.291	1.994	1.812	1.689	1.600	1.532	1.479
8.0	10.807	6.059	3.821	3.054	2.659	2.416	2.252	2.133	2.043	1.972
10.0	13.509	7.574	4.776	3.818	3.324	3.020	2.815	2.666	2.554	2.465

**IEC Curves**

For European applications, the relay offers the four standard curves defined in IEC 255-4 and British standard BS142. These are defined as IEC Curve A, IEC Curve B, IEC Curve C, and Short Inverse. The formulae for these curves are:

$$T = M \times \left( \frac{K}{(I/I_{pu})^E - 1} \right)$$

where: T = trip time (seconds), M = multiplier setpoint, I = input current, I<sub>pu</sub> = pickup current setpoint, K, E = constants.

**Table 5: IEC (BS) Inverse Time Curve Constants**

IEC (BS) Curve Shape	K	E
IEC Curve A (BS142)	0.140	0.020
IEC Curve B (BS142)	13.500	1.000
IEC Curve C (BS142)	80.000	2.000
IEC Short Inverse	0.050	0.040

**Table 6: IEC Curve Trip Times (in seconds)**

Multiplier (TDM)	Current (I/Ipickup)									
	1.5	2.0	3.0	4.0	5.0	6.0	7.0	8.0	9.0	10.0
IEC Curve A										
0.05	0.860	0.501	0.315	0.249	0.214	0.192	0.176	0.165	0.156	0.149
0.10	1.719	1.003	0.630	0.498	0.428	0.384	0.353	0.330	0.312	0.297
0.20	3.439	2.006	1.260	0.996	0.856	0.767	0.706	0.659	0.623	0.594
0.40	6.878	4.012	2.521	1.992	1.712	1.535	1.411	1.319	1.247	1.188
0.60	10.317	6.017	3.781	2.988	2.568	2.302	2.117	1.978	1.870	1.782
0.80	13.755	8.023	5.042	3.984	3.424	3.070	2.822	2.637	2.493	2.376
1.00	17.194	10.029	6.302	4.980	4.280	3.837	3.528	3.297	3.116	2.971
IEC Curve B										
0.05	1.350	0.675	0.338	0.225	0.169	0.135	0.113	0.096	0.084	0.075
0.10	2.700	1.350	0.675	0.450	0.338	0.270	0.225	0.193	0.169	0.150
0.20	5.400	2.700	1.350	0.900	0.675	0.540	0.450	0.386	0.338	0.300
0.40	10.800	5.400	2.700	1.800	1.350	1.080	0.900	0.771	0.675	0.600
0.60	16.200	8.100	4.050	2.700	2.025	1.620	1.350	1.157	1.013	0.900
0.80	21.600	10.800	5.400	3.600	2.700	2.160	1.800	1.543	1.350	1.200
1.00	27.000	13.500	6.750	4.500	3.375	2.700	2.250	1.929	1.688	1.500
IEC Curve C										
0.05	3.200	1.333	0.500	0.267	0.167	0.114	0.083	0.063	0.050	0.040

Multiplier (TDM)	Current (I/I <sub>pickup</sub> )									
	1.5	2.0	3.0	4.0	5.0	6.0	7.0	8.0	9.0	10.0
0.10	6.400	2.667	1.000	0.533	0.333	0.229	0.167	0.127	0.100	0.081
0.20	12.800	5.333	2.000	1.067	0.667	0.457	0.333	0.254	0.200	0.162
0.40	25.600	10.667	4.000	2.133	1.333	0.914	0.667	0.508	0.400	0.323
0.60	38.400	16.000	6.000	3.200	2.000	1.371	1.000	0.762	0.600	0.485
0.80	51.200	21.333	8.000	4.267	2.667	1.829	1.333	1.016	0.800	0.646
1.00	64.000	26.667	10.000	5.333	3.333	2.286	1.667	1.270	1.000	0.808
IEC Short Time										
0.05	0.153	0.089	0.056	0.044	0.038	0.034	0.031	0.029	0.027	0.026
0.10	0.306	0.178	0.111	0.088	0.075	0.067	0.062	0.058	0.054	0.052
0.20	0.612	0.356	0.223	0.175	0.150	0.135	0.124	0.115	0.109	0.104
0.40	1.223	0.711	0.445	0.351	0.301	0.269	0.247	0.231	0.218	0.207
0.60	1.835	1.067	0.668	0.526	0.451	0.404	0.371	0.346	0.327	0.311
0.80	2.446	1.423	0.890	0.702	0.602	0.538	0.494	0.461	0.435	0.415
1.00	3.058	1.778	1.113	0.877	0.752	0.673	0.618	0.576	0.544	0.518

### IAC Curves

The curves for the General Electric type IAC relay family are derived from the formulae:

$$T = M \times \left( A + \frac{B}{(I/I_{pu}) - C} + \frac{D}{((I/I_{pu}) - C)^2} + \frac{E}{((I/I_{pu}) - C)^3} \right)$$

where: T = trip time (seconds), M = multiplier setpoint, I = input current, I<sub>pu</sub> = pickup current setpoint, A to E = constants.

**Table 7: GE Type IAC Inverse Curve Constants**

IAC Curve Shape	A	B	C	D	E
IAC Extreme Inverse	0.0040	0.6379	0.6200	1.7872	0.2461
IAC Very Inverse	0.0900	0.7955	0.1000	-1.2885	7.9586
IAC Inverse	0.2078	0.8630	0.8000	-0.4180	0.1947
IAC Short Inverse	0.0428	0.0609	0.6200	-0.0010	0.0221

**Table 8: IAC Curve Trip Times**

Multiplier (TDM)										
	1.5	2.0	3.0	4.0	5.0	6.0	7.0	8.0	9.0	10.0
IAC Extremely Inverse										
0.5	1.699	0.749	0.303	0.178	0.123	0.093	0.074	0.062	0.053	0.046
1.0	3.398	1.498	0.606	0.356	0.246	0.186	0.149	0.124	0.106	0.093
2.0	6.796	2.997	1.212	0.711	0.491	0.372	0.298	0.248	0.212	0.185
4.0	13.591	5.993	2.423	1.422	0.983	0.744	0.595	0.495	0.424	0.370
6.0	20.387	8.990	3.635	2.133	1.474	1.115	0.893	0.743	0.636	0.556
8.0	27.183	11.987	4.846	2.844	1.966	1.487	1.191	0.991	0.848	0.741
10.0	33.979	14.983	6.058	3.555	2.457	1.859	1.488	1.239	1.060	0.926
IAC Very Inverse										
0.5	1.451	0.656	0.269	0.172	0.133	0.113	0.101	0.093	0.087	0.083
1.0	2.901	1.312	0.537	0.343	0.266	0.227	0.202	0.186	0.174	0.165
2.0	5.802	2.624	1.075	0.687	0.533	0.453	0.405	0.372	0.349	0.331
4.0	11.605	5.248	2.150	1.374	1.065	0.906	0.810	0.745	0.698	0.662

Multiplier (TDM)										
	1.5	2.0	3.0	4.0	5.0	6.0	7.0	8.0	9.0	10.0
6.0	17.407	7.872	3.225	2.061	1.598	1.359	1.215	1.117	1.046	0.992
8.0	23.209	10.497	4.299	2.747	2.131	1.813	1.620	1.490	1.395	1.323
10.0	29.012	13.121	5.374	3.434	2.663	2.266	2.025	1.862	1.744	1.654
IAC Inverse										
0.5	0.578	0.375	0.266	0.221	0.196	0.180	0.168	0.160	0.154	0.148
1.0	1.155	0.749	0.532	0.443	0.392	0.360	0.337	0.320	0.307	0.297
2.0	2.310	1.499	1.064	0.885	0.784	0.719	0.674	0.640	0.614	0.594
4.0	4.621	2.997	2.128	1.770	1.569	1.439	1.348	1.280	1.229	1.188
6.0	6.931	4.496	3.192	2.656	2.353	2.158	2.022	1.921	1.843	1.781
8.0	9.242	5.995	4.256	3.541	3.138	2.878	2.695	2.561	2.457	2.375
10.0	11.552	7.494	5.320	4.426	3.922	3.597	3.369	3.201	3.072	2.969
IAC Short Inverse										
0.5	0.072	0.047	0.035	0.031	0.028	0.027	0.026	0.026	0.025	0.025
1.0	0.143	0.095	0.070	0.061	0.057	0.054	0.052	0.051	0.050	0.049
2.0	0.286	0.190	0.140	0.123	0.114	0.108	0.105	0.102	0.100	0.099
4.0	0.573	0.379	0.279	0.245	0.228	0.217	0.210	0.204	0.200	0.197
6.0	0.859	0.569	0.419	0.368	0.341	0.325	0.314	0.307	0.301	0.296
8.0	1.145	0.759	0.559	0.490	0.455	0.434	0.419	0.409	0.401	0.394
10.0	1.431	0.948	0.699	0.613	0.569	0.542	0.524	0.511	0.501	0.493

### USER Curves

The relay provides a selection of user definable curve shapes used by the time overcurrent protection. The User curve is programmed by selecting the proper parameters in the formula:

$$T = \frac{A * D}{(V^P - Q)} + B * D + K$$

A, P, Q, B, K - selectable curve parameters within the ranges from the table: D is the Time Dial Multiplier.

User Curve can be used on multiple elements only if the time dial multiplier is the same for each element.

$V = I/I_{PICKUP}$  (TOC setting) is the ratio between the measured current and the pickup setting.

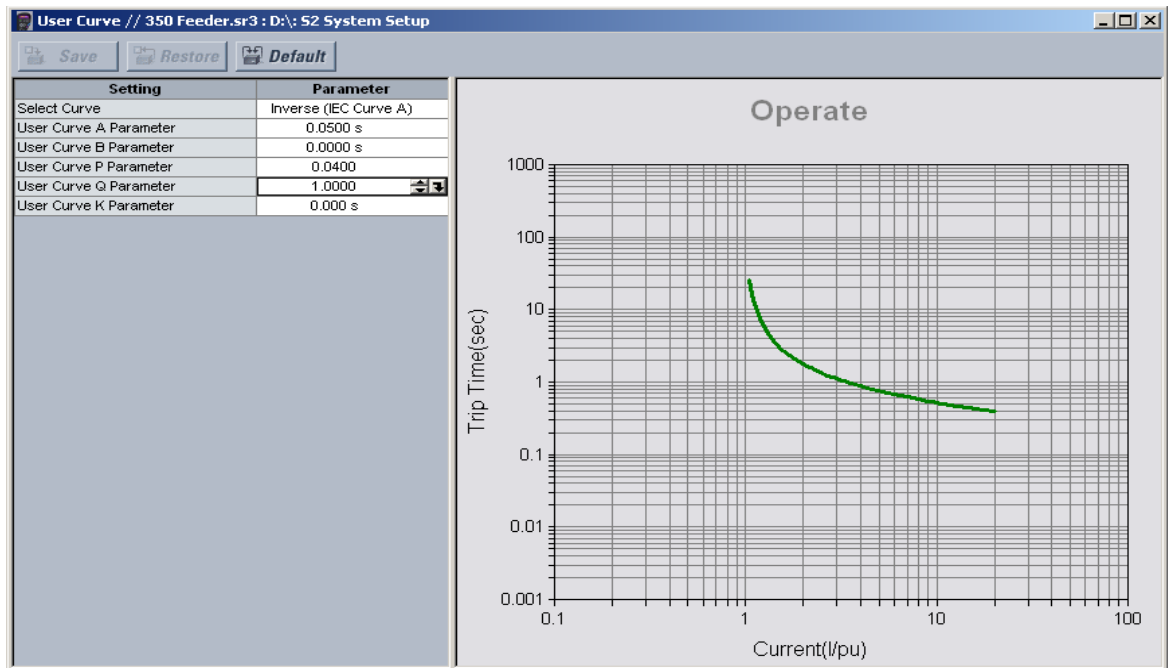
The maximum trip time for the User Curve is limited to 65.535 seconds. The User Curve can be used for one protection situation only.



NOTE

Parameters	A	B	P	Q	K
Range	0 to 125	0 to 3	0 to 3	0 to 2	0 to 1.999
Step	0.0001	0.0001	0.0001	0.0001	0.001
Unit	sec	sec	NA	NA	sec
Default Value	0.05	0	0.04	1.0	0

Figure 6-5: USER curve configuration settings



### Flexcurves

Prospective FlexCurves™ can be configured from a selection of standard curves to provide the best approximate fit, then specific data points can be edited afterwards. Click the **Initialize** button to populate the pickup values with the points from the curve specified by the "Select Curve" setting. These values can then be edited to create a custom curve. Click on the **Clear FlexCurve Data** button to reset all pickup values to zero.

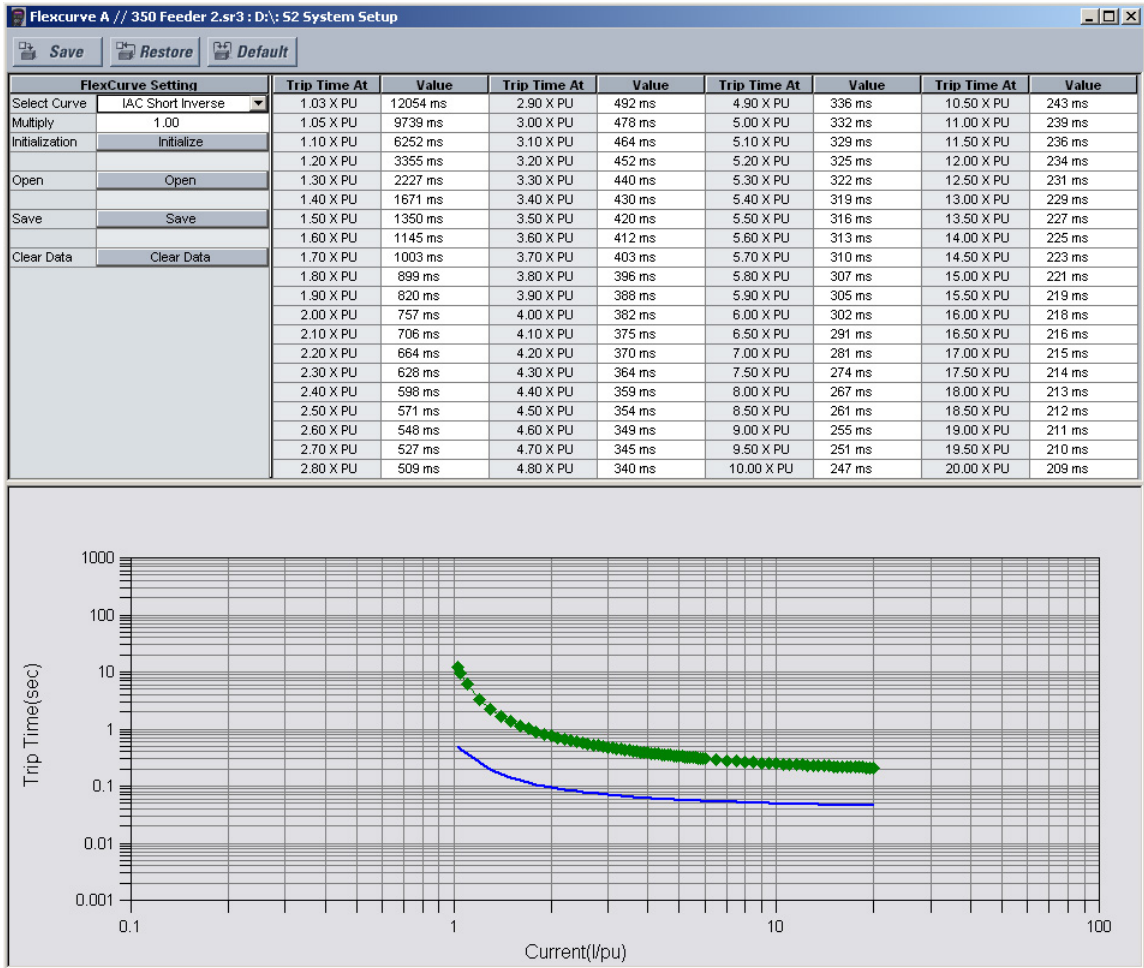
Curve data can be imported from CSV (comma-separated values) files by clicking on the **Open** button. Likewise, curve data can be saved in CSV format by clicking the **Save** button. CSV is a delimited data format with fields separated by the comma character and records separated by new lines. Refer to IETF RFC 4180 for additional details.

The curve shapes for the two FlexCurves are derived from the following equations.

$$T_{operate} = TDM \times \left( T_{flex} \text{ at } \frac{I}{I_{pickup}} \right), \text{ when } \frac{I}{I_{pickup}} \geq 1.00 \quad \text{Eq. 1}$$

In the above equations,  $T_{operate}$  represents the operate time in seconds, TDM represents the multiplier setting,  $I$  represents the input current,  $I_{pickup}$  represents the value of the pickup current setting,  $T_{flex}$  represents the FlexCurve™ time in seconds.

Figure 6-6: Flexcurve™ configuration settings



The following settings are available for each custom Flexcurve™.

**Select Curve**

Range: ANSI Moderately Inverse, ANSI Very Inverse, ANSI Extremely Inverse, IEEE Normally Inverse, IEC Curve A, IEC Curve B, IEC Curve C, IEC Short Inverse, IAC Extreme Inv, IAC Very Inverse, IAC Inverse, IAC Short Inverse, User Curve, FlexCurve B (Note: For FlexCurve A, you can select FlexCurve B as the setpoint, and vice versa for FlexCurve B.)  
 Default: Extremely Inverse

This setting specifies a curve to use as a base for a custom FlexCurve™. Must be used before Initialization is implemented (see **Initialization** below).

**Multiply**

Range: 0.01 to 30.00 in steps of 0.01  
 Default: 1.00

This setting provides selection for Time Dial Multiplier by which the times from the inverse curve are modified. For example if an ANSI Extremely Inverse curve is selected with TDM = 2, and the fault current was 5 times bigger than the PKP level, the operation of the element will not occur before a time elapse of 495 ms from pickup.

### Initialization

Used after specifying a curve to use as a base for a custom FlexCurve™ (see **Select Curve** above). When the **Initialize FlexCurve** button is clicked, the pickup settings will be populated with values specified by the curve selected in this setting.

#### 1.03 × Pickup, ..., 20.00 × Pickup

*Range: 0 to 65535 ms in steps of 1*

*Default: 0 ms*

These settings specify the time to operate at the following pickup levels 1.03 to 20.00. This data is converted into a continuous curve by linear interpolation between data points. To enter a custom FlexCurve™, enter the operate time for each selected pickup point.



NOTE

Each FlexCurve can be configured to provide inverse time characteristic to more than one Time Overcurrent Element. However, for computation of the curve operating times, one must take into account the setting of the Time Delay Multiplier from the FlexCurve menu, and the Time Delay Multiplier setting from TOC menu. The true TDM applied to the TOC element when FlexCurve is selected is the result from the multiplication of both TDM settings. For example, for FlexCurve Multiplier = 5, and Phase TOC Multiplier = 2, the total Time Dial Multiplier will be equal to 10. To avoid confusion, it is suggested to keep the FlexCurve Multiplier equal 1, and set the multipliers from the enabled TOC elements to the desired values.

### 6.4.1.2 Phase timed overcurrent protection

The relay has one Phase Time Overcurrent protection element per protection group. The settings of this function are applied to each of the three phases to produce trip or pickup per phase. The TOC pickup flag is asserted, when the current on any phase is above the PKP value. The TOC trip flag is asserted if the element stays picked up for the time defined by the selected inverse curve and the magnitude of the current. The element drops from pickup without operation, if the measured current drops below 97-98% of the pickup value, before the time for operation is reached. When Definite Time is selected, the time for TOC operation is defined only by the TDM setting.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > S3 PROTECTION > SETPOINT GROUP 1(2) > PHASE TOC**

#### PH TOC FUNCTION

*Range: Disabled, Latched Alarm, Alarm, Trip*

*Default: Disabled*

The selection of the Latched Alarm, Alarm, or Trip setting enables the Phase TOC function. The output relay #1 "Trip" will operate when the Trip setting is selected, and the Phase TOC operates. The "ALARM" LED will not turn on if the TOC operates when set to function Trip. The "ALARM" LED will flash upon phase TOC operation, with the TOC function selected as Alarm, and will self-reset, when the operation clears. If Latched Alarm is selected as a TOC function, the "ALARM" LED will flash during TOC operation, and will stay "ON" after the operation clears until the reset command is initiated. The output relay #1 "Trip" will not operate if the Latched Alarm or Alarm setting is selected.

#### PH TOC PKP

*Range: 0.04 to 20.00 × CT in steps of 0.01 × CT*

*Default: 1.00 × CT*

This setting sets the time overcurrent pickup level. For example, a PKP setting of 0.9 × CT with 300:5 CT translates into 270A primary current.

**PH TOC CURVE**

*Range: ANSI Extremely/Very/Moderately/Normally Inverse, Definite Time, IEC Curve A/B/C and Short Inverse, IAC Extremely/Very/Inverse/Short, User Curve, FlexCurve A, FlexCurve B*  
*Default: Extremely Inverse*

This setting sets the shape of the selected TOC inverse curve. If none of the standard curve shapes is appropriate, a custom User curve, or FlexCurve can be created. Refer to the User curve and the FlexCurve setup for more detail on their configurations and usage.

**PH TOC TDM**

*Range: 0.50 to 20.00 in steps of 0.01*  
*Default: 1.00*

This setting provides selection for Time Dial Multiplier by which the times from the inverse curve are modified. For example if an ANSI Extremely Inverse curve is selected with TDM = 2, and the fault current was 5 times bigger than the PKP level, the operation of the element will not occur before an elapsed time from pickup, of 495 ms.

**PH TOC RESET**

*Range: Instantaneous, Linear*  
*Default: Instantaneous*

The “Instantaneous” reset method is intended for applications with other relays, such as most static relays, which set the energy capacity directly to zero when the current falls below the reset threshold. The “Timed” reset method can be used where the relay must coordinate with electromechanical relays.

**OUTPUT RELAY 3 to 6**

*Range: Do not operate, Operate*  
*Default: Do not operate*

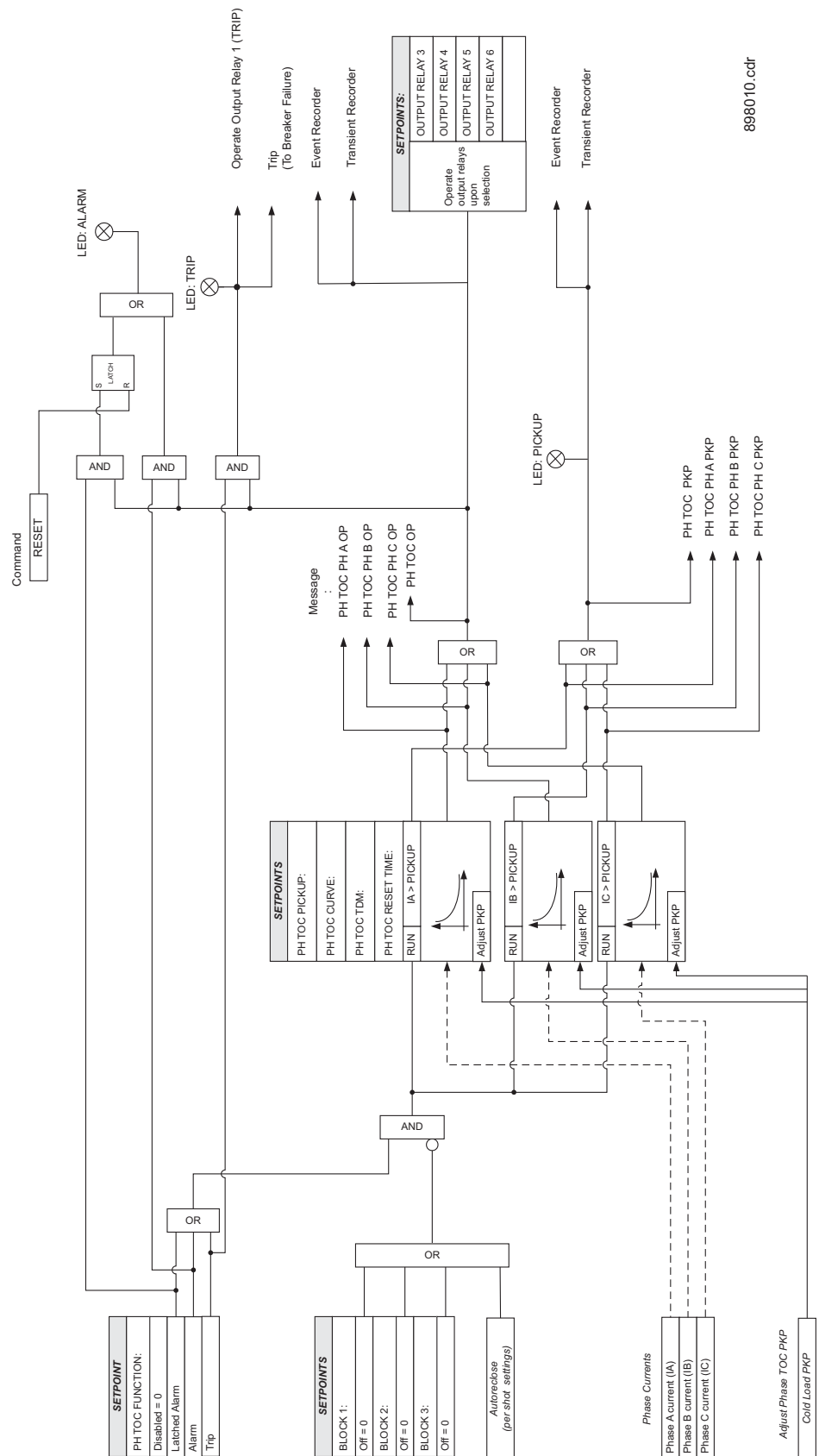
Any, or all of the output relays 3 to 6 can be selected to operate, upon phase TOC operation. The selection of relay outputs operation is available no matter whether Latched Alarm, Alarm, or Trip function is selected.

**BLOCK 1/2/3**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*  
*Default: Off*

Three blocking inputs are provided in the Phase TOC menu. When any of the selected blocking inputs - Contact input, Virtual Input, Remote Input, or Logic Element - turns on, the phase TOC function will be blocked.

Figure 6-7: Phase Time Overcurrent Protection logic diagram



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### 6.4.1.3 Phase instantaneous overcurrent protection

The 350 relay has two identical phase instantaneous overcurrent protection types per Setpoint Group: Phase IOC1, and Phase IOC2. Each consists of three separate instantaneous overcurrent elements; one per phase, with identical settings.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH:** SETPOINTS > S3 PROTECTION > SETPOINT GROUP 1(2) > PHASE IOC1(2)

#### PH IOC1/2 FUNCTION

*Range: Disabled, Latched Alarm, Alarm, Trip*

*Default: Disabled*

The selection of the Latched Alarm, Alarm, or Trip setting enables the Phase IOC function. The output relay #1 "Trip" will operate when the Trip function is selected, and the Phase IOC operates. The "ALARM" LED will not turn on if the IOC operates when set to function Trip. The "ALARM" LED will flash upon phase IOC operation, and with the IOC function selected as Alarm, will self-reset when the operation clears. If Latched Alarm is selected, the "ALARM" LED will flash during IOC operation, and will stay "ON" after the operation clears, until the Reset command is initiated. The output relay #1 "Trip" will not operate if the Latched Alarm or Alarm function is selected.

#### PH IOC1/2 PKP

*Range: 0.05 to 20.00 x CT in steps of 0.01 x CT*

*Default: 1.00 x CT*

This setting sets the instantaneous overcurrent pickup level. For example, a PKP setting of 0.9 x CT with 300:5 CT translates into 270A primary current.

#### PH IOC1/2 DELAY

*Range: 0.00 to 300.00 sec in steps of 0.01 sec*

*Default: 0.00 sec*

This setting provides selection for the time used to delay the protection operation.

#### OUTPUT RELAY 3 to 6

*Range: Do not operate, Operate*

*Default: Do not operate*

Any or all of the output relays 3 to 6 can be selected to operate upon phase IOC operation. Relay outputs operation is available no matter whether Latched Alarm, Alarm, or Trip function is selected.

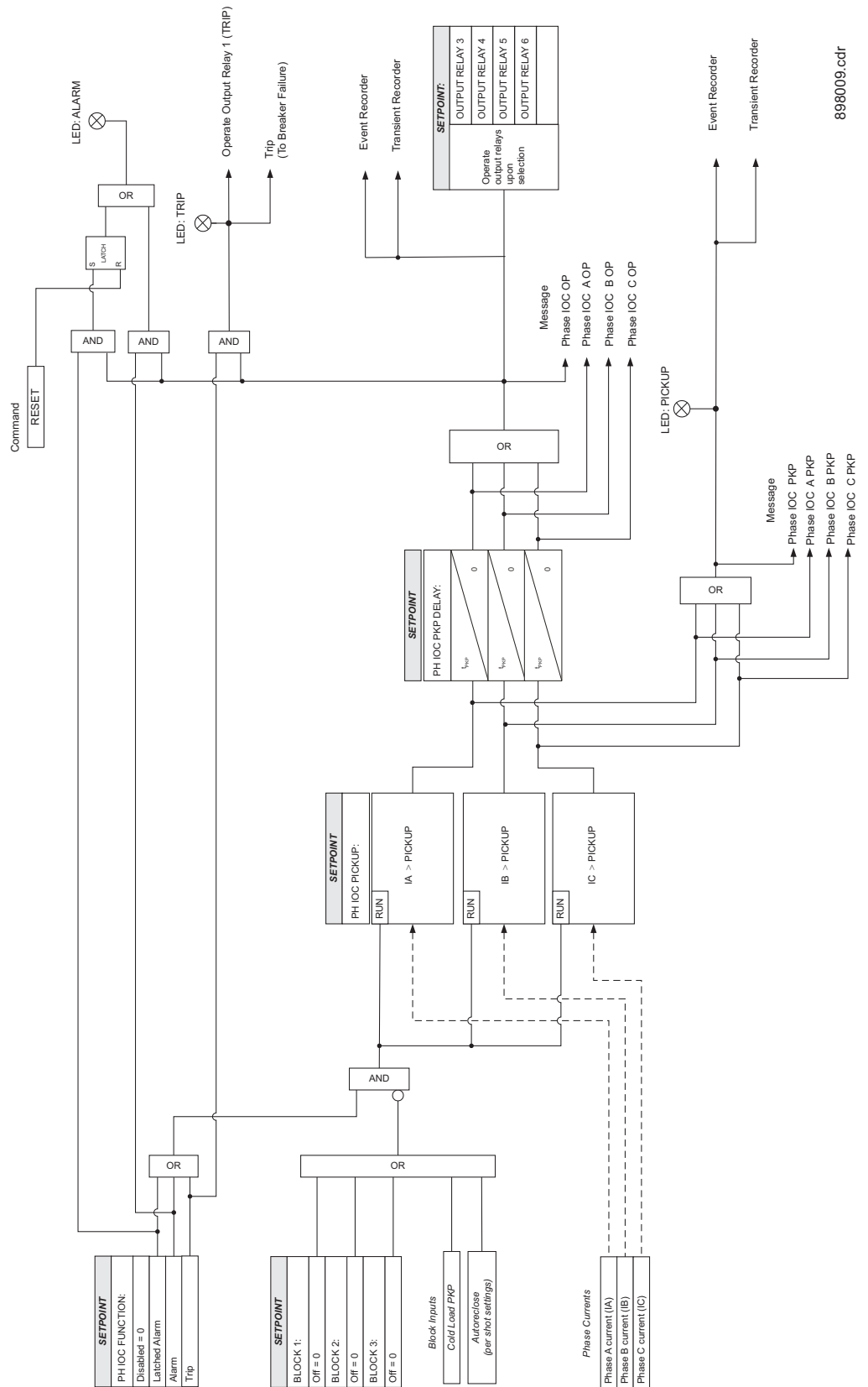
#### BLOCK 1/2/3

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*

*Default: Off*

Three blocking inputs are provided in the Phase IOC menu. When any one of the selected blocking inputs - Contact input, Virtual Input, Remote Input, or Logic Element - is turned on, the phase IOC function will be blocked.

Figure 6-8: Phase Instantaneous Overcurrent Protection logic diagram



#### 6.4.1.4 Ground/Sensitive Ground timed overcurrent protection

The relay has one Ground Time Overcurrent protection per setpoint group. The settings of this function are applied to the ground input current to produce trip or pickup flags. The Ground TOC pickup flag is asserted, when the ground current is above the PKP value. The Ground TOC operate flag is asserted if the element stays picked up for the time defined by the selected inverse curve, and the magnitude of the current. The element drops from pickup without operation if the measured current drops below 97 to 98% of the pickup value, before the time to operate is reached. When Definite Time is selected, the time for Ground TOC operation is defined only by the TDM setting.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > S3 PROTECTION > SETPOINT GROUP 1(2) > GROUND TOC**



The settings from the menu for Sensitive Ground TOC, appears only upon selection of the Sensitive Ground CT when ordering the relay. Otherwise, the relay displays the menu for Ground TOC protection.

##### **GND TOC FUNCTION**

*Range: Disabled, Trip, Alarm, Latched Alarm*

*Default: Disabled*

The selection of the Latched Alarm, Alarm, or Trip setting enables the Ground/Sensitive Ground TOC function. The output relay #1 "Trip" will operate, if the Ground/Sensitive Ground TOC function is selected as Trip, and the measured ground current satisfies the operating condition set by the settings. The "ALARM" LED will not turn on if the TOC operates when set to the Trip function. The "ALARM" LED will flash upon phase TOC operation, with the TOC function selected as Alarm, and will self-reset, when this operation clears. If Latched Alarm is selected as the TOC function, the "ALARM" LED will flash during TOC operation, and will stay "ON" after the condition clears, until the reset command is initiated. The output relay #1 "Trip" will not operate if the Latched Alarm or Alarm function is selected. Any or all of output relays 3 to 6 can be selected to operate when the Ground TOC function is selected as Latched Alarm, Alarm, or Trip.

##### **GND TOC PKP**

*Range: 0.04 to 20.00 x CT in steps of 0.01 x CT*

*Default: 1.00 x CT*

##### **SENS.GND TOC PKP**

*Range: 0.005 to 3.00 x CT in steps of 0.001 x CT*

*Default: 1.00 x CT*

This setting sets the time overcurrent pickup level. For example, a PKP setting of 0.9 x CT with 300:5 CT translates into 270A primary current.

##### **GND TOC CURVE**

*Range: ANSI Extremely/Very/Moderately/Normally Inverse, Definite Time, IEC Curve A/B/C and Short Inverse, IAC Extremely/Very/Inverse/Short, User Curve, FlexCurve A, FlexCurve B*  
*Default: Extremely Inverse*

This setting sets the shape of the selected over-current inverse curve. If none of the standard curve shapes is appropriate, a custom User curve, or FlexCurve can be created. Refer to the User curve and the FlexCurve setup for more detail on their configurations and usage.

**GND TOC TDM**

*Range: 0.50 to 20.00 in steps of 0.01*

*Default: 1.0*

This setting provides selection for Time Dial Multiplier by which the times from the inverse curve are modified. For example if an ANSI Extremely Inverse curve is selected with TDM = 2, and the fault current was 5 times bigger than the PKP level, the operation of the element will not occur before an elapsed time from pickup, of 495 ms.

**GND TOC RESET**

*Range: Instantaneous, Linear*

*Default: Instantaneous*

The “Instantaneous” reset method is intended for applications with other relays, such as most static relays, which set the energy capacity directly to zero when the current falls below the reset threshold. The “Timed” reset method can be used where the relay must coordinate with electromechanical relays.

**OUTPUT RELAY 3 to 6**

*Range: Do not operate, Operate*

*Default: Do not operate*

Any or all of the output relays 3 to 6 can be selected to operate upon ground TOC operation. The selection of relay outputs operation is available no matter whether Latched Alarm, Alarm, or Trip function is selected.

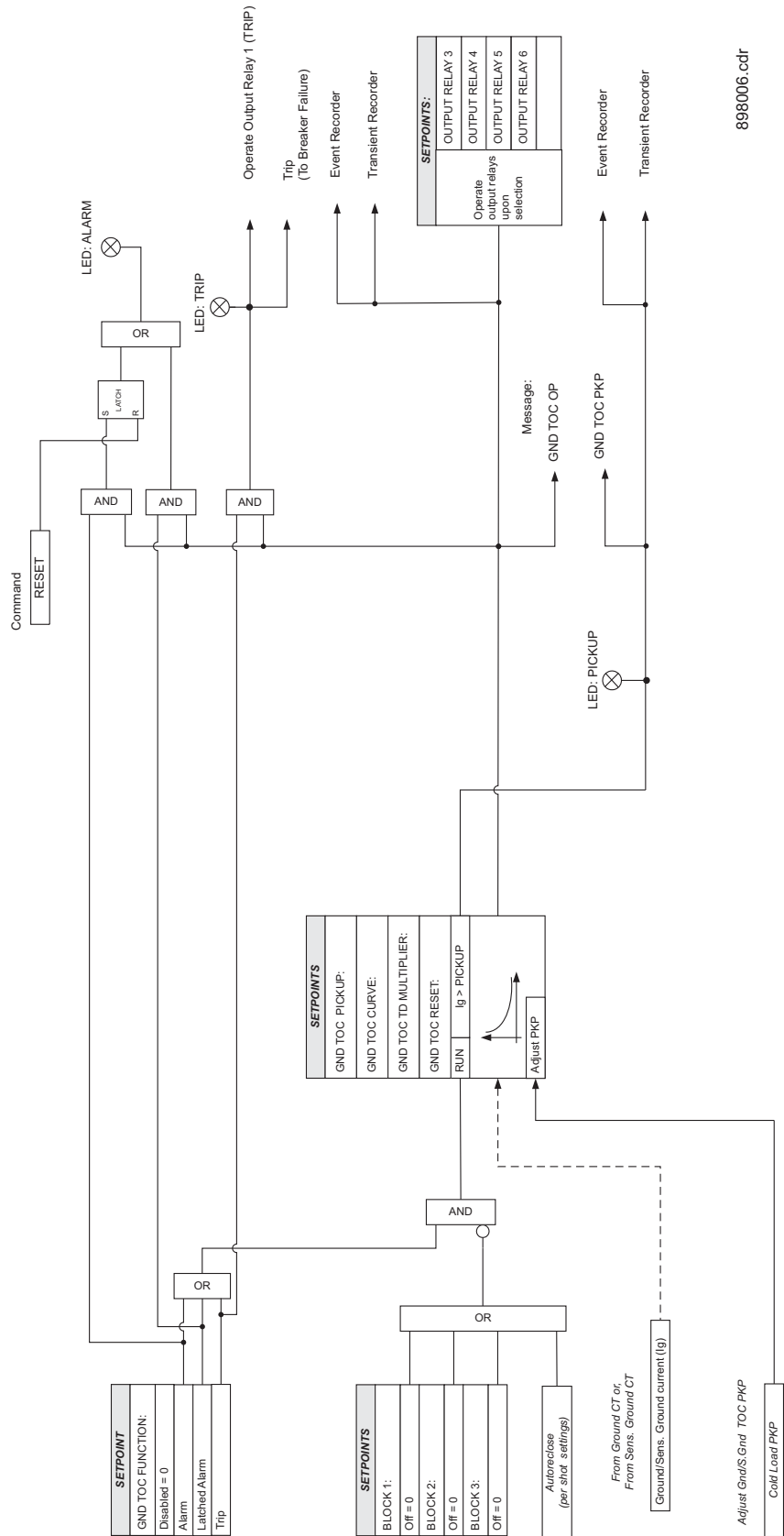
**BLOCK 1/2/3**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*

*Default: Off*

Three blocking inputs are provided in the Ground TOC menu. When any of the selected blocking inputs - Contact input, Virtual Input, Remote Input, or Logic Element - turn on, the ground TOC function is blocked.

Figure 6-9: Ground/Sensitive Ground timed overcurrent protection: Logic Diagram



### 6.4.1.5 Ground/Sensitive Ground instantaneous overcurrent protection

The relay has one Ground/Sensitive Ground Instantaneous Overcurrent protection element per setpoint group. The settings of these functions are applied to the ground/sensitive ground current for pickup and trip flags. The Ground IOC pickup flag is asserted, when the ground current is above the PKP value. The Ground IOC operate flag is asserted if the element stays picked up for the time defined by the Ground IOC PKP Delay setting. If the pickup time delay is set to 0.00 seconds, the pickup and operate flags will be asserted at the same time. The element drops from pickup without operation, if the ground current drops below 97-99% of the pickup value.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > S3 PROTECTION > SETPOINT GROUP 1(2) > GROUND IOC1(2)**

#### **GND IOC FUNCTION**

*Range: Disabled, Trip, Alarm, Latched Alarm*

*Default: Disabled*

The selection of the Latched Alarm, Alarm, or Trip setting enables the Ground/Sensitive Ground IOC function. The output relay #1 "Trip" will operate, if the Ground/Sensitive Ground IOC function is selected as Trip, and the measured ground current satisfies the operating condition set by the settings. The "ALARM" LED will not turn on if the element operates when set to function Trip. The "ALARM" LED will flash upon IOC operation, with the IOC function selected as Alarm, and will self-reset, when this operation clears. If Latched Alarm is selected as an IOC function, the "ALARM" LED will flash during the IOC operating condition, and will stay "ON" after the condition clears, until a reset command is initiated. The output relay #1 "Trip" will not operate if Latched Alarm or Alarm setting is selected. Any or all of the output relays 3 to 6 can be selected to operate when the Ground/S.Ground IOC function is selected as Latched Alarm, Alarm, or Trip.

#### **GND IOC PKP**

*Range: Disabled, 0.05 to 20.00 x CT in steps of 0.01 x CT*

*Default: 1.00 x CT*

#### **SENS.GND IOC PKP**

*Range: 0.005 to 3.00 x CT in steps of 0.001 x CT*

*Default: 1.00 x CT*

This setting sets the ground overcurrent pickup level specified per times CT. For example, a PKP setting of 0.9 x CT with 300:5 CT translates into 270A primary current.

#### **GND IOC DELAY**

*Range: 0.00 to 300.00 sec in steps of 0.01 sec*

*Default: 0.00 sec*

This setting provides selection for pickup time delay used to delay the operation of the protection.

#### **OUTPUT RELAY 3 to 6**

*Range: Do not operate, Operate*

*Default: Do not operate*

Any, or all, of the output relays 3 to 6 can be selected to operate upon ground IOC operation. The selection of relay outputs operation is available no matter whether Latched Alarm, Alarm, or Trip function is selected.

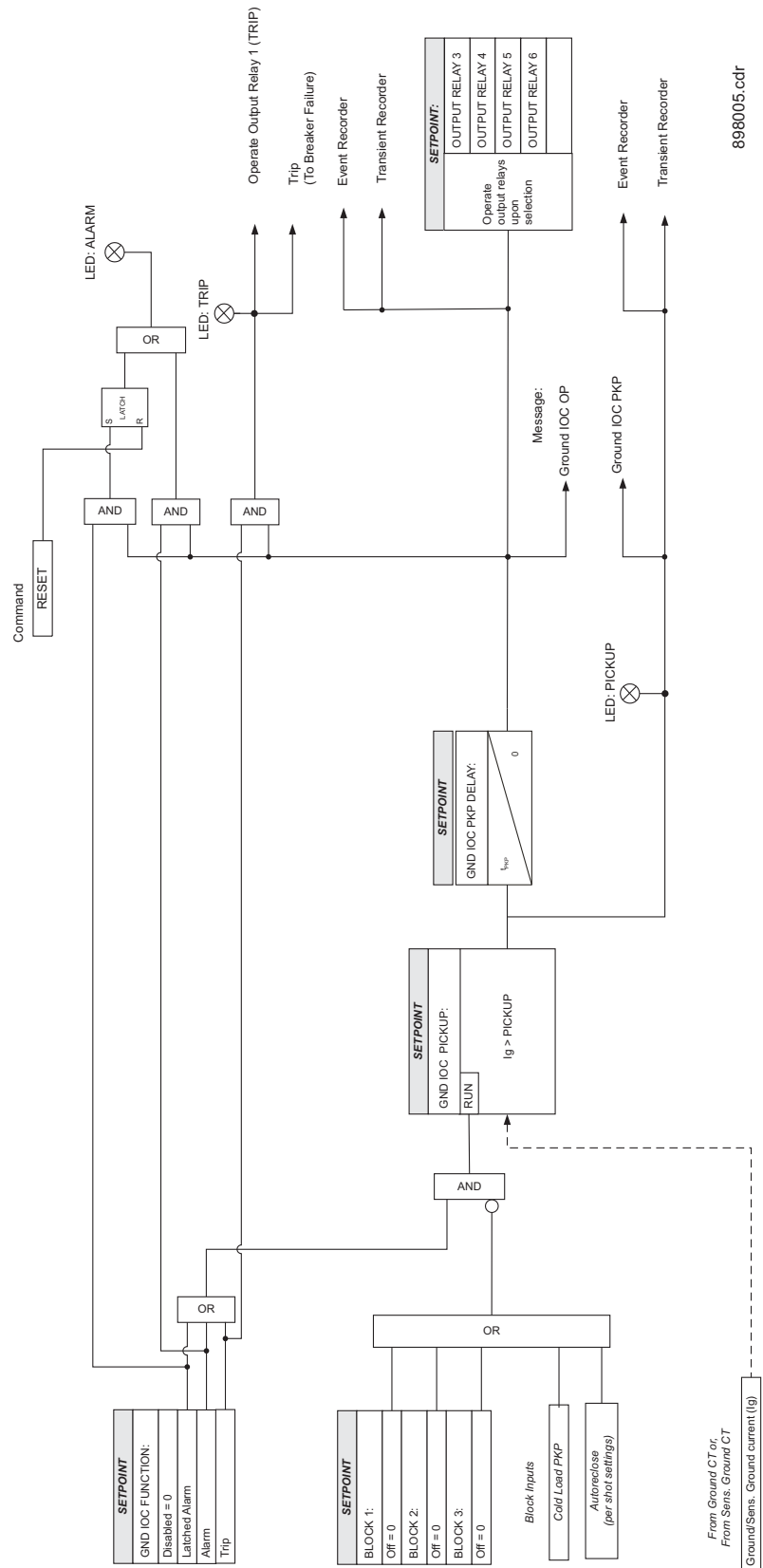
**BLOCK 1/2/3**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Element 1 to 8*

*Default: Off*

Three blocking inputs are provided in the Ground IOC menu. When any of the selected blocking inputs - Contact input, Virtual Input, Remote Input, or Logic Element - turns on, the ground IOC function is blocked.

Figure 6-10: Ground/Sensitive Ground Instantaneous Overcurrent Protection logic diagram



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### 6.4.1.6 Neutral timed overcurrent protection

The relay has one Neutral Time Overcurrent protection element per setpoint group. The settings of this function are applied to the calculated neutral current to produce pickup and trip flags. The Neutral TOC pickup flag is asserted, when the neutral current is above the PKP value. The Neutral TOC operate flag is asserted if the element stays picked up for the time defined by the selected inverse curve and the magnitude of the current. The element drops from pickup without operation, if the neutral current drops below 97-99% of the pickup value, before the time for operation is reached. When Definite Time is selected, the time for Neutral TOC operation is defined only by the TDM setting.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > S3 PROTECTION > SETPOINT GROUP 1(2) > NEUTRAL TOC**

#### **NTRL TOC FUNCTION**

*Range: Disabled, Latched Alarm, Alarm, Trip*

*Default: Disabled*

The selection of the Latched Alarm, Alarm, or Trip setting enables the Neutral TOC function. The output relay #1 "Trip" will operate if the Neutral TOC function is selected as Trip, and the neutral current calculated by the relay satisfies the operating condition set by the settings. The "ALARM" LED will not turn on if the TOC operates when set to function Trip. The "ALARM" LED will flash upon Neutral TOC operating condition with the TOC function selected as Alarm, and will self-reset when the operating condition clears. If Latched Alarm is selected as a TOC function, the "ALARM" LED will flash during TOC operation, and will stay "ON" after the operation clears, until a reset command is initiated. The output relay #1 "Trip" will not operate if Latched Alarm or Alarm setting is selected. Any or all of the output relays 3 to 6 can be selected to operate when the Neutral TOC function is selected as Latched Alarm, Alarm, or Trip.

#### **NTRL TOC PKP**

*Range: 0.05 to 20.00 x CT in steps of 0.01 x CT*

*Default: 1.00 x CT*

This setting sets the time overcurrent pickup level. For example, a PKP setting of 0.9 x CT with 300:5 CT translates into 270A neutral current.

#### **NTRL TOC CURVE**

*Range: ANSI Extremely/Very/Moderately/Normally Inverse, Definite Time, IEC Curve A/B/C and Short Inverse, IAC Extremely/Very/Inverse/Short, User Curve, FlexCurve A, FlexCurve B*

*Default: Extremely Inverse*

This setting sets the shape of the selected over-current inverse curve. If none of the standard curve shapes is appropriate, a custom User curve, or FlexCurve can be created. Refer to the User curve and the FlexCurve setup for more detail on their configurations and usage.

#### **NTRL TOC TDM**

*Range: 0.50 to 20.00 in steps of 0.01*

*Default: 1.00*

This setting provides selection for Time Dial Multiplier by which the times from the selected inverse curve are modified. For example if an ANSI Extremely Inverse curve is selected with TDM = 2, and the fault current was 5 times bigger than the PKP level, operation of the element will not occur before an elapse of 495 ms from pickup.

**NTRL TOC RESET**

*Range: Instantaneous, Linear*

*Default: Instantaneous*

The “Instantaneous” reset method is intended for applications with other relays, such as most static relays, which set the energy capacity directly to zero when the current falls below the reset threshold. The “Timed” reset method can be used where the relay must coordinate with electromechanical relays.

**OUTPUT RELAY 3 to 6**

*Range: Do not operate, Operate*

*Default: Do not operate*

Any, or all of the output relays 3 to 6 can be selected to operate, upon Neutral TOC operation. The selection of relay outputs operation is available no matter whether Latched Alarm, Alarm, or Trip function is selected.

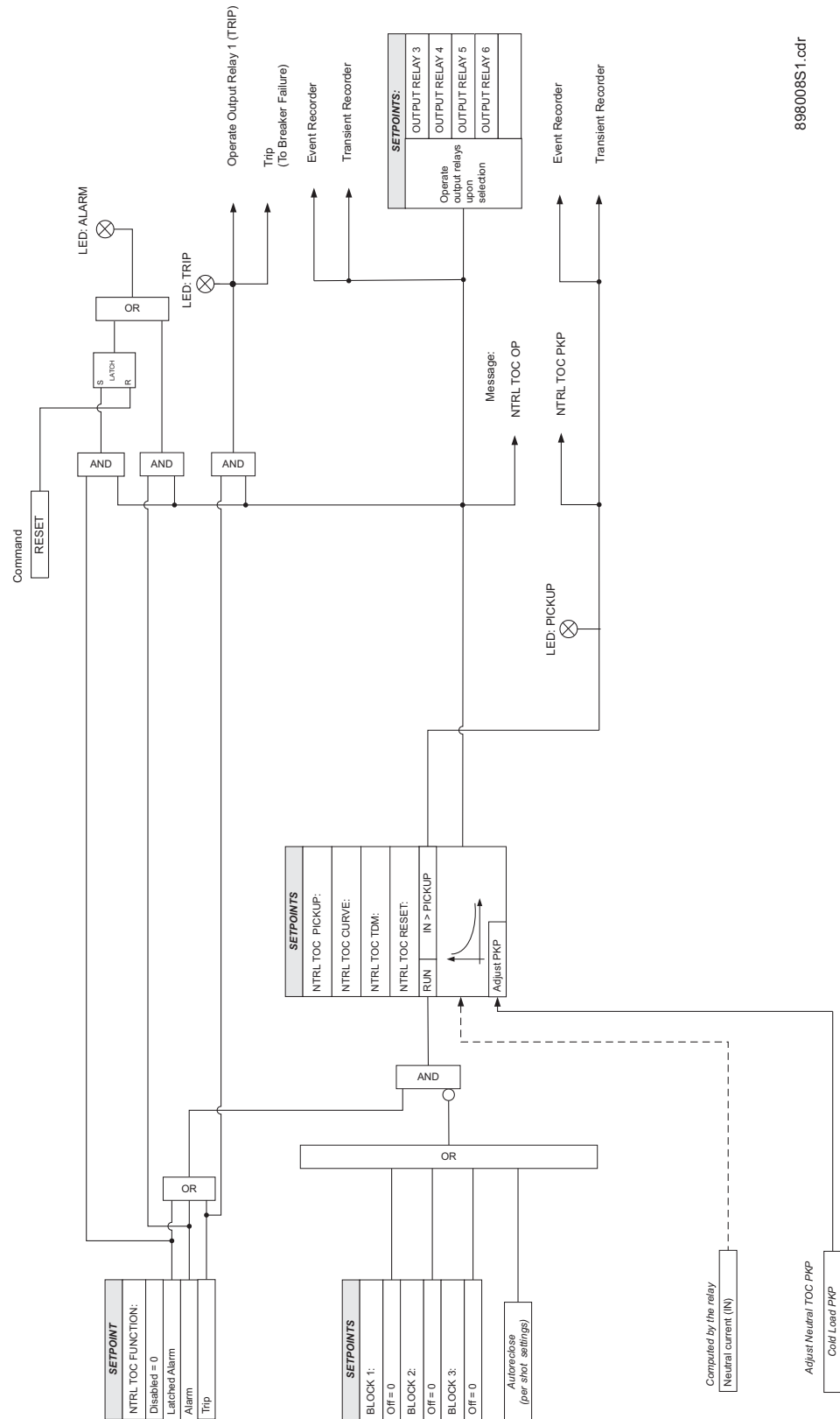
**BLOCK 1/2/3**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Element 1 to 8*

*Default: Off*

There are three blocking inputs provided in the Neutral TOC menu. One blocking input going “high” is enough to block the function. The selection for each block can include Contact input, Virtual Input, Remote Input, or Logic Element.

Figure 6-11: Neutral Timed Overcurrent Protection logic diagram



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### 6.4.1.7 Neutral instantaneous overcurrent protection

The relay has two Instantaneous Overcurrent protection elements per setpoint group. The settings of this function are applied to the calculated neutral current for pickup and trip flags. The Neutral IOC pickup flag is asserted, when the neutral current is above the PKP value. The Neutral IOC operate flag is asserted if the element stays picked up for the time defined by the Neutral IOC Delay setting. If the pickup time delay is set to 0.00 seconds, the pickup and operate flags will be asserted at the same time. The element drops from pickup without operation, if the neutral current drops below 97-99% of the pickup value before the time for operation is reached.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > PROTECTION > SETPOINT GROUP 1 (2) > NEUTRAL IOC1(2)**

#### **NTRL IOC1 (2) FUNCTION**

*Range: Disabled, Latched Alarm, Alarm, Trip*

*Default: Disabled*

The selection of the Latched Alarm, Alarm, or Trip setting enables the Neutral IOC function. The output relay #1 "Trip" will operate if the Neutral IOC function is selected as Trip, and the neutral current calculated by the relay satisfies the operating condition set by the settings. The "ALARM" LED will not turn on if the neutral IOC operates when set to function Trip. The "ALARM" LED will flash upon Neutral IOC operation with the IOC function selected as Alarm and will self-reset when this operation clears. If Latched Alarm is selected as an IOC function, the "ALARM" LED will flash during IOC operation and will stay "ON" after the operating condition clears, until the reset command is initiated. The output relay #1 "Trip" will not operate if the Latched Alarm or Alarm setting is selected. Any or all of the output relays 3 to 6 can be selected to operate when the Neutral IOC function - Latched Alarm, Alarm, or Trip - is selected.

#### **NTRL IOC PKP**

*Range: 0.05 to 20 x CT in steps of 0.01 x CT*

*Default: 1.00 x CT*

This setting sets the neutral instantaneous overcurrent pickup level.

#### **NTRL IOC DELAY**

*Range: 0.00 to 300 sec in steps of 0.01 sec*

*Default: 0.00 sec*

This setting sets the neutral instantaneous overcurrent delay.

#### **NTRL IOC DIRECTION**

*Range: Disabled, Forward, Reverse*

*Default: Disabled*

This setting provides control to the Neutral IOC1(2) function in terms of permitting operation upon fault conditions in the selected current flow direction, and blocking it when faults occur in the opposite direction.

#### **OUTPUT RELAY 3 to 6**

*Range: Do Not Operate, Operate*

*Default: Do Not Operate*

Any or all of the output relays 3 to 6 can be selected to operate upon the Neutral IOC condition. Relay outputs operation is available no matter whether the **Latched Alarm**, **Alarm**, or **Trip** function is selected.

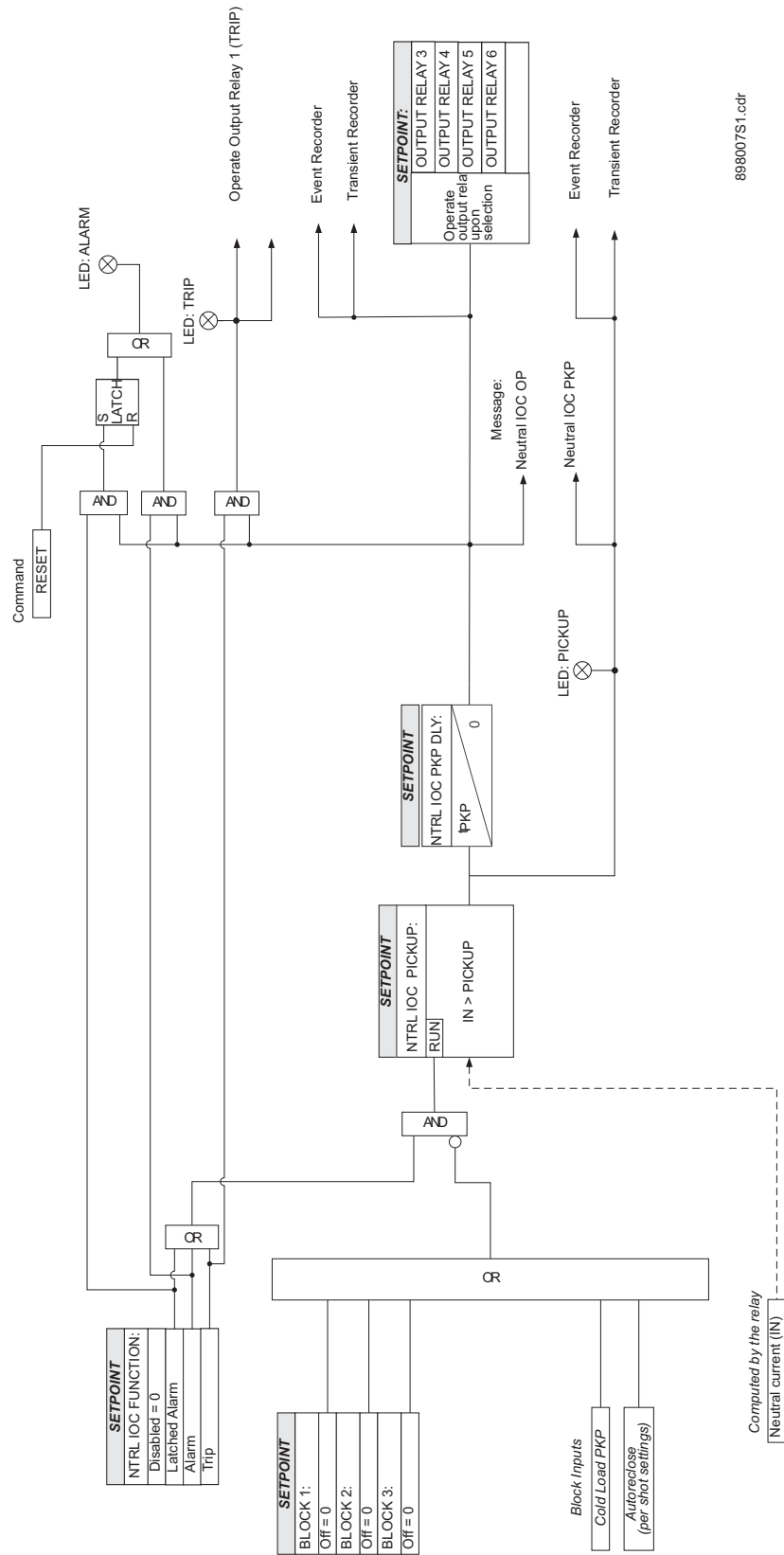
**BLOCK 1/2/3**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Element 1 to 8*

*Default: Off*

Three blocking inputs are provided in the Neutral IOC menu. One blocking input going “high” is enough to block the function. The selection for each block can be Contact input, Virtual Input, Remote Input, or Logic Element.

Figure 6-12: Neutral Instantaneous Overcurrent Protection logic diagram



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## 6.4.2 Cable Thermal Model

The thermal overload protection (Thermal Model) can be applied to prevent damage to the protected cables, dry transformers, capacitor banks, or even overhead lines. Loads exceeding the load ratings of the protected equipment can, over time, degrade the insulation, and may, in return, lead to short circuit conditions. As the heating of plant equipment such as cables or transformers is resistive ( $I^2R$ ), the generated heat is directly proportional to the square of the flowing current ( $I^2$ ). The relay uses a thermal time characteristic based on current squared and integrated over time.

The relay will continuously calculate the thermal capacity as a percentage of the total thermal capacity. The thermal capacity is calculated as follows:

$$\theta(t) = \left[ \theta(t-1) + \frac{\Delta t}{\tau} \left[ I^2 - \theta(t-1) \right] \right]$$

Where:

$\theta(t)$  = Cable thermal capacity (%) at time  $t$

$\theta(t-1)$  = Cable thermal capacity (%) at time  $t-1$

$\Delta t/\tau$  = Time step  $\Delta t$  divided by the heating/cooling time constant  $\tau$

$I^2 = (I_{phase}/I_{pickup})^2$  = Squared ratio between the actual load current and the pickup setting

$\tau$  = Heating and cooling time constant, usually provided by the manufacturer.

The heating time constant is used when the squared load/pickup ratio is greater than the thermal capacity  $\theta(t-1)$  estimated in the previous time step. Otherwise the formula uses the cooling time constant.

The time to trip is estimated when the load current exceeds the PKP setting, and the 49 element picks up. At the same time the thermal capacity will start to increase at a rate depending on the current amplitude and the prior loading condition of the cable. When the thermal capacity exceeds the alarm level, the element will generate an alarm signal. The thermal model alarm can be used as a warning for the start of dangerous overloading conditions, and can prevent unnecessary tripping. When the thermal capacity exceeds the trip level, the element will generate a trip signal. As per the formula below, the operate time (time to trip) is determined from when the element picks up until it trips, and depends on both the measured load over time, and the equipment heating and cooling time constants.

$$T_{TRIP} = \tau * \ln \left( \frac{I^2}{I^2 - \theta^2} \right)$$

Where:

$T_{TRIP}$  = Time to trip in seconds

$\theta^2 = 1$  = Trip thermal state set to 100%

$\tau$  = Heating and cooling time constant, usually provided by the manufacturer.

$I^2$  = Squared ratio of the actual phase current and the pickup setting.

The time to trip will start timing out once the level of the computed thermal capacity (%) becomes higher than 100 % thermal capacity ( $\theta=1$ ). The trip flag will dropout when the Thermal capacity falls below 97% of the pickup level.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > S3 PROTECTION > SETPOINT GROUP 1(2) > THERMAL MODEL****THERMAL MDL FUNC**

*Range: Disabled, Latched Alarm, Alarm, Trip*

*Default: Disabled*

The thermal capacity will be displayed on the relay even if the Thermal Model Function is set to "Disabled. The output relay #1 "Trip" will operate only if the function is selected as a Trip and the thermal capacity value of any phase is over 100%. The LED "ALARM" will turn on when the function is selected as a Trip or Alarm if the thermal capacity value of any phase is over the Thermal MDL Alarm setting. This LED will turn off when the thermal capacity value of all phases is below 97% of the Thermal MDL Alarm setting. If Latched Alarm is selected as a function setting, the LED "ALARM" will flash if the thermal capacity value of any phase is over the Thermal MDL Alarm setting, and will stay "ON" when the thermal capacity value of all phases is below 97% of the Thermal MDL Alarm setting, until the reset command is initiated. The output relay #1 "Trip" will not operate if the Latched Alarm or Alarm setting is selected. Any of the output relays 3 to 6 can be selected to operate when the Thermal Model Function is selected as Latched Alarm, Alarm or Trip.

The thermal capacity values are stored in memory and can be cleared either by using the "Clear Thermal Capacity" command, or by cycling relay control power.

**THERMAL MDL PKP**

*Range: 0.05 to 20 x CT in steps of 0.01 x CT*

*Default: 1.00 x CT*

This setting sets the level of phase current above which the thermal model starts timing out the time-to-trip per the logarithmic formula above.

**THERMAL MDL ALARM**

*Range: 70.0 to 110.0% in steps of 0.1%*

*Default: 80.0%*

This setting sets the alarm level for the accumulated thermal capacity above which the element generates an alarm.

**HEAT TIME CONSTANT ( $\tau_H$ )**

*Range: 3.0 to 600.0 min in steps of 0.1 min*

*Default: 6.0 min*

This time constant is used to compute the thermal capacity when the thermal capacity at each time-step is greater than the one computed in the previous time-step.

**COOL TIME CONSTANT ( $\tau_C$ )**

*Range: 1.00 to 6.00 x  $\tau_H$  in steps of 0.01 x  $\tau_H$*

*Default: 2.00 x  $\tau_H$*

This time constant is used to compute the thermal capacity when the thermal capacity at each time-step is less than the one computed in the previous time-step.

**OUTPUT RELAY 3 to 6**

*Range: Do Not Operate, Operate*

*Default: Do Not Operate*

Any or all of output relays 3 to 6 can be selected to operate upon the Thermal Model condition. The selection of relay outputs operation is available no matter whether the **Latched Alarm, Alarm, or Trip** function is selected.

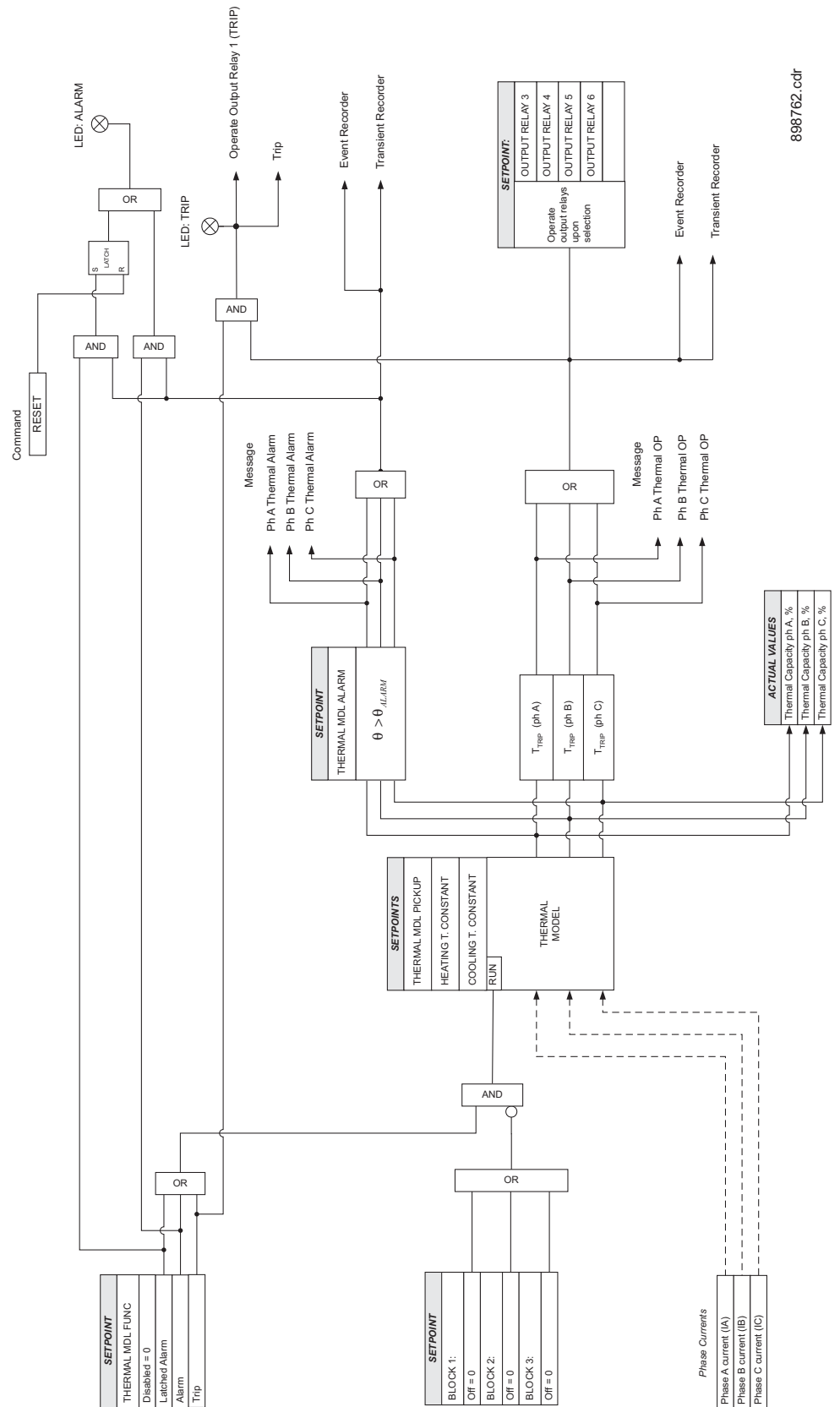
**BLOCK 1/2/3**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Element 1 to 8*

*Default: Off*

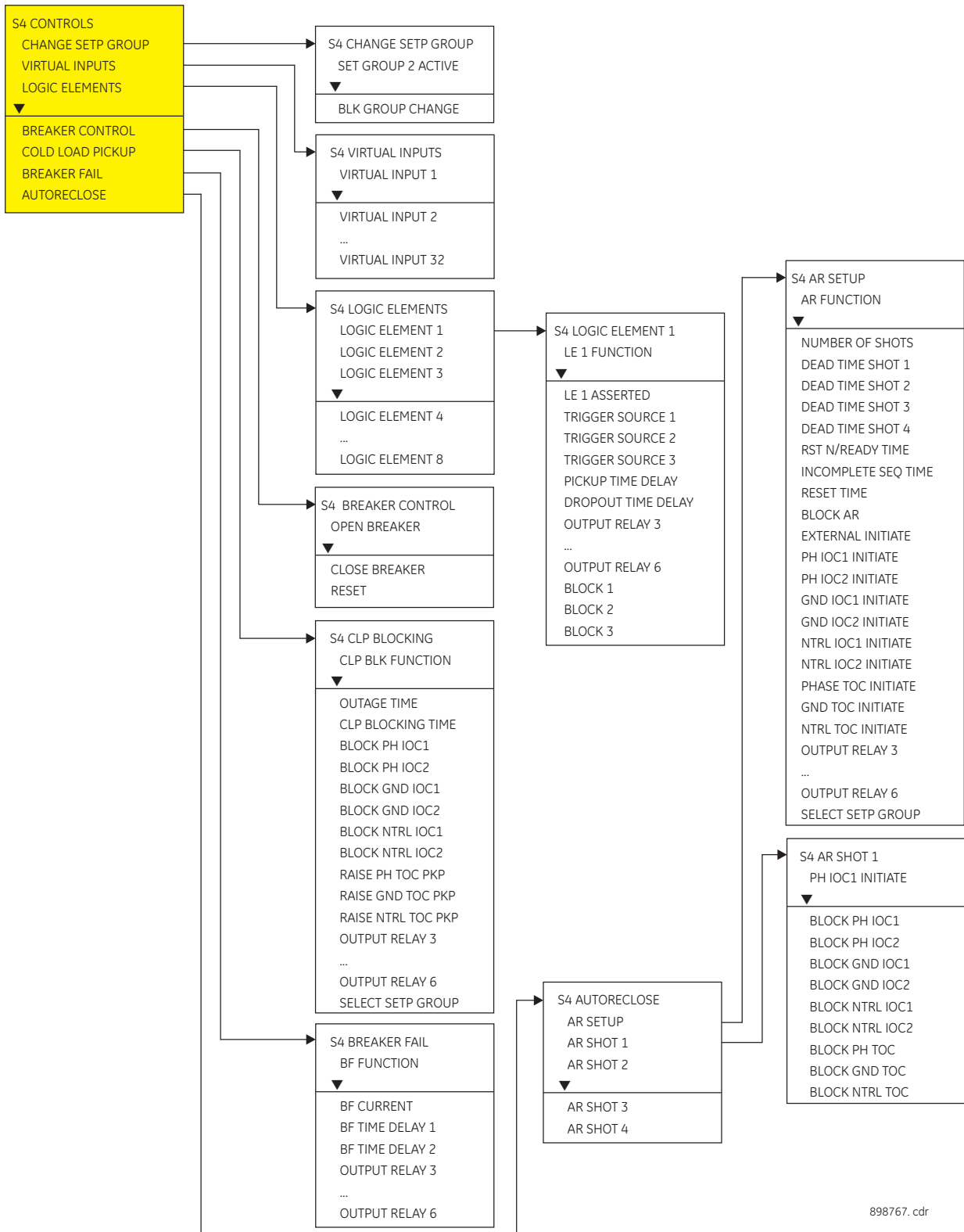
Three blocking inputs are provided in the menu. One blocking input “high” is enough to block the function. The available selections for each block include Contact input, Virtual Input, Remote Input, or Logic Element.

Figure 6-13: Thermal Model Protection logic diagram



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## 6.5 S4 Control



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## 6.5.1 Change setpoint group

The 350 relay has two identical setpoint groups- Group 1 and Group 2 for all protection elements. Switching between these two groups is available automatically by assigning an input (contact, virtual, remote, logic element), or via communications.

Group 1 is the default setpoint group. The relay can automatically switch from Group 1 protections to Group 2 protections, and vice versa, by setting up the switching conditions under “**Change Setpoint Group**”. Under some application conditions, such as an over-current element pick up, it may not be desirable to change setpoint groups. A setpoint change can also be prevented if the breaker is open, so that a fault detected before a reclosure will not cause a group change while the breaker is open. In such cases, the user can set a condition under “BLK GROUP CHANGE”, where if asserted, the active setpoint group will stay active, even if the input configured to switch to the other setpoint group is asserted. For example if the active group was Group 1 at the time of a trip, the breaker opens, and the input configured under “BLK GROUP CHANGE” is asserted, the relay will maintain Setpoint Group 1, even if the input “SET GROUP 2 ACTIVE” is asserted. Vice versa, if the “BLK GROUP CHANGE” input is asserted; the relay will not switch from Group 2 to Group 1, even if the input under “SET GROUP 2 ACTIVE” is de-asserted.

The relay will default to Setpoint Group 1, if both the input “SET GROUP 2 ACTIVE” and the blocking input “BLK GROUP CHANGE” are de-asserted.

Switching from Group 1 to Group 2 can be also initiated by the Autoreclose, or the Cold Load Pickup functions. If the setpoint group selected in the Autoreclosure menu is different from the active setpoint group, then the Autoreclosure function will force the relay to apply the Autoreclosure selected setpoint group. The Autoreclosure function will then apply the AR shot settings to the corresponding protections. The relay will revert to the previous setpoint group after detecting the Autoreclosure resets.

Similarly, if “Enabled” and not blocked by the Autoreclosure, the Cold Load Pickup function will force the relay to apply the protections of the other setpoint group, if the one selected under the CLP menu is different from this, being in-service. The relay will revert to the setpoint group used originally, after the CLP blocking function resets.

### PATH: [CONTROLS > CHANGE SPNT GROUP](#)

#### **SET GROUP 2 ACTIVE**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*

*Default: Off*

This setting selects an input used to change from Setpoint Group 1 to Setpoint Group 2, when asserted. If no group change supervision is selected, Setpoint group 2 will stay active as long as the “SET GROUP 2 ACTIVE” input is asserted, and will revert to Group 1, when this input is de-asserted.

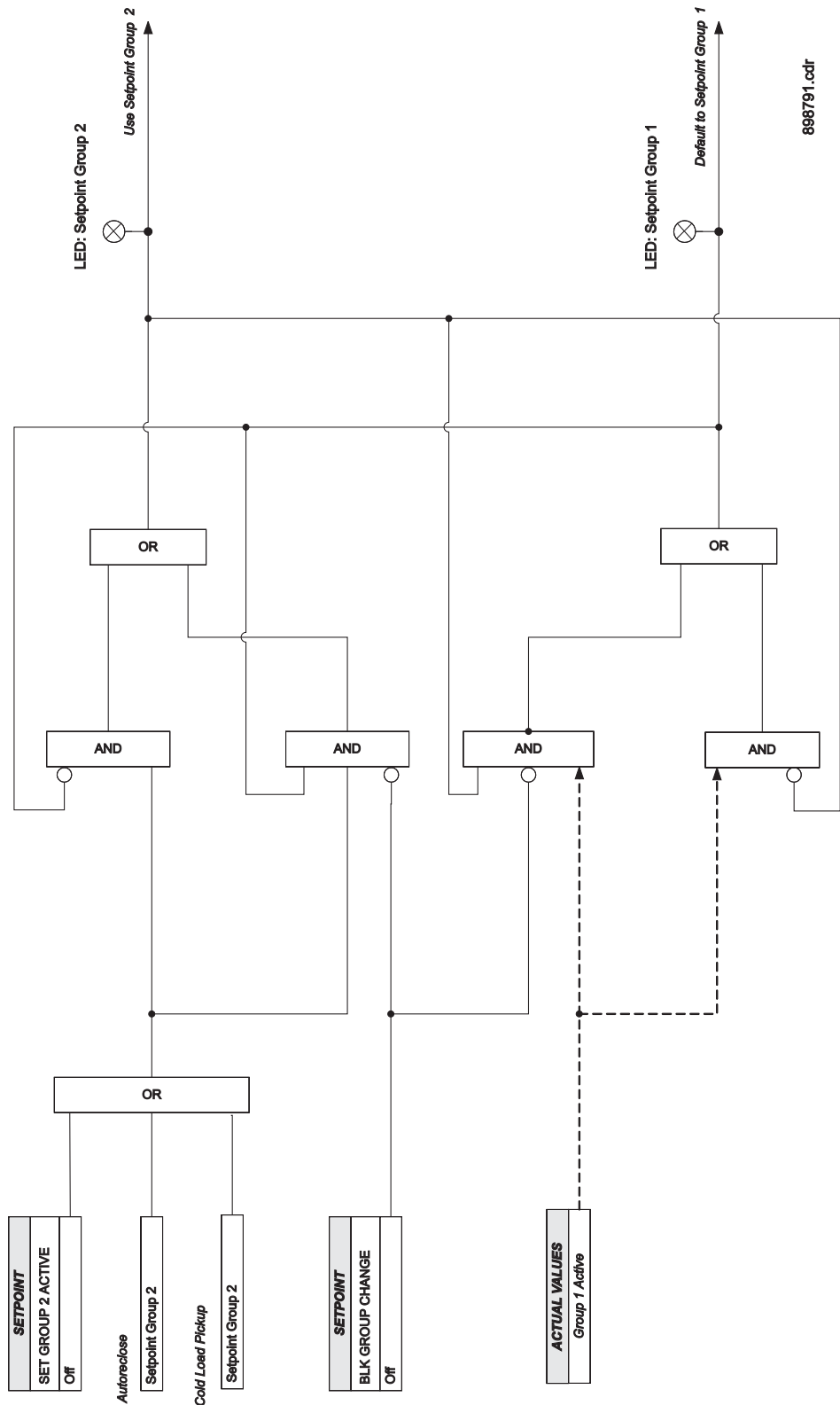
#### **BLOCK GROUP CHANGE**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*

*Default: Off*

This setting defines an input that can be used to block changing setpoint groups. When the assigned input is asserted, changing from one setpoint group to the other one is blocked.

Figure 6-14: Switching Setpoint Groups logic diagram



## 6.5.2 Virtual inputs

There are 32 virtual inputs that can be individually programmed to respond to input commands entered via the relay keypad, or by using communication protocols.

**PATH:** [SETPOINTS > S4 CONTROLS > VIRTUAL INPUTS](#).

### **VIRTUAL INPUT 1**

*Range: Off, On*

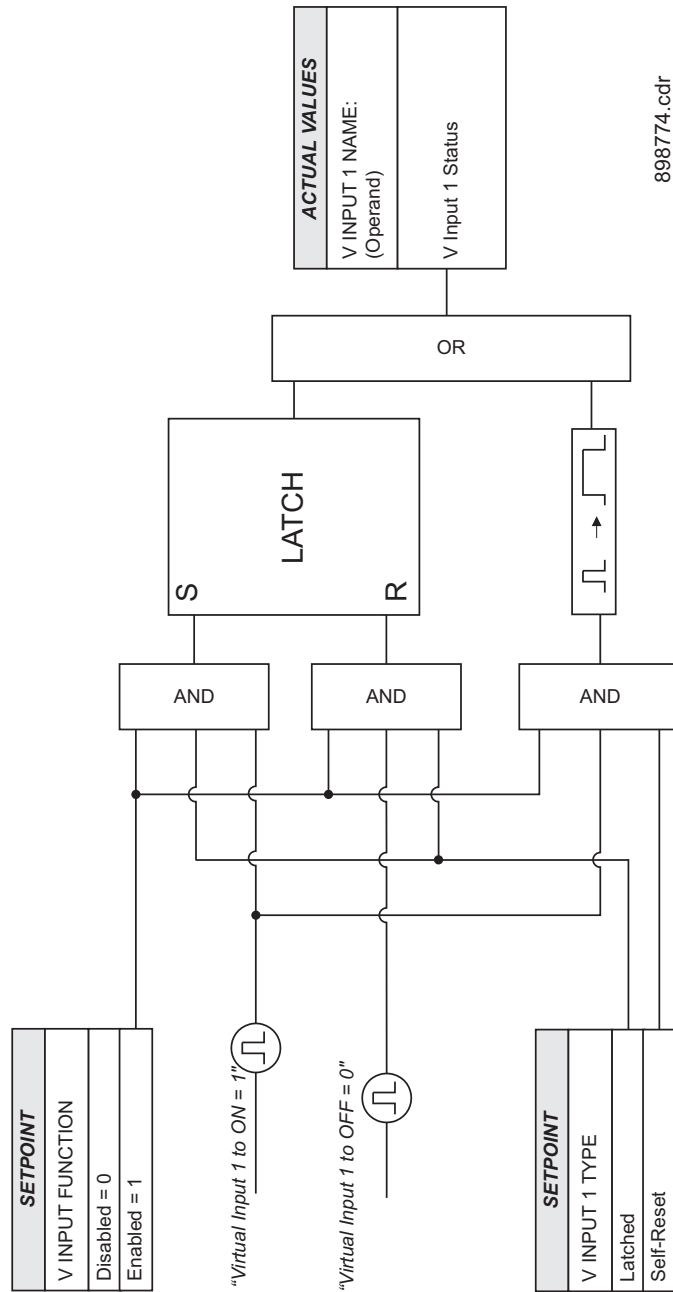
*Default: Off*

The state of each virtual input can be controlled under [SETPOINTS > S4 CONTROL > VIRTUAL INPUTS](#) menu. For this purpose, each of the virtual inputs selected for control need be "Enabled" under [SETPOINTS > S5 INPUTS/OUTPUTS > VIRTUAL INPUTS](#), and its type "Self-Reset" or "Latched" specified.

If Self-Reset type was selected, entering "On" command will lead to a pulse of one protection pass. To prolong the time of the virtual input pulse, one can assign it as a trigger source to a Logic Element with a dropout timer set to the desired pulse time. If "Latched" type is selected, the state of the virtual input will be latched, upon entering "On" command.

Refer to the logic diagram in the [S5 INPUTS/OUTPUTS > VIRTUAL INPUTS](#) chapter for more details.

Figure 6-15: Virtual Inputs Scheme logic



### 6.5.3 Logic elements

The 350 relay has eight Logic Elements available for the user to build simple logic using the state of any programmed contact, virtual or remote input, or an output from another logic element. Changing the state of any of the assigned inputs used as trigger sources, changes the state of the Logic element, unless a blocking input is present. The logic provides for assigning up to three triggering inputs in an "OR" gate for the logic element operation, up to three blocking inputs in an "OR" gate for defining the block signal. Pickup and dropout timers are available for delaying the logic element operation and reset respectively. In addition, the user can define whether to use an "ON", or an "OFF" state of the programmed element by selecting ASSERTED: "On" or "Off".

Referring to the Logic Element logic diagram above, the Logic Element can be set to one of the four functions: **Control**, **Alarm**, **Latched Alarm** or **Trip**. When **Alarm**, or **Latched Alarm** is selected, the output relay #1 (Trip) is not triggered when the logic element operates. The Trip output relay will be triggered when **Trip** is selected as a function, and the Logic element operates. The Logic element function can be also selected as **Control**, and used with the other relay elements, without turning on the ALARM, or the TRIP LED.

The LED "PICKUP" will light on upon pickup condition no matter the selection of the logic element function. The LED "ALARM" will light on upon Logic element operation only if either Alarm, or Latched Alarm selected. When Trip function is selected, the operation of the logic element will light on the LED "TRIP" only. The selection to trigger auxiliary output relays is provided for any selected logic element function.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > S4 CONTROLS > LOGIC ELEMENTS > LOGIC ELEMENT 1(8)**

#### **LOGIC E1 (8) FUNCTION**

*Range: Disabled, Control, Alarm, Latched Alarm, Trip*

*Default: Disabled*

This setting defines the use of the Logic Element. When "Trip" is selected as a function, the logic element will trigger the Output Relay # 1 (Trip) upon operation.

#### **LOGIC E1 (8) ASSERTED**

*Range: On, Off*

*Default: Off*

This setting defines which Logic Element state -"On" or "Off" - to be used as output from the logic.

#### **TRIGGER SOURCE 1, 2, 3**

*Range: Off, Any input from the list of inputs*

*Default: Off*

Each of the three trigger sources is configurable, assigning an input selected from a list of inputs. An input can be a contact input, virtual input, or remote input. See the list of available inputs from the table below.

#### **PICKUP TIME DELAY**

*Range: 0 to 600 ms in steps of 1 ms*

*Default: 1 ms*

This setting specifies the pickup time delay before Logic Element operation.

#### **DROPOUT TIME DELAY**

*Range: 0 to 600 ms in steps of 1 ms*

*Default: 1 ms*

This setting specifies the time delay from a reset timer that starts upon expiry of the pickup time delay and prolongs the operation of the Logic Element until its time expires.

#### **OUTPUT RELAYS 3 to 6**

*Range: Do not operate, Operate*

*Default: Do not operate*

Any, or all, of output relays 3 to 6 can be selected to operate upon the Logic Element operating condition. The selection of auxiliary relay outputs is available no matter whether the control **Alarm**, **Latched Alarm**, or **Trip** function is selected.

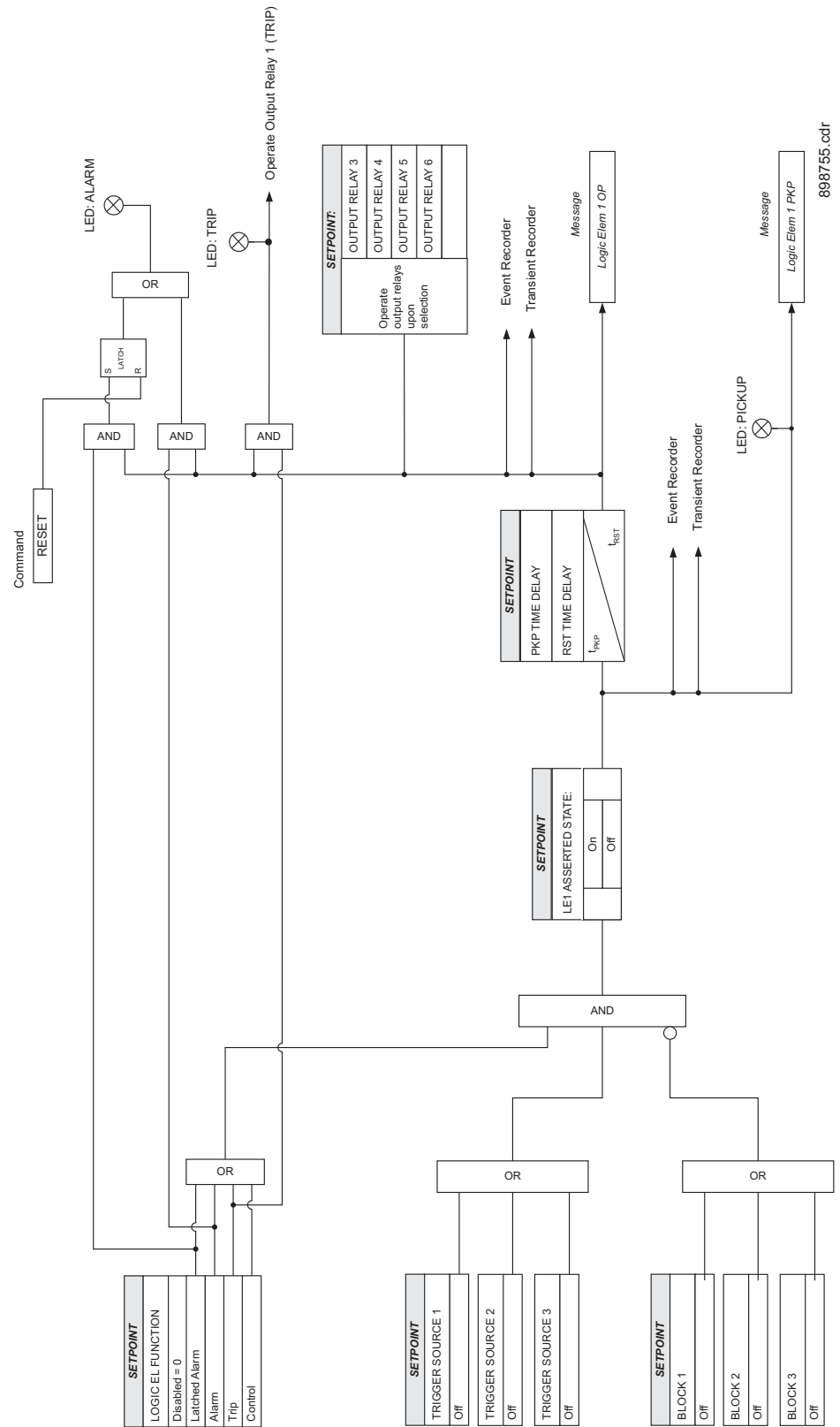
**BLOCK 1, 2, 3**

*Range: Off, Any input from the list of inputs*

*Default: Off*

Each of the three blocks is configurable, assigning an input selected from a list of inputs. The list of inputs consists of all contact inputs, virtual and remote inputs, output flags from protection, and control elements and inputs from all seven other logic inputs. See the list of available inputs from the table below.

Figure 6-16: Logic Element logic diagram



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**Table 9: List of logic inputs**

<b>Input Type</b>	<b>Input Name</b>
Contact Inputs	BKR 52a input (CI1)
	BKR 52b input (CI2)
	Contact Input 3
	Contact Input 4
	Contact Input 5
	Contact Input 6
	Contact Input 7
	Contact Input 8
Virtual Inputs	Virtual Input 1
	Virtual Input 2
	Virtual Input 3
	Virtual Input 4
	Virtual Input 5
	Virtual Input 6
	Virtual Input 7
	Virtual Input 8
	Virtual Input 9
	Virtual Input 10
	Virtual Input 11
	Virtual Input 12
	Virtual Input 13
	Virtual Input 14
	Virtual Input 15
	Virtual Input 16
	Virtual Input 17
	Virtual Input 18
	Virtual Input 19
	Virtual Input 20
	Virtual Input 21
	Virtual Input 22
	Virtual Input 23
	Virtual Input 24
	Virtual Input 25
	Virtual Input 26
	Virtual Input 27
	Virtual Input 28
	Virtual Input 29
	Virtual Input 30
	Virtual Input 31
	Virtual Input 32
Remote Inputs	Remote Input 1
	Remote Input 2
	Remote Input 3
	Remote Input 4
	Remote Input 5
	Remote Input 6

Input Type	Input Name
	Remote Input 7
	Remote Input 8
	Remote Input 9
	Remote Input 10
	Remote Input 11
	Remote Input 12
	Remote Input 13
	Remote Input 14
	Remote Input 15
	Remote Input 16
	Remote Input 17
	Remote Input 18
	Remote Input 19
	Remote Input 20
	Remote Input 21
	Remote Input 22
	Remote Input 23
	Remote Input 24
	Remote Input 25
	Remote Input 26
	Remote Input 27
	Remote Input 28
	Remote Input 29
	Remote Input 30
	Remote Input 31
	Remote Input 32
Logic Elements	Logic Element #1
	Logic Element #2
	Logic Element #3
	Logic Element #4
	Logic Element #5
	Logic Element #6
	Logic Element #7
	Logic Element #8

### 6.5.4 Breaker control

The Breaker Control menu is designed to trip and close the breaker from the relay either remotely (LOCAL MODE setting set to "OFF," or the selected contact input deselected) or locally (the input from the LOCAL MODE setpoint asserted). While in LOCAL MODE, the REMOTE OPEN and CLOSE setpoints are not active.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH:** SETPOINTS > S4 CONTROLS > BREAKER CONTROL

**LOCAL MODE**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*

*Default: Off*

The LOCAL MODE setting places the relay in local mode. The relay is in Remote Mode, if not forced into Local Mode by this setpoint (i.e. LOCAL MODE set to "OFF," or the selected input de-asserted).

**RESET**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*

*Default: Off*

The RESET setting resets the latched alarm or Trip LEDs, and the latched relays.

**REMOTE OPEN**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*

*Default: Off*

This setting specifies the input which when asserted, initiates a trip (output relay #1 TRIP energized) and opens the breaker.

**REMOTE CLOSE**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*

*Default: Off*

This setting specifies the input which when asserted initiates a close (output relay #2 CLOSE energized) and closes the breaker.

**KEYPAD BKR OPEN**

*Range: Yes, No*

*Default: No*

This setting provides flexibility to the user to open the breaker from the keypad. Selecting "Yes" will introduce a pulse of 100ms to the "trip" output relay. The setting is active, when the selected input under LOCAL MODE setpoint is asserted

**KEYPAD BKR CLOSE**

*Range: Yes, No*

*Default: No*

This setting provides flexibility to the user to close the breaker from the keypad. Selecting "Yes" will introduce a pulse of 100ms to the "close" output relay. The setting is active, when the selected input under LOCAL MODE setpoint is asserted

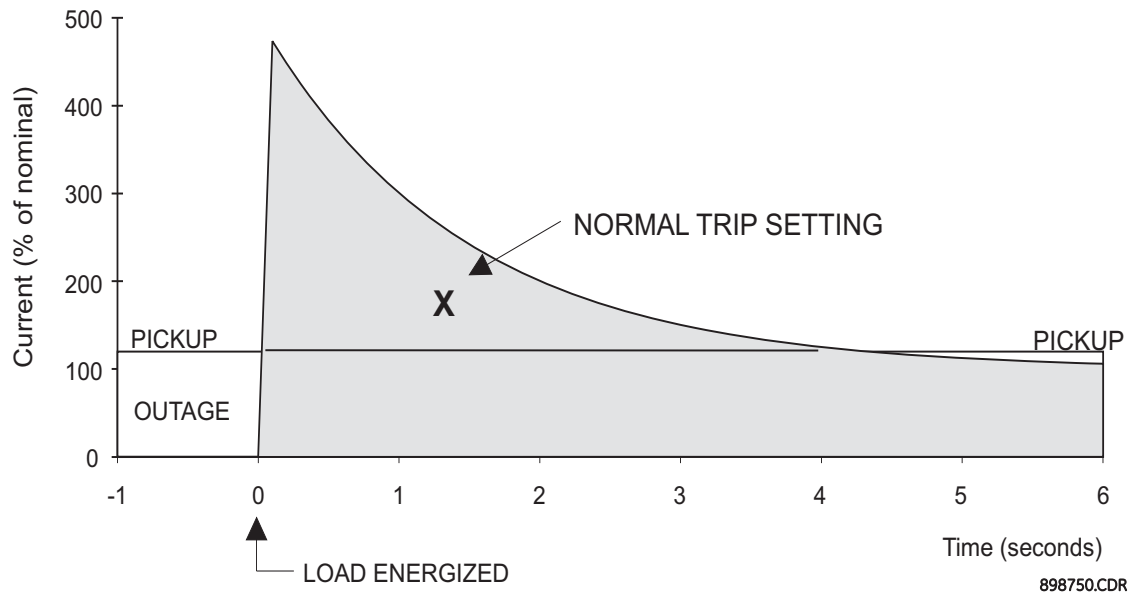
By default, the breaker control mode is set to "Remote" ( LOCAL MODE set to "OFF"). In this mode, only the REMOTE OPEN and REMOTE CLOSE setpoints are active. The rest of the setpoints with exception of the RESET setpoint are deactivated, regardless of the status of their selected inputs.

Local Mode is set if the input for the LOCAL MODE setpoint is asserted. In this mode, the REMOTE OPEN and REMOTE CLOSE setpoints are deactivated, regardless of the status of their selected inputs. **Breaker Open** and **Breaker Close** commands from the KEYPAD BKR OPEN and KEYPAD BKR CLOSE setpoints will be active, if the breaker operation is set to Local Mode (i.e. the selected input under the LOCAL MODE setpoint asserted).

### 6.5.5 Cold load pickup

The 350 can be programmed to block the instantaneous over-current elements, and raise the pickup level of the time over-current elements, when a cold load condition is detected. The cold load condition is detected during closing of the breaker on a feeder that has been de-energized for a long time. The feeder inrush current and the motor accelerating current during breaker closing may be above some over-current protection settings. The diagram shows the slow decaying of the cold load current starting at about 500% of the nominal current at the time of breaker closing, decaying down to 300% after 1 second, 200% after 2 seconds, and 150% after 3 seconds.

Figure 6-17: Cold load pickup



The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH:** [SETPOINTS](#) > [S4 CONTROLS](#) > [COLD LOAD PICKUP](#)

#### CLP BLK FUNCTION

*Range: Disabled, Alarm, Latched Alarm*

*Default: Disabled*

If set to Alarm, the alarm LED will flash upon detection of Cold Load Pickup condition, and will turn off upon clearing the condition. If Latched Alarm setting is selected, the alarm LED will flash during the Cold Load Pickup condition, and will remain ON, when the condition is cleared. The Alarm LED turns OFF upon manual or remote reset command.

#### OUTAGE TIME

*Range: 1 to 1000 min in steps of 1 min*

*Default: 20 min*

This timer starts when the feeder is de-energized (currents drop below 3% of CT nominal). The Cold Load Pickup is armed after its time expiration.

#### CLP BLOCKING TIME

*Range: 1 to 1000 sec in steps of 1 sec*

*Default: 5 s*

This setting sets the time of blocking for the selected instantaneous overcurrent elements, and the time of raised pickup level of the time overcurrent elements. This timer starts when currents bigger than 10% of CT nominal are detected.

**CLP EXT INITIATE**

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Element 1 to 8*

*Default: Off*

This setting allows the user to force the CLP element into Cold Load Pickup armed state, bypassing the timer **Outage Time Before Pickup**.

**BLOCK PH IOC1(2) / BLOCK GND IOC1(2) / BLOCK NTRL IOC1(2)**

*Range: No, Yes*

*Default: No*

Each instantaneous over-current element from the list can be selected for block or not, upon cold load pickup condition.

**RAISE PH TOC PKP/ RAISE GND TOC PKP/ RAISE NTRL TOC PKP**

*Range: 0 to 100% in steps of 1%*

*Default: 0%*

The pickup level of each time over-current element from the list can be raised by 0 to 100%, upon cold load pickup condition.

**OUTPUT RELAYS 3 to 6**

*Range: Do not operate, Operate*

*Default: Do not operate*

Each of the output relays can be programmed to operate when cold load pickup function is armed.

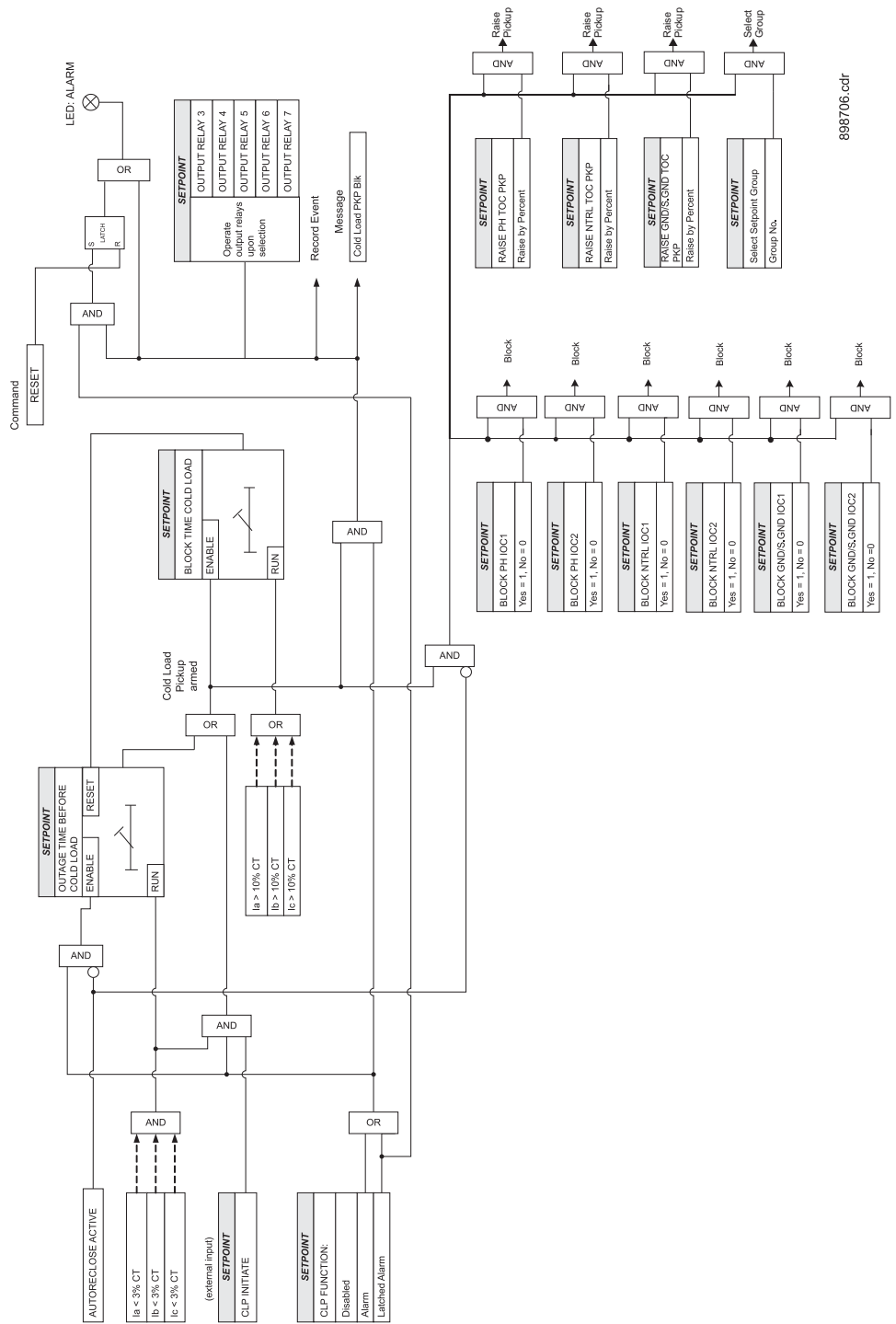
**SELECT SETP GROUP**

*Range: Active Group, SP Group 1 Active, SP Group 2 Active*

*Default: SP Group 1 Active*

The CLP blocking function will block the IOC, and adjust the TOC pickup levels for the over-current elements from whichever Setting Group is active, if the setting Active Group is selected.

Figure 6-18: Cold Load Pickup logic diagram



## 6.5.6 Breaker failure

The Breaker Failure function monitors the phase currents, after a trip command from the protection elements is initiated. If any phase current is above the set current level after the BF DELAY time expires, a breaker failure will be declared, and will operate the selected output relays. The Breaker failure scheme provides also an external input to initiate breaker failure via Contact Input, Virtual Input, Remote Input, or Logic Element.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH:** SETPOINTS > S4 CONTROLS > BREAKER FAIL

### BF FUNCTION

*Range: Disabled, Alarm, Latched Alarm*

*Default: Disabled*

If set to Alarm, the alarm LED will flash upon detection of Breaker Failure condition, and will turn off upon clearing the condition. If Latched Alarm setting is selected, the alarm LED will flash during the Breaker Failure condition, and will remain ON, when the condition is cleared. The Alarm LED turns OFF upon manual or remote reset command.

### BF CURRENT

*Range: 0.05 to 20.00 x CT in steps of 0.01*

*Default: 1.00 x CT*

This setting selects the current level to be monitored by the BF logic, after the programmed time delays.

### BF EXT INITIATE

*Range: Off, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Element 1 to 8*

*Default: Off*

This setting allows the user to select Contact Input, Virtual or Remote Input, Logic Element to initiate the Breaker Failure logic.

### BF TIME DELAY 1

*Range: 0.03 to 1.00 s in steps of 0.01 s*

*Default: 0.10 s*

This timer starts when breaker trip command is issued from any of the protection elements.

### BF TIME DELAY 2

*Range: 0.00 to 1.00 s in steps of 0.01 s*

*Default: 0.00 s*

This timer does not start until a trip condition is recognized, BF TIMER DELAY 1 has expired, and at least one of the phase currents is above the BF CURRENT setting.

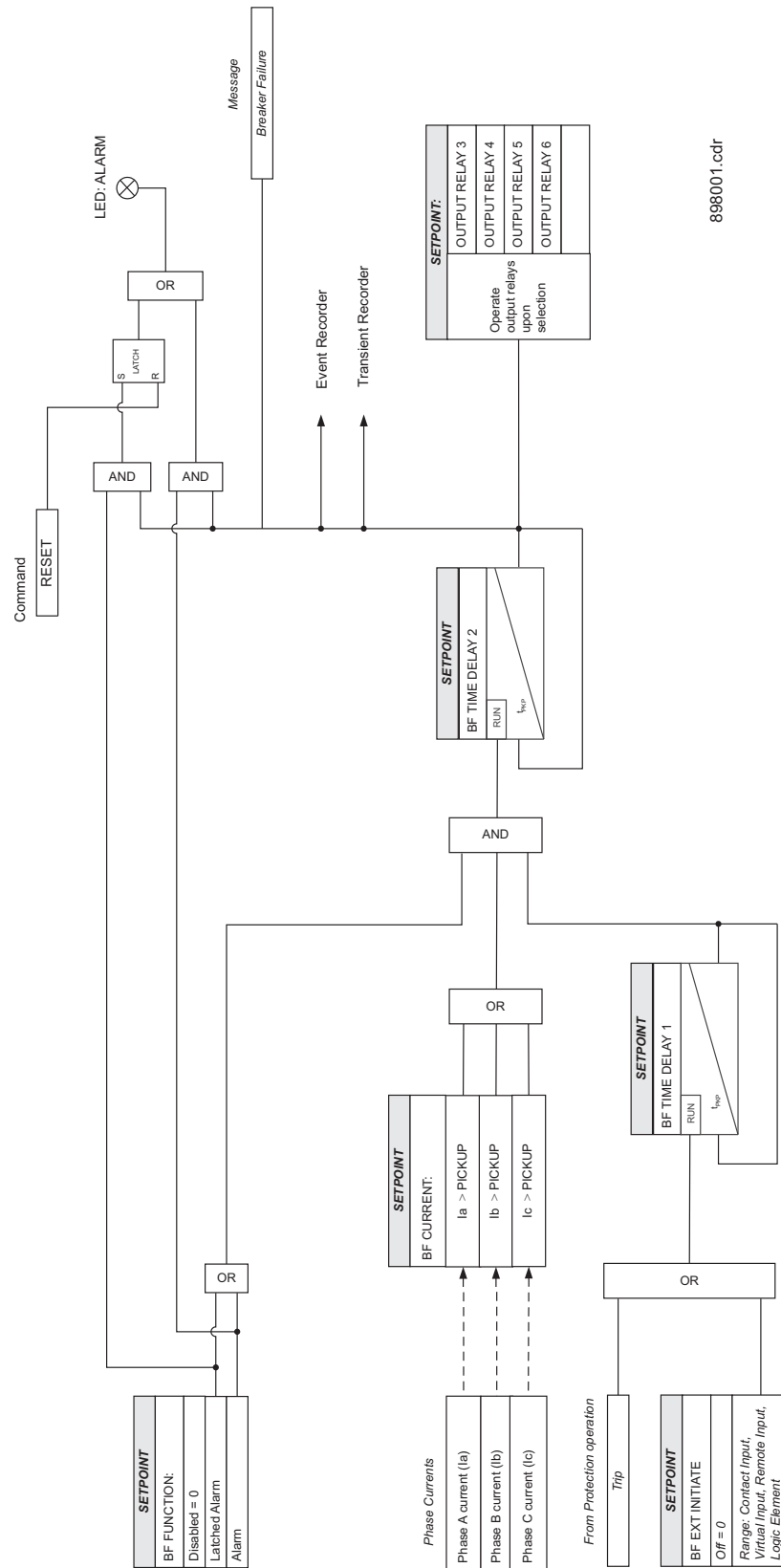
### OUTPUT RELAY 3 to 6

*Range: Do not operate, Operate*

*Default: Do not operate*

Each of the output relays can be programmed to operate upon detection of breaker failure.

Figure 6-19: Breaker failure logic diagram



## 6.5.7 Autorecloser

The automatic recloser is intended for use on single three-pole tripping breaker applications. Up to four reclosing “shots” can be programmed with independent set of protection elements for initiation, and individual dead time prior to each subsequent shot. A typical example for selection of individual set of overcurrent protection elements for initiation is the selection of instantaneous overcurrent protections for the first AR initiation, and selection of time overcurrent protections after the first reclose. This would provide longer time before the breaker opens, and allow the fuses to burn off, if the fault is still present.



To synchronize the Reclose function with the breaker status feedback, it is recommended that a debounce of 2 cycles is used, regardless of whether the breaker status is detected using one or both contacts.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH:** [SETPOINTS](#) > [S4 CONTROLS](#) > [AUTORECLOSE](#) > [AR SETUP](#)

### AR FUNCTION

*Range: Disabled, Enabled*

*Default: Disabled*

This setting enables or disables the Autorecloser function.

### NUMBER OF SHOTS

*Range: 1 to 4, step 1*

*Default: 1*

The maximum number of reclosures that will be attempted before AR Not Ready.

### DEAD TIME SHOT 1 to 4

*Range: 0.1 to 600.0 s, step 0.1 s*

*Default: 1.0 s*

This setting specifies the dead time delay before each reclosure. Four time delay settings are to be configured and used to time out before the first, second, third, or fourth breaker reclosure.

### RST N/READY TIME

*Range: 0.1 to 600.0 s, step 0.1 s*

*Default: 10 s*

This setting specifies the reset AR Not Ready time. Upon breaker close, the timer times out, and resets the AR lockout.

### INCOMP SEQ TIME

*Range: 0.1 to 600.0 s, step 0.1 s*

*Default: 5.0 s*

This timer is used to set the maximum time interval allowed for single reclosure shot. The timer starts timing out for both situations: upon AR initiate to open the breaker, where the breaker doesn't open, or whenever breaker reclose command is issued, where the breaker doesn't close. Upon incomplete sequence time expiry, the AR goes into AR Not Ready mode.

### RESET TIME

*Range: 0.1 to 600.0 s, step 0.1 s*

*Default: 5.0 s*

This time is used to reset the AR into AR ready mode after successful reclosure. If no breaker tripping occurs within the reset time, the AR shot counter is reset.

**BLOCK AR**

*Range: Off, Contact Input1 to 8, Virtual Input1 to 32, Remote Input1 to 32, Logic Elements1 to 8*

*Default: Off*

This setting provides selection for contact input, virtual input, remote input, or logic element to block off the AR scheme.

**EXT INITIATE**

*Range: Off, Contact Input1 to 8, Virtual Input1 to 32, Remote Input1 to 32, Logic Elements1 to 8*

*Default: Off*

This setting provides selection for contact input, virtual input, remote input, or logic element to initiate the AR scheme.

**PH IOC1/2 INITIATE**

*Range: Off/On*

*Default: Off*

When set to "On", the operation of this element initiates the AR sequence.

**GND [S.GND] IOC1/2 INITIATE**

*Range: Off/On*

*Default: Off*

When set to "On", the operation of this element initiates the AR sequence.

**NTRL IOC1/2 INITIATE**

*Range: Off/On*

*Default: Off*

When set to "On", the operation of this element initiates the AR sequence.

**PHASE TOC INITIATE**

*Range: Off/On*

*Default: Off*

When set to "On", the operation of this element initiates the AR sequence.

**NTRL TOC INITIATE**

*Range: Off/On*

*Default: Off*

When set to "On", the operation of this element initiates the AR sequence.

**GND [S.GND] TOC INITIATE**

*Range: Off/On*

*Default: Off*

When set to "On", the operation of this element initiates the AR sequence.

**AR READY - RELAY 3 to 6**

*Range: Do not operate, Operate*

*Default: Do not operate*

Any or all of the output relays can be selected to operate upon autoreclose status detected as "AR READY".

**AR IN-PROGR - RELAY 3 to 6**

*Range: Do not operate, Operate*

*Default: Do Not Operate*

Any or all of the output relays can be selected to operate upon autoreclose status detected as "AR IN-PROGRESS".

**AR N/READY - RELAY 3 to 6**

*Range: Do not operate, Operate*

*Default: Do Not Operate*

Any or all of the output relays can be selected to operate upon autoreclose status detected as "AR LOCKOUT".

**SELECT SETP GROUP**

*Range: Active group, SP Group 1 Active, SP Group 2 Active*

*Default: SP Group 1 Active*

The Autoreclose function will be executed in the setpoint group selected as a setting in "SELECT SETP GROUP", or in the active setpoint group if the setting "Active Group" is selected.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > S4 CONTROLS > AUTORECLOSE > AR SHOT 1(4)**

**BLOCK PH IOC1/2 Shot 1 to 4**

*Range: Off/On*

*Default: Off*

If set to "On" for the selected shot, the operation of the element will initiate breaker trip after the corresponding breaker reclosing shot.

**BLOCK NTRL IOC1/2 Shot 1 to 4**

*Range: Off/On*

*Default: Off*

If set to "On" for the selected shot, the operation of the element will initiate breaker trip after the corresponding breaker reclosing shot.

**BLOCK GND/S.GND IOC1/2 Shot 1 to 4**

*Range: Off/On*

*Default: Off*

If set to "On" for the selected shot, the operation of the element will initiate breaker trip after the corresponding breaker reclosing shot.

**BLOCK PH TOC Shot 1 to 4**

*Range: Off/On*

*Default: Off*

If set to "On" for the selected shot, the operation of the element will initiate a breaker trip after the corresponding breaker reclosing shot.

**BLOCK GND TOC Shot 1 to 4**

*Range: Off/On*

*Default: Off*

If set to "On" for the selected shot, the operation of the element will initiate a breaker trip after the corresponding breaker reclosing shot.

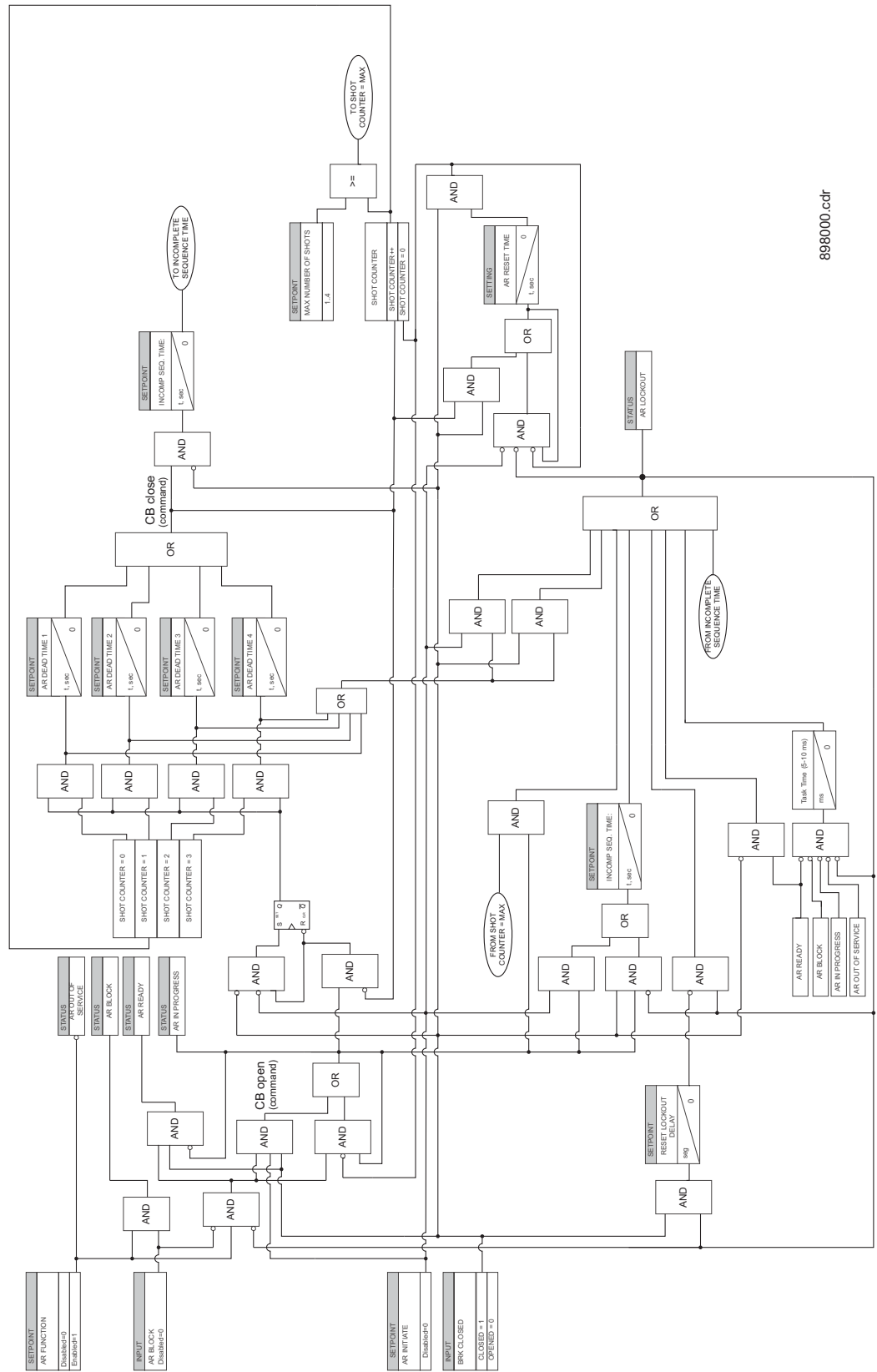
**BLOCK NTRL TOC Shot 1 to 4**

*Range: Off/On*

*Default: Off*

If set to "On" for the selected shot, the operation of the element will initiate a breaker trip after the corresponding breaker reclosing shot.

Figure 6-20: Autoreclose logic diagram



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The Automatic Reclosure function is designed to perform up to four breaker autoreclosings, with a configurable dead time before each reclosing shot. Upon AR function enabled, and breaker status “closed”, the AR is set into “AR Ready” state. If an intermittent feeder fault occurs such as overhead conductor touching tree branch, one or more of the overcurrent protection elements enabled under AR initiate menu will operate and issue a breaker trip command. If the breaker opens, the dead time configured under the first AR shot will start timing out. After this time expires, the AR scheme will produce the first breaker reclosing shot. Upon breaker close and no fault conditions, the overcurrent elements set for initiation on the first AR shot will not operate, and the reclosing is declared successful. The remaining of the configured AR sequence will be executed. The AR Reset time will start timing out, where upon time expiry resets the AR counter. The AR sequence is reset with AR function into “AR Ready” state.

If the fault is permanent, the configured AR sequence will be executed in full, where the breaker opens after the last reclosing shot and the AR function goes into lockout.

The reclosure scheme passes through the following states during operation:

**AR NOT READY:** When in this state, the AR is blocked. The AR NOT READY occurs if any of the following conditions are present:

- The maximum shot number was reached.
- The incomplete sequence AR INCOM SEQ TIME timer times out.
- The AR BLOCK INPUT is set

**AR READY:** To reach this state the AR RESET NOT READY timer times out from NOT READY state or the AR RESET TIME timer times out from WAIT RST TIME state. In this state the autorecloser is waiting for reclose Initiation (RI) event to start the reclosure process.

**WAIT FOR 52 OPEN:** Once a Reclose Initiation event occurs the autorecloser is waiting for breaker status OPEN or otherwise the AR INCOM SEQ TIME timer will time out. If the AR INCOM SEQ TIME expires, the autorecloser will go into NOT READY state. However if the breaker opens, the AR scheme will start the configured DEAD TIME timer, and will be put into WAIT DEAD TIME state.

**WAIT DEAD TIME:** In this state the autorecloser is waiting for the relevant AR DEAD TIME SHOT timer to time out. If during this time out the breaker status changes to CLOSE, a Reclose Initiation or an AR BLOCK input occurs the autorecloser process ends in a NOT READY state. If not, the WAIT FOR 52 CLOSE state is reached.

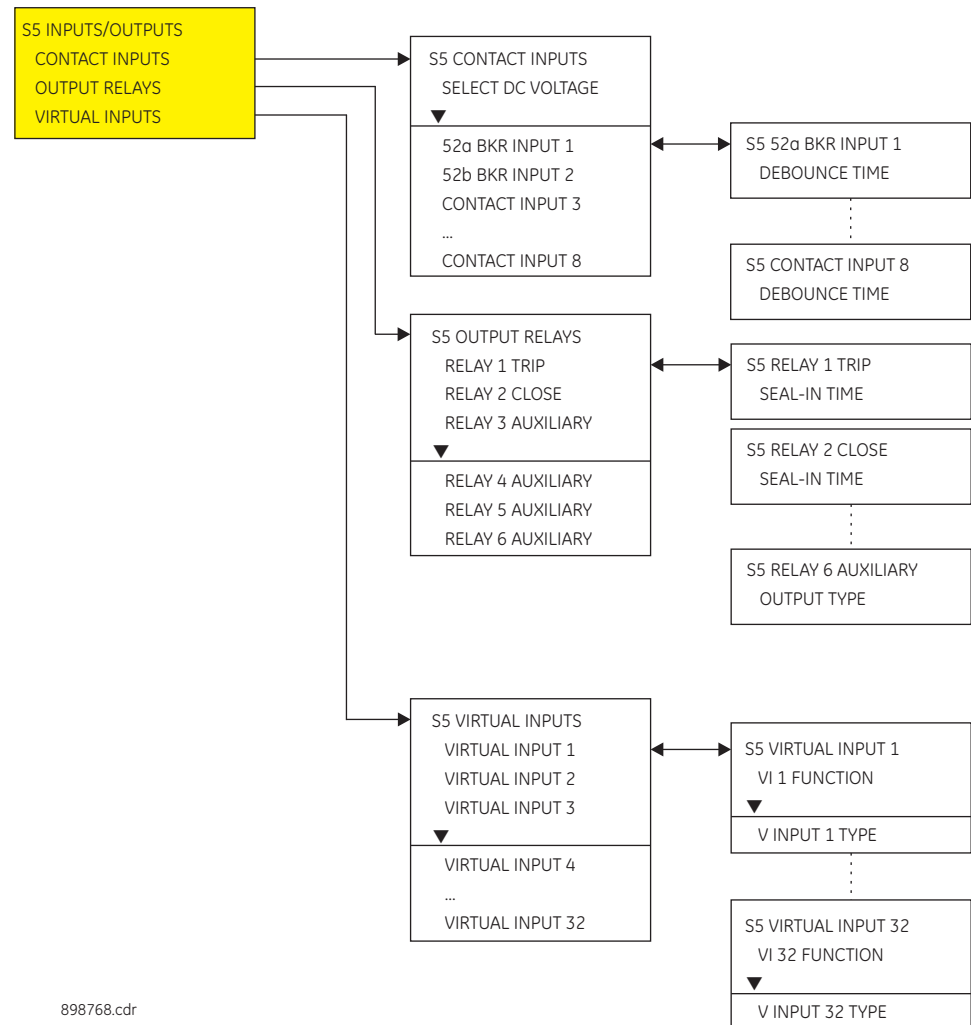
**WAIT FOR 52 CLOSE:** In this state upon reclosing command, the autorecloser is waiting for the breaker to CLOSE. If the AR INCOM SEQ TIME timer times out or a new Reclose Initiation occurs and it's the last shot then the autorecloser ends in a NOT READY state. If a new Reclose Initiation occurs and it is not the last from the programmed sequence, the autorecloser goes into the WAIT FOR 52 OPEN status.

**WAIT RESET TIME:** In this state, when the AR RST TIME timer times out the number of shots is reset and the autorecloser goes into AR READY state waiting for a new AR execution. If the breaker status changes to OPEN or an AR BLOCK input occurs, or a new *Reclose Initiation* happens and it's the last shot then the autorecloser ends in a NOT READY state.

If a new *Reclose Initiation* different from the last shot occurs the autorecloser goes into the WAIT FOR 52 OPEN status for the next shot.

*Reclose Initiation* is produced by a trip with the relevant permission enabled.

## 6.6 S5 Inputs/Outputs



### 6.6.1 Contact inputs

The 350 relay is equipped with eight (8) contact inputs, which can be used to provide a variety of functions such as for circuit breaker control, external trips, blocking of protection elements, etc. All contact inputs are wet type contacts (refer to the 350 typical wiring diagram) that require an external DC voltage source. The voltage threshold (17V, 33V, 84V, 166V) is selectable, and it applies for all eight contact inputs.

The contact inputs are either open or closed with a programmable debounce time to prevent false operation from induced voltage. Because of de-bouncing, momentary contacts must have a minimum dwell time greater than half power frequency cycle. The debounce time is adjustable by the user.

**PATH:** [SETPOINTS](#) > [S5 INPUTS/OUTPUTS](#) > [CONTACT INPUTS](#)

**SELECT DC VOLTAGE***Range: 17 V, 33 V, 84 V, 166 V**Default: 84 V***52a BKR INPUT 1***Range: Select alpha-numeric name**Default: 52a (CI#1)***52b BKR INPUT 2***Range: Select alpha-numeric name**Default: 52b (CI#2)***CONTACT INPUT X [3 to 8]***Range: Select alpha-numeric name**Default: Input X***DEBOUNCE TIME**

L

**CONTACT INPUT X [1 TO 8]***Range: 1 to 64 ms**Default: 2 ms*

Each of the contact inputs 3 to 8, can be named to reflect the function it represents within the application. Up to 18 alpha-numeric characters are available for names.

The debounce time is used to discriminate between oscillating inputs. The state will be recognized if the input is maintained for a period consisting of the protection pass plus the debounce setting.



Contact Input 1 and Contact Input 2 are named by the factory as 52a and 52b respectively and are used for monitoring the breaker open/close state when wired to the breakers auxiliary contacts 52a and 52b.

## 6.6.2 Output relays

The 350 relay is equipped with seven electromechanical output relays: two special relays designated for Breaker Trip and Close (Relay 1 "Trip", Relay 2 "Close"), four general purpose relays (Auxiliary Relays 3 to 6), and one Critical Failure relay for fail-safe relay indication. The special purpose relays have fixed operating characteristics and the general purpose relays can be configured by the user. Logic diagrams for each output relay are provided for detailed explanation of their operation.

Operation of these breaker-control relays is designed to be controlled by the state of the circuit breaker as monitored by a 52a or 52b contact.

- The Trip and Close relays reset after the breaker is detected in a state corresponding to the command. When a relay feature sends a command to one of these special relays, it will remain operational until the requested change of breaker state is confirmed by a breaker auxiliary contact and the initiating condition has reset.
- If the initiating feature resets, but the breaker does not change state, the output relay will be reset after a default interval of 2 seconds.
- If neither of the breaker auxiliary contacts, 52a nor 52b, is programmed to a logic input, the Trip Relay is de-energized after either the delay programmed in the Breaker Failure feature, or a default interval of 100 ms after the initiating input resets. The Close Relay is de-energized after 200 ms.
- If a delay is programmed for the Trip or Close contact seal-in time, then this delay is added to the reset time. Note that the default setting for the seal-in time is 40 ms.

52a Contact Configured	52b Contact Configured	Relay Operation
Yes	Yes	Trip Relay remains operational until 52b indicates an open breaker. Close Relay remains operational until 52a indicates a closed breaker.
Yes	No	Trip Relay remains operational until 52a indicates an open breaker. Close Relay remains operational until 52a indicates a closed breaker.
No	Yes	Trip Relay remains operational until 52b indicates an open breaker. Close Relay remains operational until 52b indicates a closed breaker.
No	No	Trip Relay operates until either the Breaker Failure delay expires (if the Breaker Failure element is enabled), or 100 ms after the feature causing the trip resets. Close Relay operates for 200 ms.

### 6.6.2.1 Output Relay 1 "Trip"

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.2.1 - Working with the Keypad*.

**PATH:** SETPOINTS > S5 INPUTS/OUTPUTS > OUTPUT RELAYS > RELAY 1 TRIP

#### SEAL IN TIME

*Range: 0.00 to 9.99 s in steps of 0.01*

*Default: 0.04 s*

This setting defines the time to be added to the reset time of the Relay 1 Trip output, thus extending its pulse width. This is useful for those applications where the 52 contacts reporting the breaker state are faster than the 52 contacts that are responsible for interrupting the coil current.

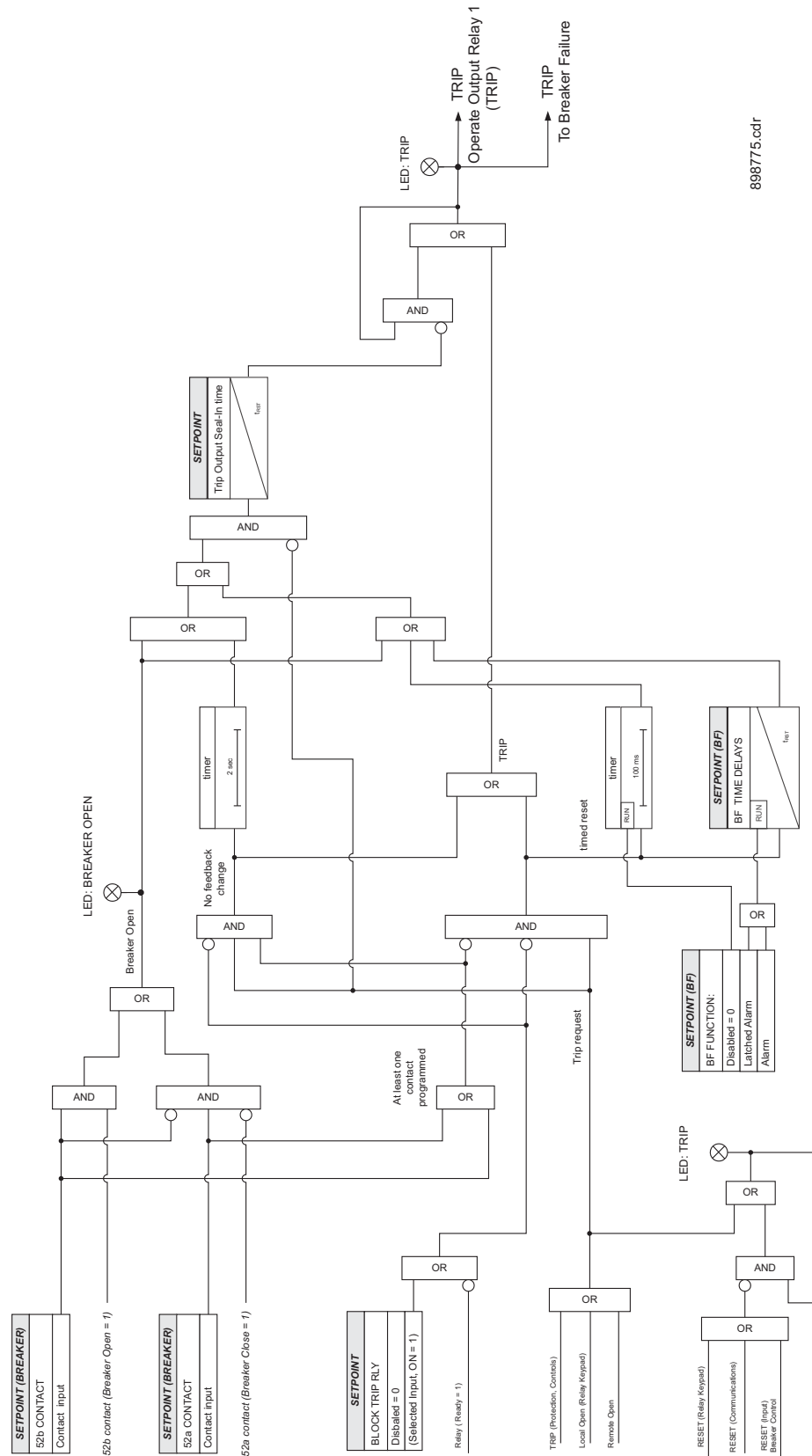
#### BLOCK RLY 1 TRIP

*Range: Disabled, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*

*Default: Disabled*

This setting defines a block to the Trip Output relay. When the selected input is asserted, the Trip Output relay will be blocked.

Figure 6-21: Relay 1 "TRIP" logic diagram



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### 6.6.2.2 Output Relay 2 "Close"

**PATH:** SETPOINTS > S5 INPUTS/OUTPUTS > OUTPUT RELAYS > RELAY 2 CLOSE

**SEAL IN TIME**

*Range: 0.00 to 9.99 s in steps of 0.01*

*Default: 0.04 s*

This setting defines the time to be added to the reset time of the Relay 2 Close output, thus extending its pulse width. This is useful for those applications where the 52 contacts reporting the breaker state are faster than the 52 contacts that are responsible for interrupting the coil current.

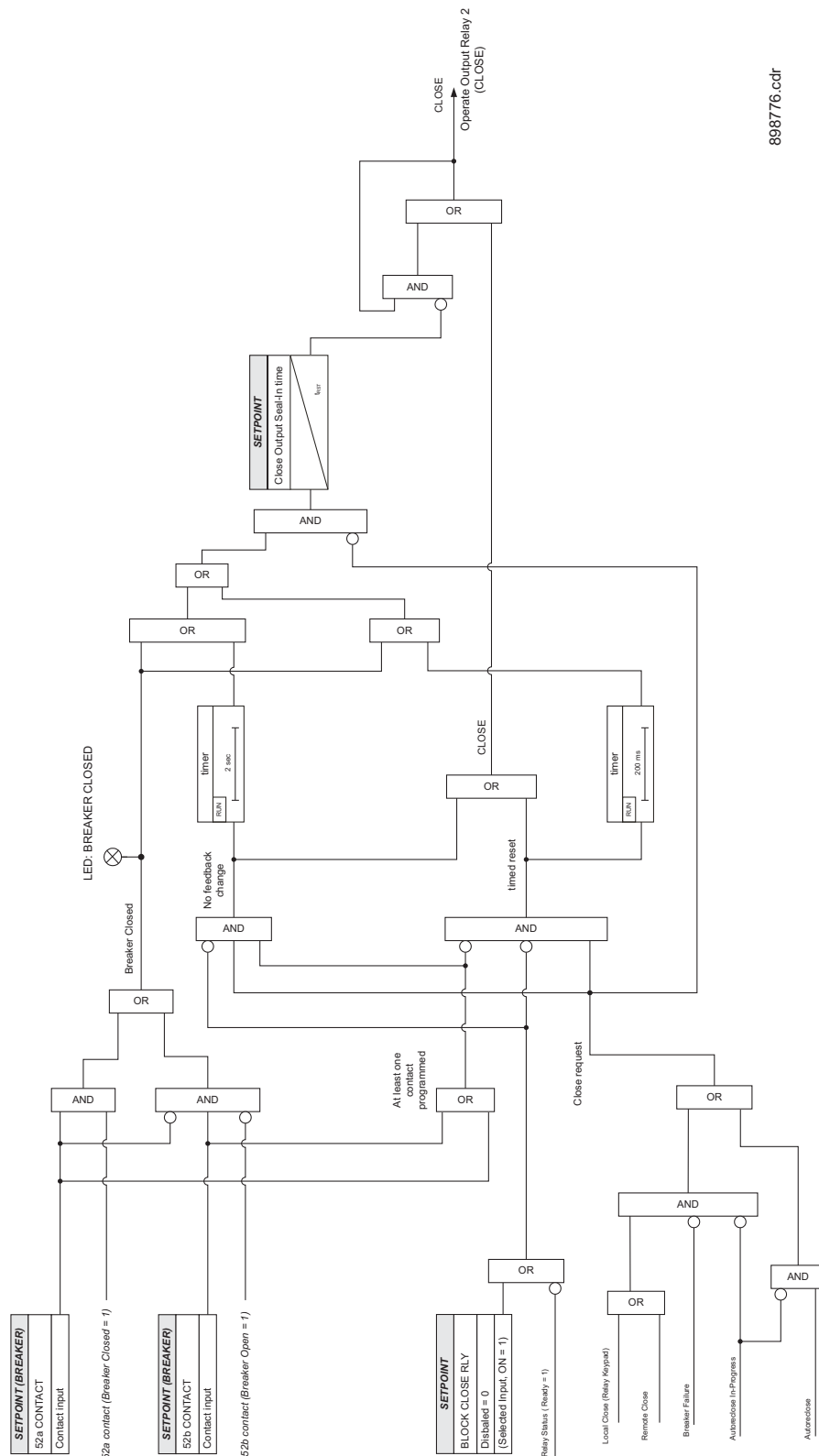
**BLOCK RLY 2 CLOSE**

*Range: Disabled, Contact Input 1 to 8, Virtual Input 1 to 32, Remote Input 1 to 32, Logic Elements 1 to 8*

*Default: Disabled*

This setting defines a block to the Close Output relay. When the selected input is asserted, the Close Output relay will be blocked. The block function can be useful for breaker maintenance purposes.

Figure 6-22: Relay 2 "CLOSE" logic diagram



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### 6.6.2.3 Auxiliary Output Relays 3 to 6

The 350 relay is equipped with four auxiliary output relays numbered from 3 to 6. All these relays are available for selection for operation of protection, control, or maintenance features. Each auxiliary relay can be selected as either **Self-Reset**, or **Latched**. If the Self-Reset type is selected, the output relay will be energized as long as the element is in operating mode and will reset when the element drops out. If the Latched type is selected, the output relay will stay energized, after the element dropout, and will be de-energized upon the reset command.

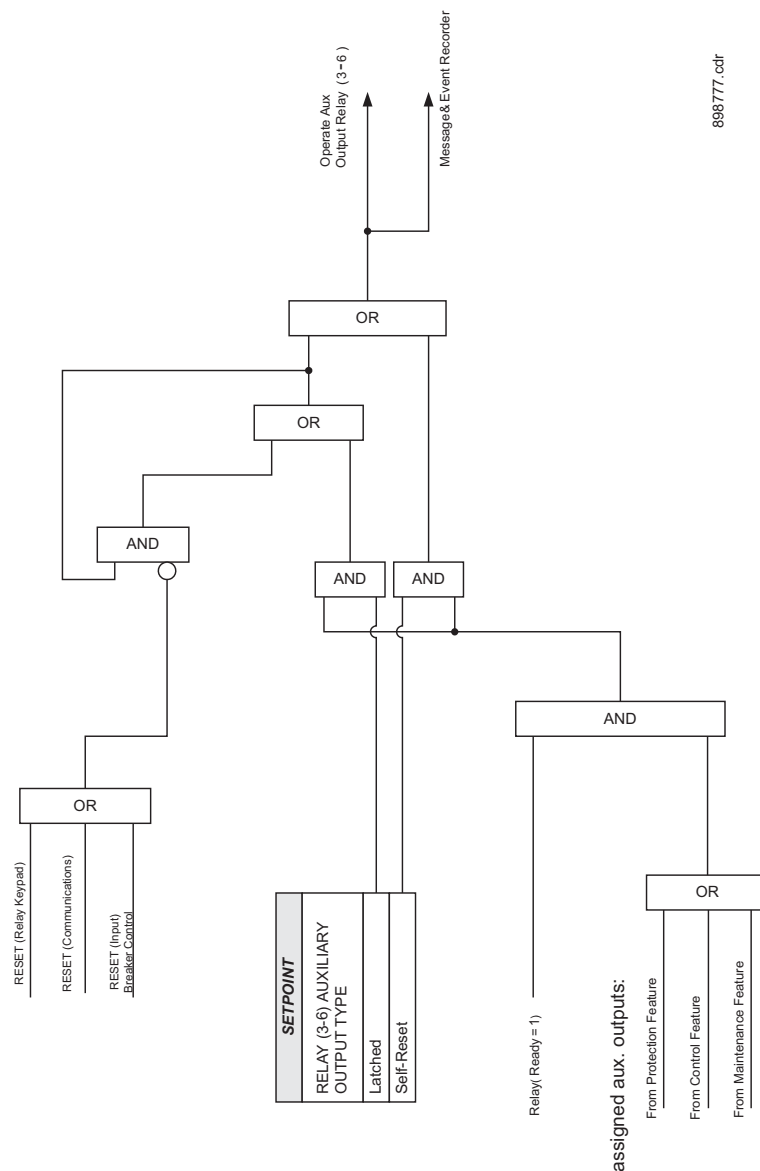
**PATH:** SETPOINTS > S5 INPUTS/OUTPUTS > OUTPUT RELAYS > RELAY 3(6) AUXILIARY

**OUTPUT TYPE**

Range: Self Reset, Latched

Default: Self Reset

Figure 6-23: Auxiliary relays



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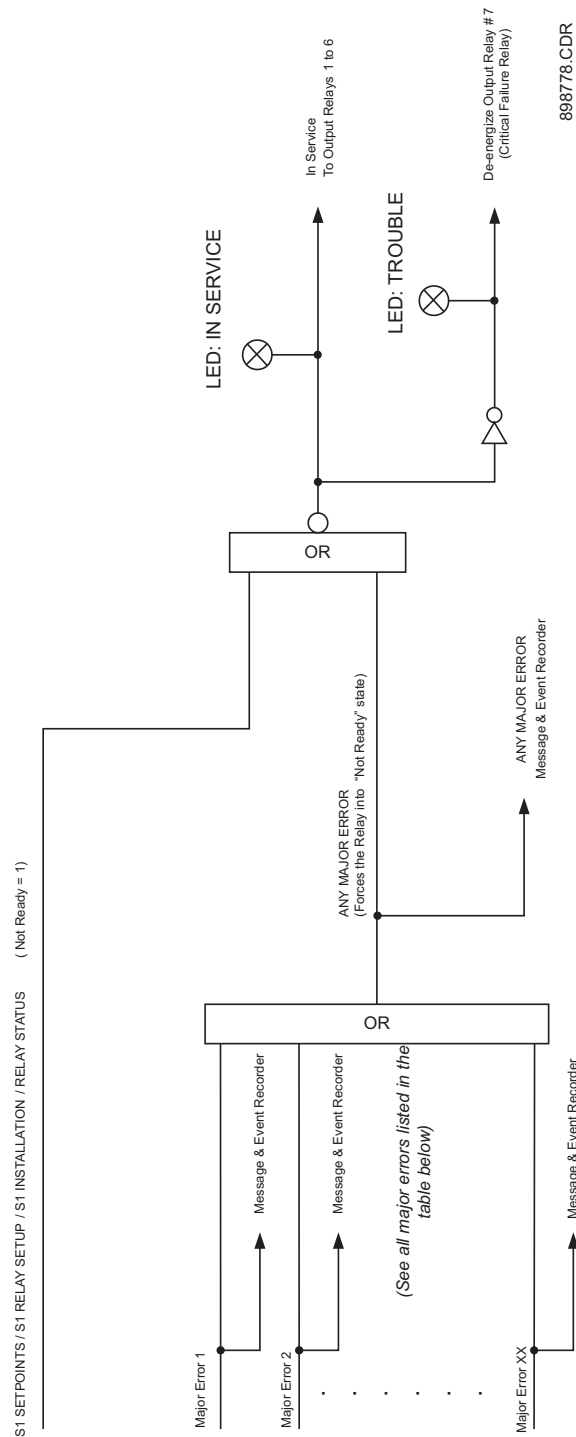
#### 6.6.2.4 Critical Failure Relay #7

The 350 relay is also equipped with one output relay (# 7 - "Critical Failure Relay") for fail-safe indication. There are no user-programmable setpoints associated with this output relay. The logic for this relay is shown below.

The Critical Failure Relay (Output Relay 7) is a form C contact (refer to the Typical Wiring Diagram) with one NO and one NC contacts (no control power). Output relay 7 is energized or de-energized (state change) depending on the following conditions:

1. Output Relay 7 will be **de-energized**, if the relay is not IN-SERVICE or the control power is not applied to the relay
2. Output Relay 7 will be **energized** when the control power is applied to the relay and the relay is IN-SERVICE mode.
3. Output Relay 7 will stay **de-energized**, when the control power is applied, if the relay was not programmed as "Ready", or upon major self-test failure during relay boot up.
4. Output Relay 7 will change state from **energized** to **de-energized** if the 350 relay experiences any major self-test failure.

Figure 6-24: Output relay 7: Critical Failure Relay



### 6.6.3 Virtual inputs

There are 32 virtual inputs that can be individually programmed to respond to input commands entered via the relay keypad, or by using communication protocols.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH: SETPOINTS > S5 INPUTS/OUTPUTS > VIRTUAL INPUTS****VI x FUNCTION***Range: Disabled/Enabled**Default: Disabled*

The Virtual Input is enabled and ready to be triggered when set to **Enabled**. All virtual inputs will appear under the **S4 CONTROLS > SETPOINTS > S4 VIRTUAL INPUTS** menu.

**VI x TYPE***Range: Self-Reset, Latched**Default: Self-reset*

When the **Self-Reset** type is selected, the Virtual Input will be evaluated for one protection pass only, upon "On" initiation and it will reset. When the **Latched** type is selected, the virtual input will keep the state "On" until reset command "Off" is initiated.



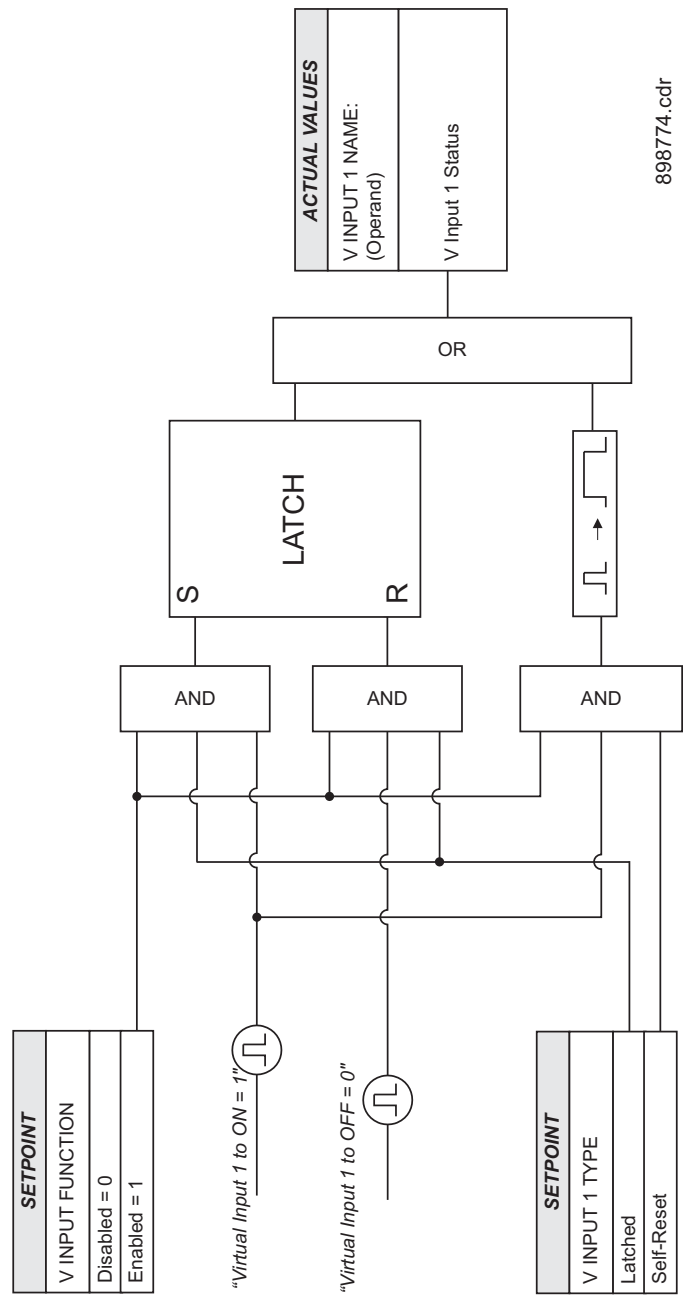
See also the Virtual Inputs section under **S4 CONTROLS**, on how to trigger a virtual input signal state.

Virtual input programming begins with enabling the Virtual Input Function, and selecting the Virtual Input Type **Self-Reset** or **Latched** under **SETPOINTS > S5 INPUTS/OUTPUTS > VIRTUAL INPUTS**. Next, the user can assign a command **On/Off** to the enabled Virtual Input under **SETPOINTS > S4 CONTROLS > S4 VIRTUAL INPUTS**. Referring to the Virtual Inputs logic diagram below, a Virtual Input type can be selected to be either **Self-Reset**, or **Latched**. When **Self-Reset** is selected and the "On" command is executed, the virtual input is evaluated as a pulse at a rate of one protection pass. To prolong the time of the virtual input pulse, one can assign it as a trigger source to a logic element with a dropout timer set to the desired pulse time. Selecting the **Latched** type, will latch the virtual input state, when the "On" command is executed.



The "On" state of the Virtual Input will not be retained in the case of cycling of the relay control power supply.

Figure 6-25: Virtual inputs scheme logic



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### 6.6.4 Remote inputs

**Remote Inputs** are available for programming under the EnerVista SR3 Setup software.





# 350 Feeder Protection System

## Chapter 7: Maintenance

Information about the relay and the breaker can be obtained through the features included in the Maintenance page.



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## 7.1 M1 Relay information

**PATH:** MAINTENANCE > M1 RELAY INFO

**RELAY NAME**

*Range: alpha-numeric name of up to 18 characters*

*Default: Feeder Name*

**ORDER CODE**

**350-EP1GLHSECNSNDN**

This screen shows the relay Order Code.

**FIRMWARE REVISION**

**1.10**

This screen shows the relay Firmware Revision.

**BUILD DATE**

**Feb 18 2009**

This screen shows the relay Firmware Build Date.

**BUILD TIME**

**17:13:42**

This screen shows the relay Firmware Build Time.

**BOOT REVISION**

**1.00**

This screen shows the relay Boot Code Revision.

**SERIAL NUMBER**

**ML0T08000063**

Each 350 relay has a unique serial number.

## 7.2 M3 Breaker maintenance

### 7.2.1 Trip coil

The Trip coil monitoring is performed by a built-in voltage monitor on the Form A output relay: #1 Trip. The voltage monitor is connected across the Form A contact, and effectively the relay detects healthy current through the circuit. To do that, an external jumper must be made between terminals “A2” and “A3” for Trip coil monitoring.

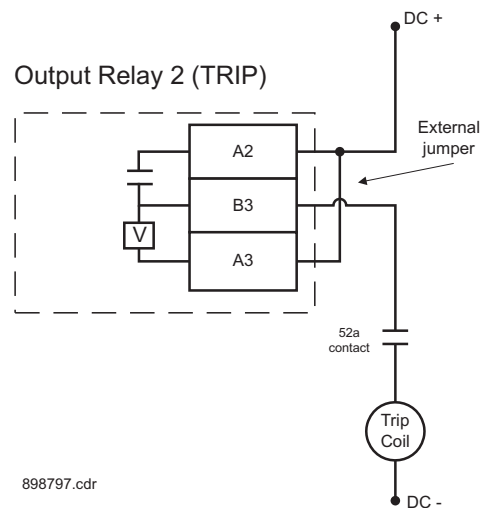
As long as the current through the Voltage Monitor is above the threshold of the trickle currents (see Technical Specification for Form A output relays), the circuit integrity for the Trip coil is effectively normal. If the Trip coil circuit gets disconnected, or if in general a high resistance is detected in the circuitry, a Trip alarm will be set and the “ALARM” and “MAINTENANCE” LEDs will be on.

**Example 1:** The figure below shows the connections of the breaker trip coil to the relay’s trip output relay for voltage monitoring of the trip circuit.



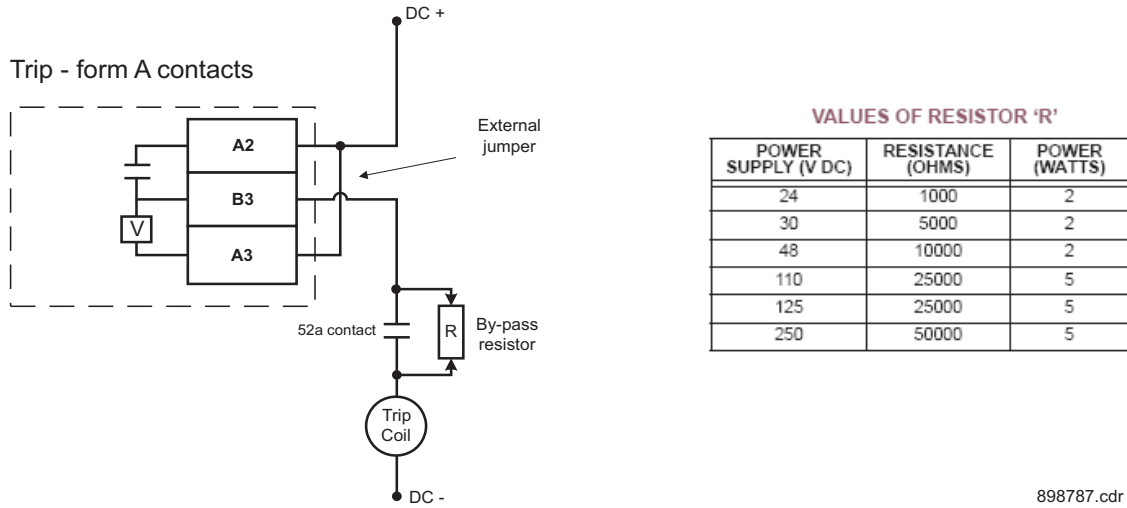
To monitor the trip coil circuit integrity, use the relay terminals “A2” and “B3” to connect the Trip coil, and provide a jumper between terminals “A2” and “A3” (voltage monitor).

**Figure 7-1: Trip Coil circuit with voltage monitoring**



**Example 2:** Some applications require that the Trip coil be monitored continuously, regardless of the breaker position (open or closed). This can be achieved by connecting a suitable resistor (see the table) across breaker auxiliary contact 52a in the trip circuit. With such connections, the trickle current will be maintained by the resistor when the breaker is open. For these applications the setting for “BYPASS BKR STATUS” should be set to ENABLED.

Figure 7-2: Trip circuit with continuous monitoring



The following path is available using the keypad. For instructions on how to use the keypad, please refer to Section 3.1.3 - Working with the Keypad.

**PATH:** MAINTENANCE > M3 BKR MAINTENANCE

**TRIP COIL FUNCTION**

Range: Disabled, Alarm, Latched Alarm  
 Default: Disabled

Selecting Alarm, or Latched Alarm, enables the Trip Coil Monitor monitoring function. The "ALARM" and "MAINTENANCE" LEDs will light up upon detection of a trip coil circuitry problem. The "ALARM" LED will flash upon Trip Coil Monitor operating condition, with the Trip Coil Monitor function selected as Alarm, and will self-reset, when the condition clears. If Latched Alarm is selected, the "ALARM" LED will flash during the Trip Coil Monitor condition, and will stay "ON" after the condition clears, until the reset command is initiated. Any or all of output relays 3 to 6 can be selected to operate when the Trip Coil Monitor function is selected as Alarm, or Latched Alarm.

**TRIP COIL DELAY**

Range: 1 to 10 sec in steps of 1 sec  
 Default: 5 s

This setting defines the Trip Coil Monitor Delay, before targets appear on the display, "ALARM" and "MAINTENANCE" LEDs light up on the front panel, and selected output relays operate.

**BYPASS BKR STATUS**

Range: Disabled, Enabled  
 Default: Disabled

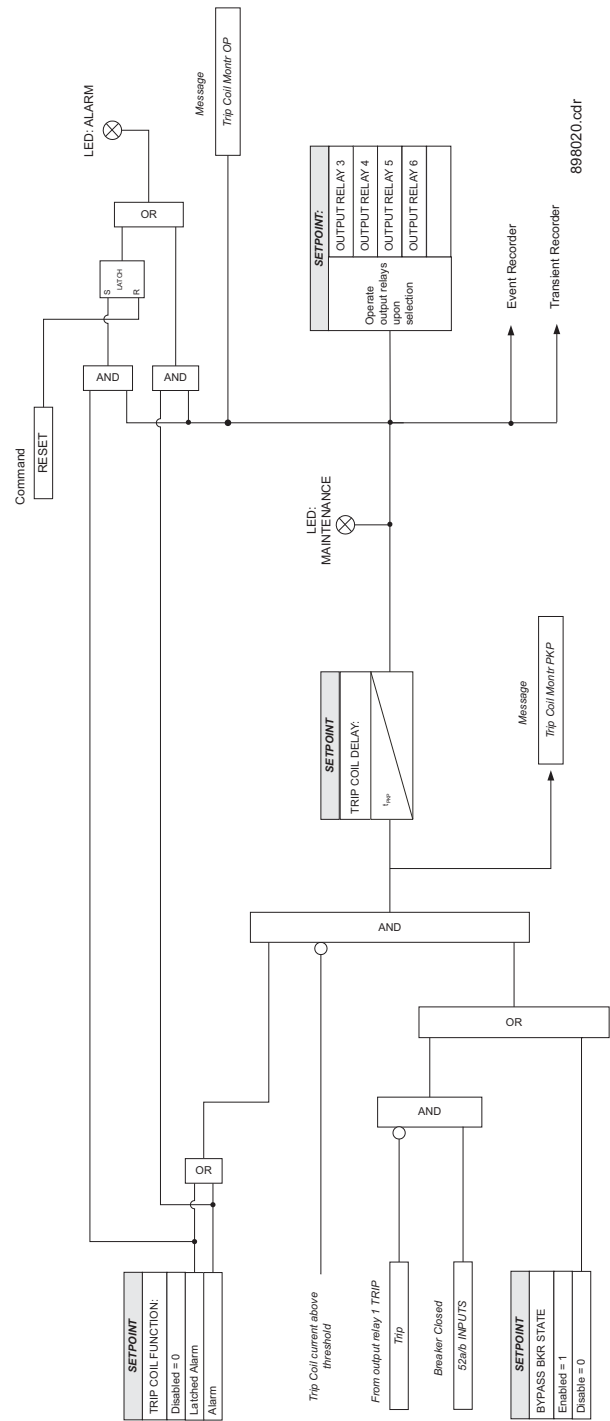
Set the "BYPASS BKR STATE" to Enabled when a by-pass resistor is connected across the breaker auxiliary contact for continuous Trip circuit integrity monitoring. The circuits will be monitored regardless of breaker position. When "BYPASS BKR STATE" is set to Disabled, monitoring of the trip coil will be blocked when the breaker is open.

**OUTPUT RELAY 3 to 6**

Range: Do not operate, Operate  
 Default: Do not operate

Any, or all, of output relays 3 to 6 can be selected to operate upon detection of Trip Coil, or a Trip coil circuitry problem. The selection of the relay outputs operation is available no matter whether the Alarm, or Latched Alarm, function is selected.

Figure 7-3: Trip coil monitoring logic diagram



### 7.2.2 Close coil

Close coil monitoring is performed by a built-in voltage monitor on the Form A output relay: #2 Close. The voltage monitor is connected across the Form A contact, and effectively the relay detects healthy current through the circuit. To do that, an external jumper should be made between terminals “B4”, and “B5” for Close coil monitoring.

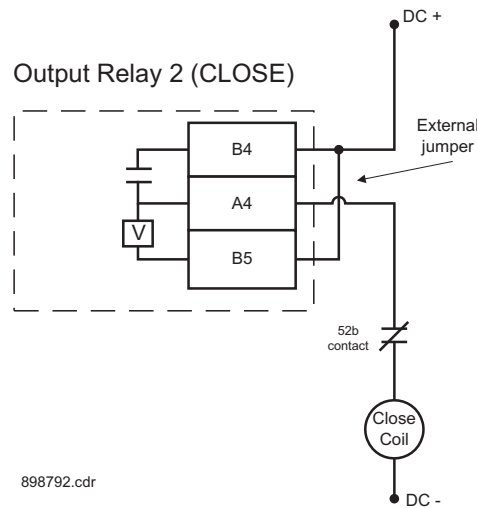
As long as the current through the Voltage Monitor is above the threshold of the trickle currents (see Technical Specification for Form A output relays), the circuit integrity for the Close coil is effectively normal. If the Close coil circuit gets disconnected, or if in general a high resistance is detected in the circuitry, a Close Coil alarm will be set and the “ALARM” and “MAINTENANCE” LEDs will be on.

**Example 1:** The figure below shows the connection of the breaker close coil to the relay’s close output relay for voltage monitoring of the close circuit.



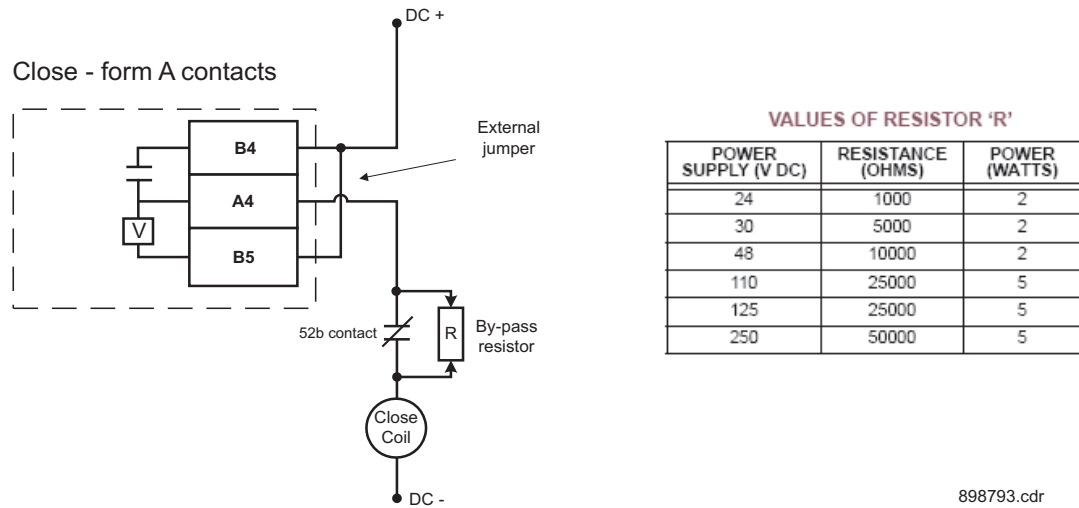
To monitor the close coil circuit integrity, use the relay terminals “B4” and “A4” to connect the Close coil, and provide a jumper between terminals “B4” and “B5” (voltage monitor).

**Figure 7-4: Close Coil circuit with voltage monitoring**



**Example 2:** Some applications require that the Close Coil be monitored continuously, regardless of the breaker position (open or closed). This can be achieved by connecting a suitable resistor (see the table) across breaker auxiliary contact 52b in the Close circuit. With such connections, the trickle current will be maintained by the resistor when the breaker is closed. For these applications the setting for “BYPASS BKR STATUS” should be set to ENABLED.

Figure 7-5: Close Coil circuit with continuous monitoring



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The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH:** MAINTENANCE > M3 BKR MAINTENANCE

#### CLOSE COIL FUNCTION

*Range:* Disabled, Alarm, Latched Alarm

*Default:* Disabled

Selecting Alarm, or Latched Alarm, enables the Close Coil Monitor monitoring function. The "ALARM" and "MAINTENANCE" LEDs will light up upon detection of a close coil circuitry problem. The "ALARM" LED will flash upon a Close Coil Monitor operating condition, with the Close Coil Monitor function selected as Alarm, and will self-reset, when the condition clears. If Latched Alarm is selected, the "ALARM" LED will flash during the Close Coil Monitor condition, and will stay "ON" after the condition clears, until the reset command is initiated. Any or all of output relays 3 to 6 can be selected to operate when the Close Coil Monitor function is selected as Alarm, or Latched Alarm.

#### CLOSE COIL DELAY

*Range:* 1 to 10 sec in steps of 1 sec

*Default:* 5 s

This setting defines the Close Coil Monitor Delay, before targets appear on the display, "ALARM" and "MAINTENANCE" LEDs light up on the front panel, and selected output relays operate.

#### BYPASS BKR STATUS

*Range:* Disabled, Enabled

*Default:* Disabled

Set the "BYPASS BKR STATE" to Enabled when a by-pass resistor is connected across the breaker auxiliary contact for continuous Close circuit integrity monitoring. The circuits will be monitored regardless of breaker position. When "BYPASS BKR STATE" is set to Disabled, monitoring of the close coil will be blocked when the breaker is closed.

#### OUTPUT RELAY 3 to 6

*Range:* Do not operate, Operate

*Default:* Do not operate

Any, or all, of output relays 3 to 6 can be selected to operate upon detection of a Close coil circuitry problem. The selection of the relay outputs operation is available no matter whether the Alarm, or Latched Alarm, function is selected.



## 7.2.3 Breaker trip counter

When the total number of breaker trips detected reaches the TRIP COUNTER LIMIT setpoint, an output will occur.

The following path is available using the keypad. For instructions on how to use the keypad, please refer to *Section 3.1.3 - Working with the Keypad*.

**PATH:** MAINTENANCE > M3 BKR MAINTENANCE > BKR TRIP COUNTER

### TRIP COUNT FUNCTN

*Range: Disabled, Alarm, Latched Alarm*

*Default: Disabled*

The selection of the **Latched Alarm**, or **Alarm** setting enables the BKR Trip Counter function. The "ALARM" LED will turn on when the Total breaker trips reaches the TRIP COUNTER LIMIT setting. The "ALARM" LED will flash when the BKR Trip Counter reaches the TRIP COUNTER LIMIT setting with function selected as **Alarm**, and will reset, when the trip counter is reset. The "ALARM" LED will latch when **Latched Alarm** is selected, until the counter is reset, and the **reset targets** command is initiated.

Any or all of output relays 3 to 6 can be selected to operate when the number of breaker trips reaches the "TRIP COUNTER LIMIT," regardless of the selected trip counter function.

### INITIAL TRIPS

*Range: 0 to 10000 in steps of 1*

*Default: 0*

This setting defines the number of breaker trips, that occurred before enabling the breaker trip counter for breaker monitoring.

### TRIP COUNTER LIMIT

*Range: 1 to 10000 in steps of 1*

*Default: 1 trip*

This setting defines the limit number for breaker trips. The BKR TRIP COUNTER will operate and produce an output if the number of breaker trips reaches the set limit.

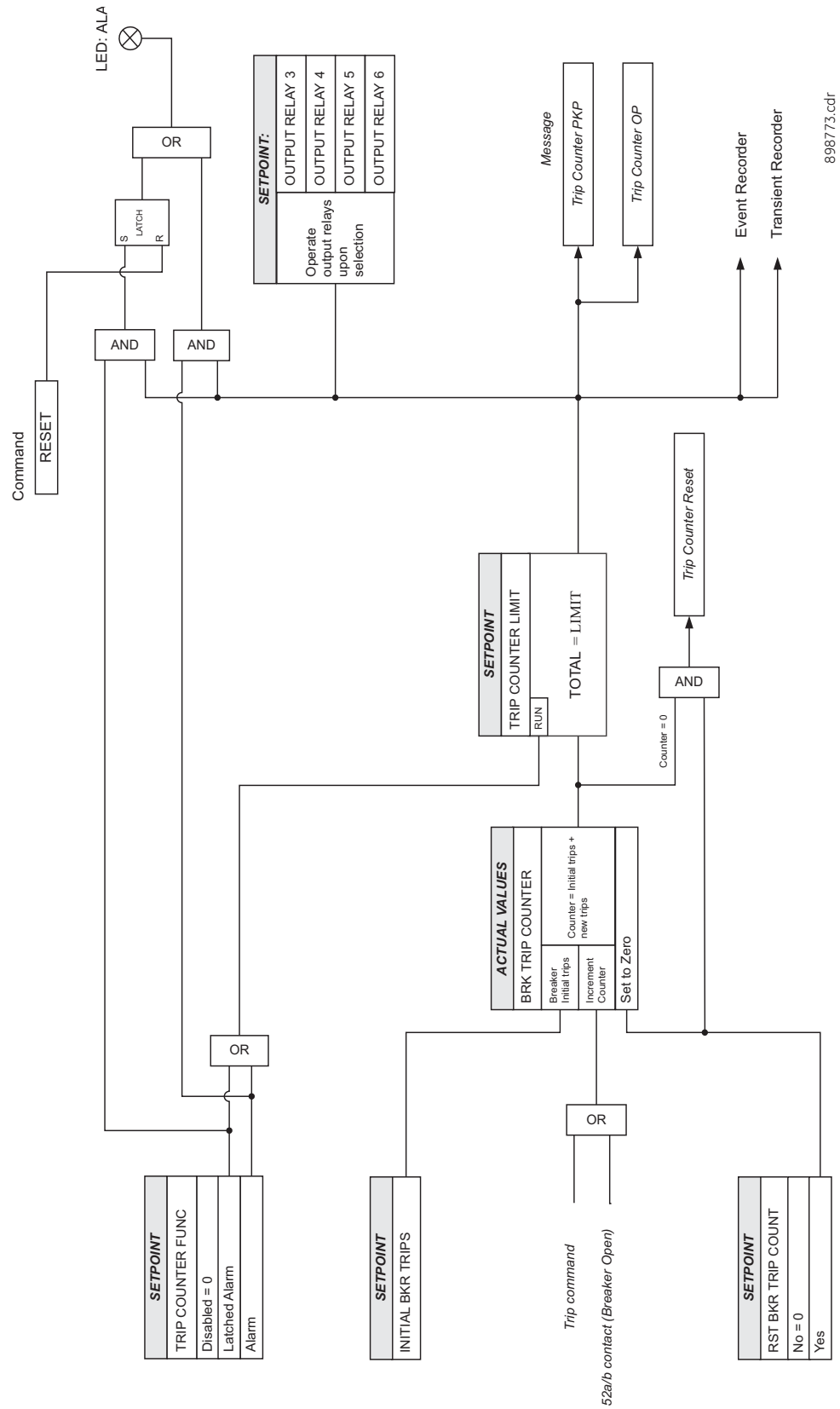
### OUTPUT RELAY 3 to 6

*Range: Do not operate, Operate*

*Default: Do not operate*

Any, or all, of output relays 3 to 6 can be selected to operate, upon the BKR TRIP COUNTER condition.

Figure 7-7: BKR Trip Counter logic diagram



898773.cdr

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## 7.3 M4 Breaker monitor

The status of the breaker trip and close coils, as well as the trip and close circuits, can be monitored under **MAINTENANCE > M4 BKR MONITOR**. In the case where a breaker coil or circuit fails, the relay will display the message "Unhealthy" for the corresponding coil.

Further information on the breaker is provided under **BKR TRIP COUNTER**, where the 350 stores the number of trips. The counter can be reset under **M3 RESET COUNTERS > RST BKR TRIP COUNT** set to "Yes".

**PATH:** **MAINTENANCE > M4 BKR MONITOR**

**TRIP COIL**

**Healthy**

*Range: Healthy, Unhealthy*

**CLOSE COIL**

**Healthy**

*Range: Healthy, Unhealthy*

**BKR TRIP COUNTER**

**5**

*Number of Trips*

